

# DATA SHEET

## **PCA2000; PCA2001** 32 kHz watch circuit with programmable adaptive motor pulse

Product specification  
Supersedes data of 2003 Feb 04

2003 Dec 17

## 32 kHz watch circuit with programmable adaptive motor pulse

## PCA2000; PCA2001

### FEATURES

- Amplitude-regulated 32 kHz quartz crystal oscillator, with excellent frequency stability and high immunity to leakage currents
- Electrically programmable time calibration with 1 ppm resolution stored in One Time Programmable (OTP) memory
- The quartz crystal is the only external component connected
- Very low power consumption, typical 90 nA
- One second output pulses for bipolar stepping motor
- Minimum power consumption for the entire watch, due to self adaptation of the motor drive according to the required torque
- Reliable step detection circuit
- Motor pulse width, pulse modulation, and pulse adaptation range programmable in a wide range, stored in OTP memory
- Stop function for accurate time setting and power saving during shelf life
- End Of Life (EOL) indication for silver oxide or lithium battery (only the PCA2000 has the EOL feature)
- Test mode for accelerated testing of the mechanical parts and the IC.

### APPLICATIONS

- Driver circuits for bipolar stepping motors
- High immunity motor drive circuits.

### ORDERING INFORMATION

TYPE NUMBER	PACKAGE		
	NAME	DESCRIPTION	VERSION
PCA2000U/AA	–	bare die; chip in tray	–
PCA2001U/AA	–	bare die; chip in tray	–
PCA2000U/10AA	–	bare die; chip on film frame carrier	–
PCA2001U/10AA	–	bare die; chip on film frame carrier	–

### GENERAL DESCRIPTION

The PCA2000; PCA2001 are CMOS integrated circuits for battery operated wrist watches with a 32 kHz quartz crystal as timing element and a bipolar 1 Hz stepping motor. The quartz crystal oscillator and the frequency divider are optimized for minimum power consumption. A timing accuracy of 1 ppm is achieved with a programmable, digital frequency adjustment.

To obtain the minimum overall power consumption for the watch, an automatic motor pulse adaptation function is provided. The circuit supplies only the minimum drive current, which is necessary to ensure a correct motor step. Changing the drive current of the motor is achieved by chopping the motor pulse with a variable duty cycle. The pulse width and the range of the variable duty cycle can be programmed to suit different types of motor. The automatic pulse adaptation scheme is based on a safe dynamic detection of successful motor steps.

A pad RESET is provided (used for stopping the motor) for accurate time setting and for accelerated testing of the watch.

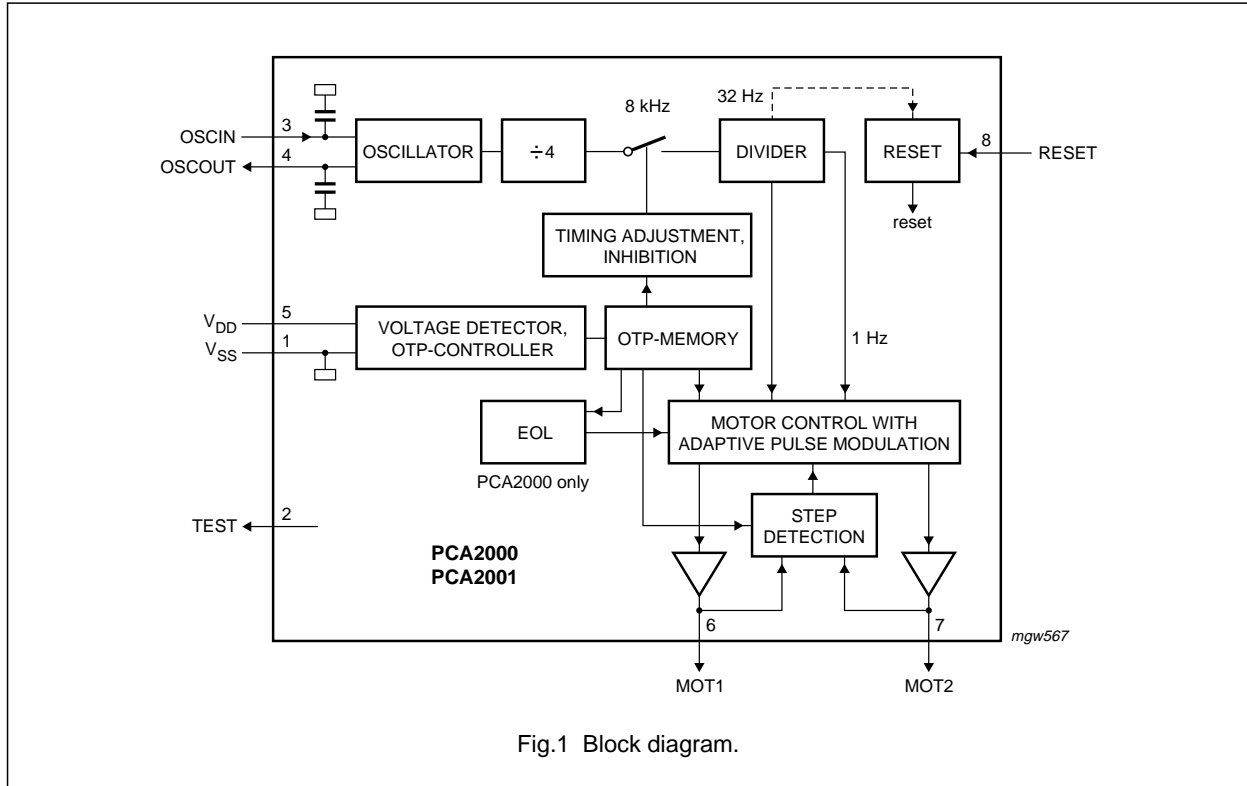
The PCA2000 has a battery EOL warning function. If the battery voltage drops below the EOL threshold voltage (which can be programmed for silver oxide or lithium batteries), the motor steps change from one pulse per second to a burst of four pulses every 4 seconds.

The PCA2001 uses the same circuit as the PCA2000, but without the EOL function.

# 32 kHz watch circuit with programmable adaptive motor pulse

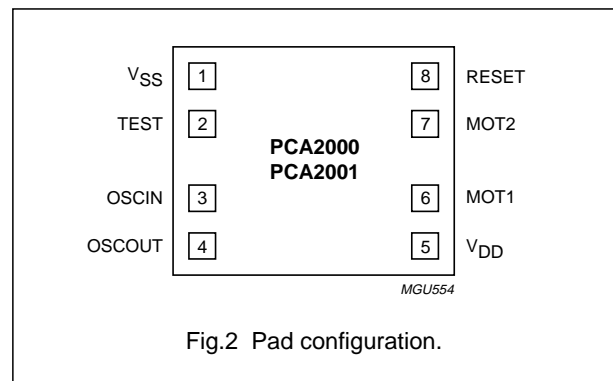
## PCA2000; PCA2001

### BLOCK DIAGRAM



### PINNING

SYMBOL	PAD	DESCRIPTION
V <sub>SS</sub>	1	ground
TEST	2	test output
OSCIN	3	oscillator input
OSCOUT	4	oscillator output
V <sub>DD</sub>	5	supply voltage
MOT1	6	motor 1 output
MOT2	7	motor 2 output
RESET	8	reset input



## 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

### FUNCTIONAL DESCRIPTION

#### Motor pulse

The motor output supplies pulses of different driving stages, depending on the torque required to turn on the motor. The number of different stages can be selected between three and six. With the exception of the highest driving stage, each motor pulse ( $t_p$  in Figs 3 and 6) is followed by a detection phase during which the motor movement is monitored, in order to check whether the motor has turned correctly or not.

If a missing step is detected, a correction sequence is generated (see Fig.3) and the driving stage is switched to the next level. The correction sequence consists of two pulses: first a short pulse in the opposite direction (0.98 ms, modulated with the maximum duty cycle) to give the motor a defined position, followed by a motor pulse of the strongest driving level. Every 4 minutes, the driving level is lowered again by one stage.

The motor pulse has a constant pulse width. The driving level is regulated by chopping the driving pulse with a variable duty cycle. The driving level starts from the programmed minimum value and increases by 6.25% after each failed motor step. The strongest driving stage, which is not followed by a detection phase, is programmed separately.

Therefore, it is possible to program a larger energy gap between the pulses with step detection and the strongest, not monitored, pulse. This might be necessary to ensure a reliable and stable operation under adverse conditions (magnetic fields, vibrations). If the watch works in the highest driving stage, the driving level jumps after the 4-minute period directly to the lowest stage, and not just one stage lower.

To optimize the performance for different motors, the following parameters can be programmed:

- Pulse width: 0.98 to 7.8 ms in steps of 0.98 ms
- Duty cycle of lowest driving level: 37.5% to 56.25% in steps of 6.25%
- Number of driving levels (including the highest driving level): 3 to 6
- Duty cycle of the highest driving level: 75% or 100%
- Enlargement pulse for the highest driving level: on or off.

The enlargement pulse has a duty cycle of 25% and a pulse width which is twice the programmed motor pulse width. The repetition period for the chopping pattern is 0.98 ms. Figure 4 shows an example of a 3.9 ms pulse.

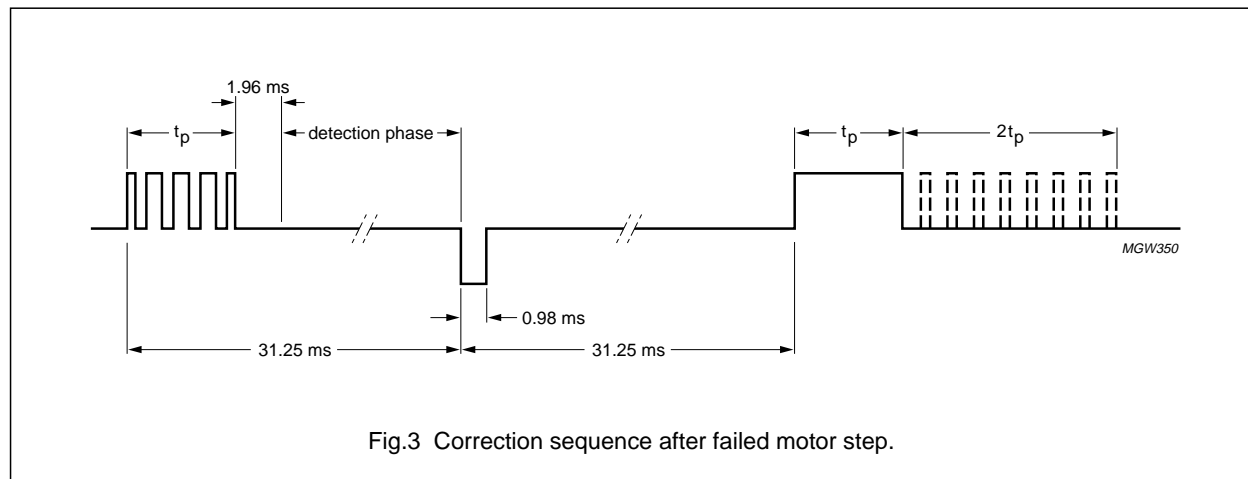
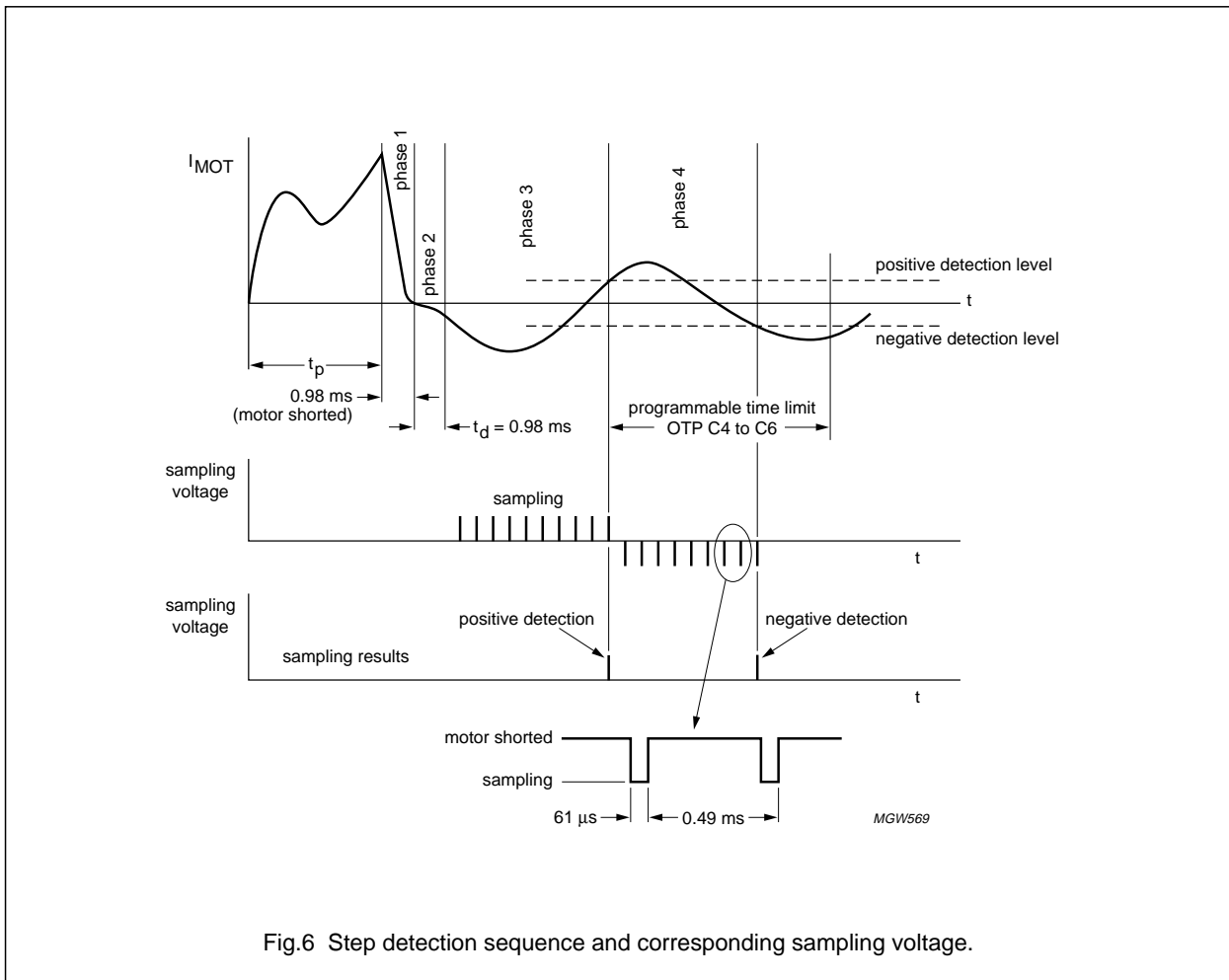
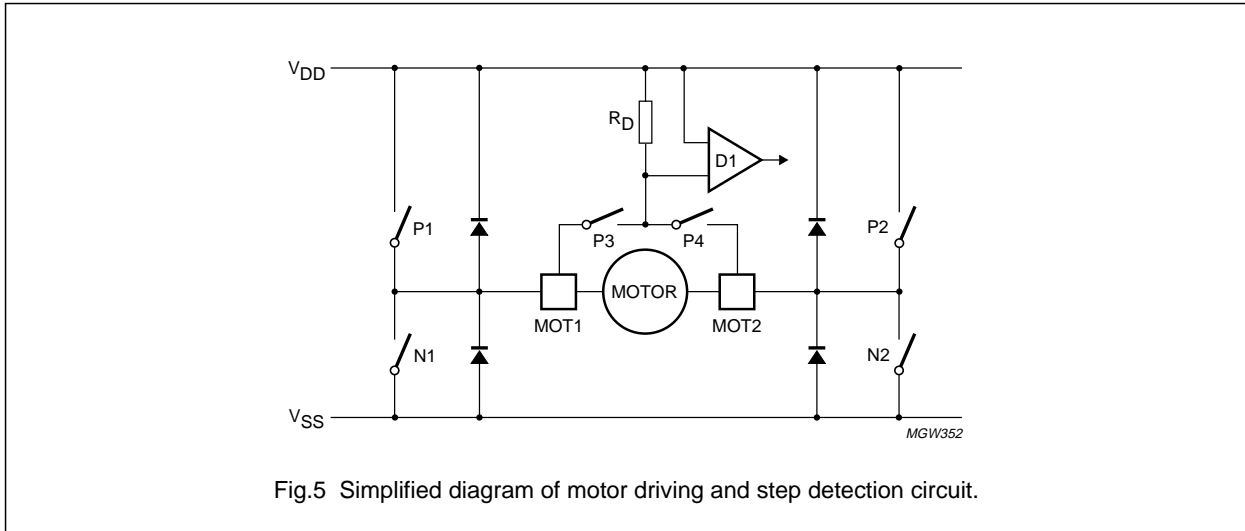


Fig.3 Correction sequence after failed motor step.



# 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001



## 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

### Time calibration

The quartz crystal oscillator has an integrated capacitance of 5.2 pF, which is lower than the specified capacitance ( $C_L$ ) of 8.2 pF for the quartz crystal. Therefore, the oscillator frequency is typically 60 ppm higher than 32.768 kHz. This positive frequency offset is compensated by removing the appropriate number of 8192 Hz pulses in the divider chain (maximum 127 pulses), every 1 or 2 minutes. The time correction is given in Table 1.

After measuring the effective oscillator frequency, the number of correction pulses must be calculated and stored together with the calibration period in the OTP memory (see Section "Programming the memory cells").

The oscillator frequency can be measured at pad RESET, where a square wave signal with the frequency of  $\frac{1}{1024} \times f_{osc}$  is provided.

This frequency shows a jitter every minute or every two minutes, depending on the programmed calibration period, which originates from the time calibration.

Details on how to measure the oscillator frequency and the programmed inhibit time are given in Section "Measurement of oscillator frequency and inhibit time".

### Reset

At pin RESET an output signal with a frequency of  $\frac{1}{1024} \times f_{osc} = 32$  Hz is provided.

Connecting pad RESET to  $V_{DD}$  stops the motor drive and opens all four (P1, N1, P2 and N2) driver switches (see Fig.5). Connecting pad RESET to  $V_{SS}$  activates the test mode. In this mode the motor output frequency is 32 Hz, which can be used to test the mechanical function of the watch.

After releasing the pad RESET, the motor starts exactly one second later with the smallest duty cycle and with the opposite polarity to the last pulse before stopping.

The debounce time for the RESET function is between 31 and 62 ms.

### Programming possibilities

The programming data is stored in OTP cells (EPROM cells). At delivery, all memory cells are in state 0. The cells can be programmed to the state 1, but then there is no more set back to state 0.

The programming data is organized in an array of three 8-bit words: word A contains the time calibration, and words B and C contain the setting for the monitor pulses (see Table 2).

**Table 1** Time calibration

CALIBRATION PERIOD	CORRECTION PER STEP (n = 1)		CORRECTION PER STEP (n = 127)	
	ppm	seconds per day	ppm	seconds per day
1 minute	2.03	0.176	258	22.3
2 minutes	1.017	0.088	129	11.15

**Table 2** Words and bits

WORD	BIT							
	1	2	3	4	5	6	7	8
A	number of 8192 Hz pulses to be removed							calibration period
B	lowest stage: duty cycle		number of driving stages		highest stage: duty cycle and stretching		factory test bit	
C	pulse width			maximum time delay between positive and negative detection pulses			EOL voltage	factory test bit

## 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

**Table 3** Description of word A bits

BIT	VALUE	DESCRIPTION
<b>Inhibit time</b>		
1 to 7	–	Adjust the number of the 8192 Hz pulses to be removed. Bit 1 is the MSB and bit 7 is the LSB.
<b>Calibration period</b>		
8	0	1 minute
	1	2 minutes

**Table 4** Description of word B bits

BIT	VALUE	DESCRIPTION
<b>Duty cycle lowest driving stage</b>		
1 to 2	00	37.5%
	01	43.75%
	10	50%
	11	56.25%
<b>Number of driving stages</b>		
3 to 4	00	3
	01	4
	10	5
	11	6; note 1
<b>Duty cycle highest driving stage</b>		
5	0	75%; note 2
	1	100%
<b>Stretching pulse</b>		
6	0	pulse is not stretched
	1	pulse of $2t_{pr}$ and duty cycle of 25% is added
<b>Factory test bits</b>		
7 to 8	–	

**Notes**

- Including the highest driving stage, which one has no motor step detection.
- If the maximum duty cycle of 75% is selected, not all programming combinations are possible since the second highest level must be smaller than the highest driving level.

**Table 5** Description of word C bits

BIT	VALUE	DESCRIPTION
<b>Pulse width <math>t_{pr}</math> (ms)</b>		
1 to 3	000	0.98
	001	1.95
	010	2.90
	011	3.90
	100	4.90
	101	5.90
	110	6.80
	111	7.80
<b>Time delay <math>t_{max}</math> (ms); note 1</b>		
4 to 6	000	3.91
	001	4.88
	010	5.86
	011	6.84
	100	7.81
	101	8.79
	110	9.77
	111	10.74
<b>EOL voltage of the battery</b>		
7	0	1.38 V (silver-oxide)
	1	2.5 V (lithium)
<b>Factory test bit</b>		
8	–	

**Note**

- Between positive and negative detection pulses.



## 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

### Programming procedure

For a watch it is essential that the timing calibration can be made after the watch is fully assembled. In this situation, the supply pads are often the only terminals which are still accessible.

Writing to the OTP cells and performing the related functional checks is achieved in the PCA2000; PCA2001 by modulating the supply voltage. The necessary control circuit consists basically of a voltage level detector, an instruction counter which determines the function to be performed, and an 8-bit shift register which allows writing to the OTP cells of an 8-bit word in one step and acts as a data pointer for checking the OTP content.

There are five different instruction states (states 3 and 5 are handled as state 4):

- State 1: measurement of the quartz crystal oscillator frequency (divided by 1024)
- State 2: measurement of the inhibit time
- State 3: write/check word A
- State 4: write/check word B
- State 5: write/check word C.

Each instruction state is switched on with a pulse to  $V_P$  (6.7 V). After this large pulse, an initial waiting time of  $t_0$  (20 ms) is required. The programming instructions are then entered by modulating the supply voltage with small pulses (amplitude  $V_{P(mod)} = 0.35$  V and pulse width  $t_{mod} = 30$   $\mu$ s). The first small pulse defines the start time, the following pulses perform three different functions, depending on the delay from the preceding pulse (see Figs 7, 8, 11, and 12):

- $t_1 = 0.7$  ms: increments the instruction counter
- $t_2 = 1.7$  ms: clocks the shift register with data = logic 0
- $t_3 = 2.7$  ms: clocks the shift register with data = logic 1.

The programming procedure requires a stable oscillator. This means that a waiting time, determined by the start-up time of the oscillator is necessary after power-up of the circuit.

After the  $V_{P(start)}$  pulse, the instruction counter is in state 1 and the data shift register is cleared.

The instruction state ends with a second pulse to  $V_{P(stop)}$  or with a pulse to  $V_{store}$ .

In any case, the instruction states are terminated automatically 2 seconds after the last  $V_{DD(mod)}$  pulse.

### Programming the memory cells

Applying the two-stage programming pulse (see Fig.7) transfers the stored data in the shift register to the OTP cells.

Perform the following to program a memory word:

1. Starting with a  $V_{P(start)}$  pulse wait for the time period  $t_0$  then set the instruction counter to the word you want to write ( $t_d = t_1$ ).
2. Enter the data you want to store in the shift register ( $t_d = t_2$  or  $t_3$ ). Enter the LSB first (bit 8) and the MSB last (bit 1).
3. Apply the two-stage programming pulse ( $V_{pre-store}$  then  $V_{store}$ ) stores the word. The delay between the last data bit and the pre-store pulse ( $V_{pre-store}$ ) is  $t_d = t_4$ .

The example shown in Fig.7 performs the following functions:

- Start
- Setting instruction counter to state 4 (word B)
- Entering data word 110101 into the shift register (sequence: first bit 6 and last bit 1)
- Writing to the OTP cells for word B.

### General start up sequence

You must follow the sequence below to ensure the correct operation at start up:

1. Apply the supply voltage to the circuit.
2. Wait for at least 2 seconds.
3. Connect the pad RESET to  $V_{DD}$  for a minimum of 62 ms (this activates the stop mode).
4. Disconnect the pad RESET from  $V_{DD}$  (this resets the circuit to normal operating mode).

After this sequence the memory contents are read immediately and the programmed options are set. This sequence also resets all major circuit blocks and ensures that they function correctly.

## 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

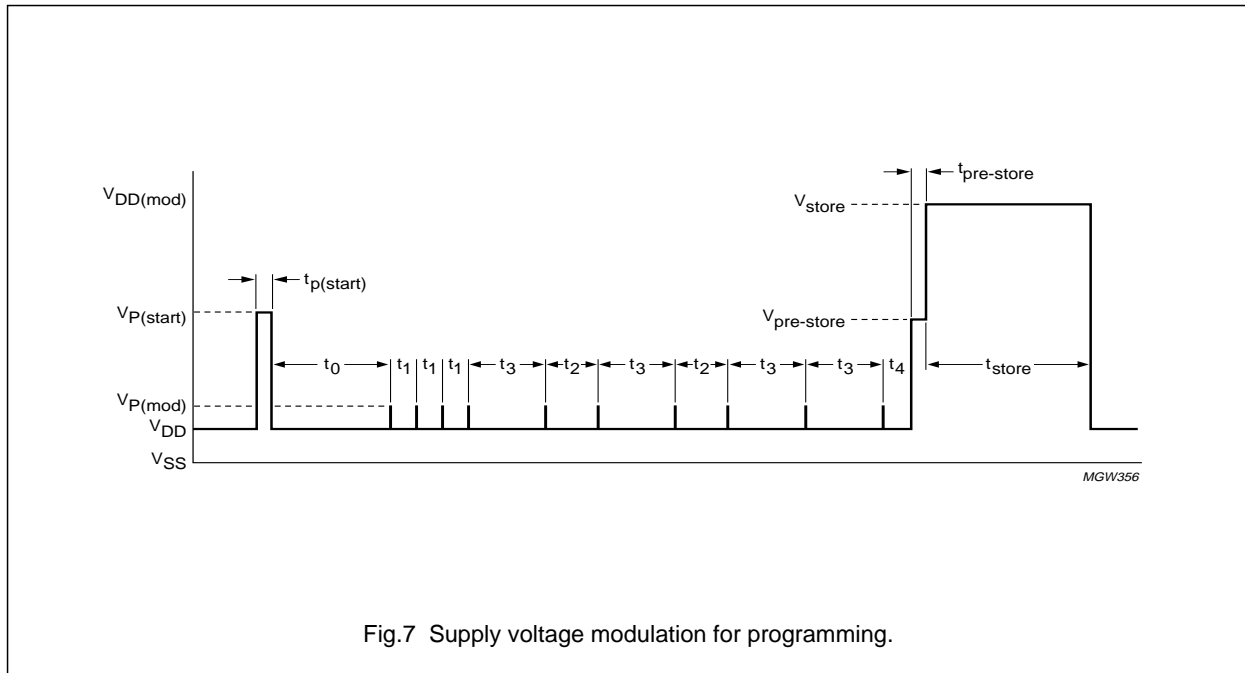


Fig.7 Supply voltage modulation for programming.

### Checking memory content

The stored data of the OTP array can be checked bit wise by measuring the supply current. The array word is selected by the instruction state and the bit is addressed by the shift register.

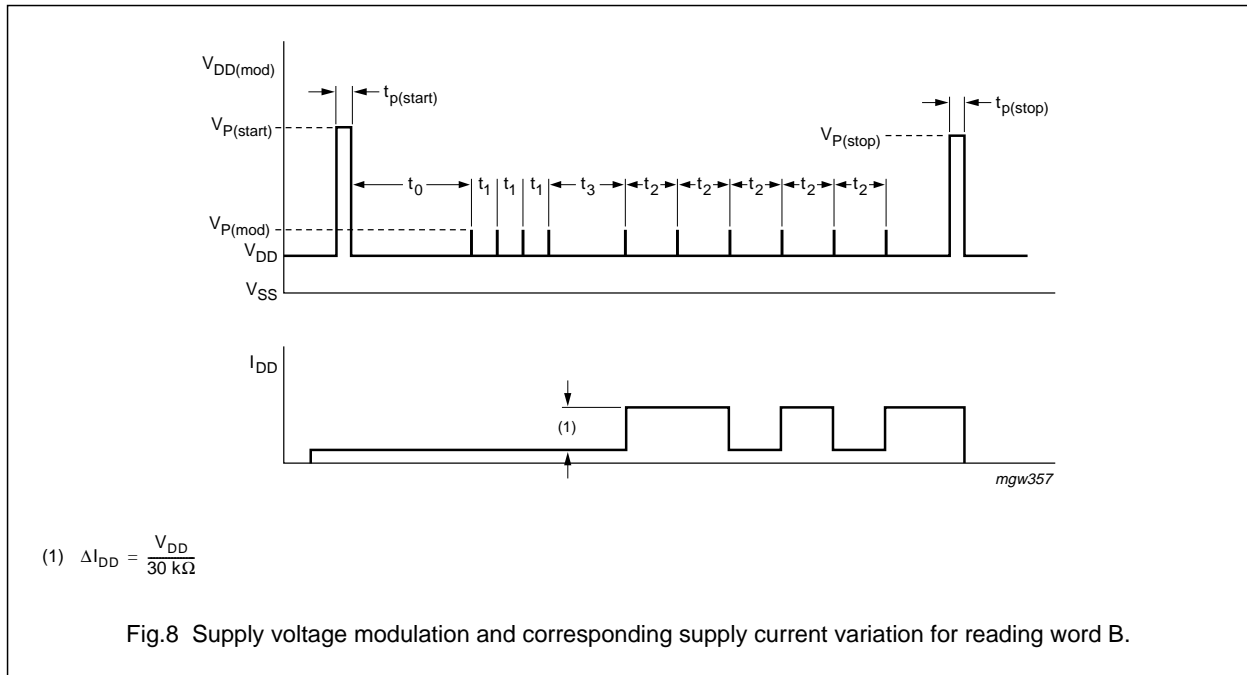
To read a word, the word is first selected (pulse distance  $t_1$ ), and a logic 1 is written into the first cell of the shift register (pulse distance  $t_3$ ). This logic 1 is then shifted through the entire shift register (pulse distance  $t_2$ ), so that it points with each clock pulse to the next bit.

If the addressed OTP cell contains a logic 1, a  $30\text{ k}\Omega$  resistor is connected between  $V_{DD}$  and  $V_{SS}$ , which increases the supply current accordingly.

Figure 8 shows the supply voltage modulation for reading word B, with the corresponding supply current variation for word B = 110101 (sequence: first MSB and last LSB).

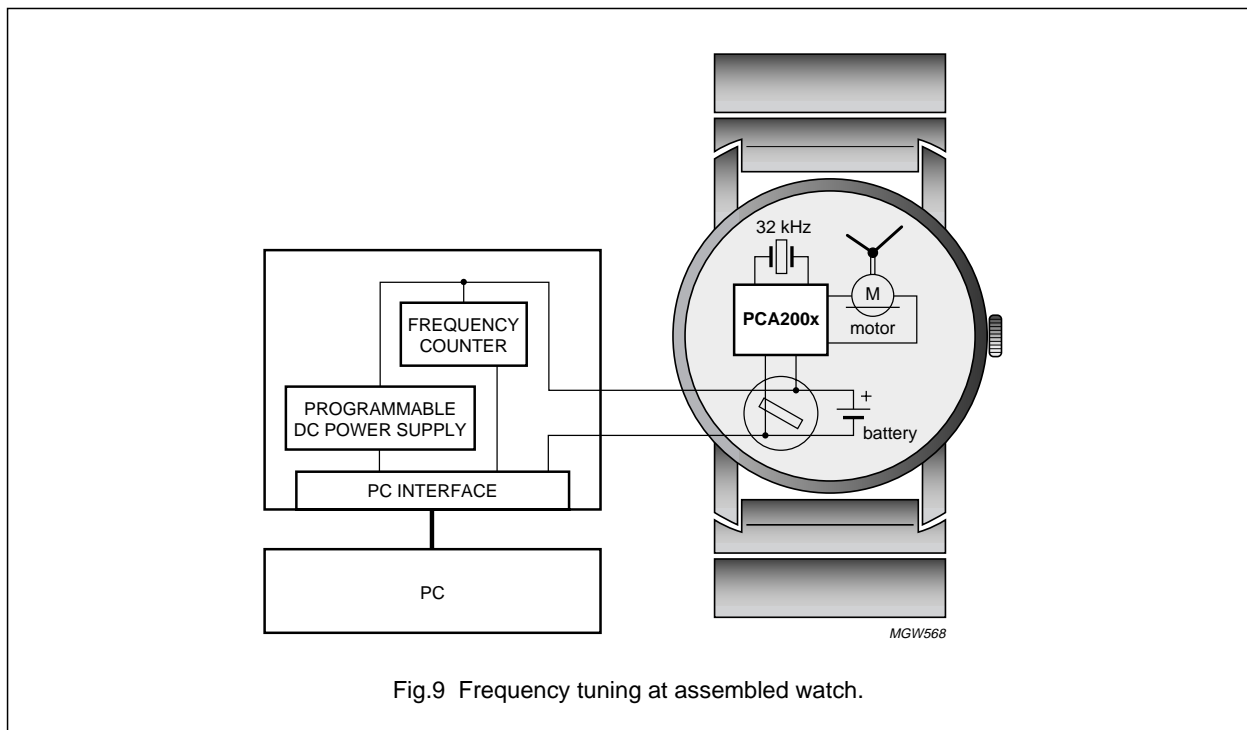
# 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001



## Frequency tuning of assembled watch

Figure 9 shows the test set-up for frequency tuning the assembled watch.



# 32 kHz watch circuit with programmable adaptive motor pulse

## PCA2000; PCA2001

### Measurement of oscillator frequency and inhibit time

The output of the two measuring states can either be monitored directly at pad RESET or as a modulation of the supply voltage (a modulating resistor of 30 kΩ is connected between V<sub>DD</sub> and V<sub>SS</sub> when the signal at pad RESET is at HIGH-level).

You must follow the supply voltage modulation (see Fig.10)) in order to guarantee the correct start up of the circuit during production and testing.

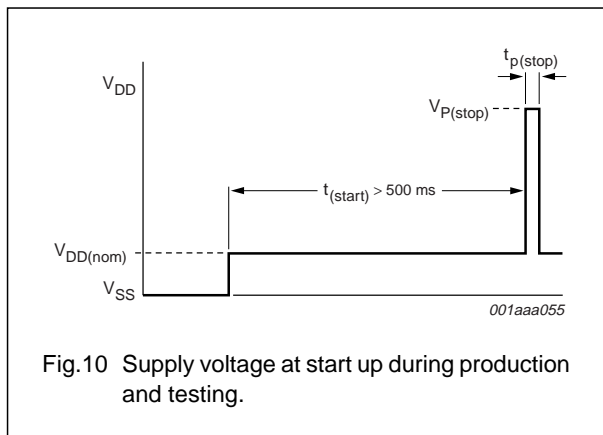


Fig.10 Supply voltage at start up during production and testing.

### Measuring states:

- State 1: quartz crystal oscillator frequency divided by 1024; state 1 starts with a pulse to V<sub>P</sub> and ends with a second pulse to V<sub>P</sub>
- State 2: inhibit time (see Figs 11 and 12); a signal with periodicity of 31.25 + n × 0.122 ms appears at pad RESET and as current modulation at pad V<sub>DD</sub>.

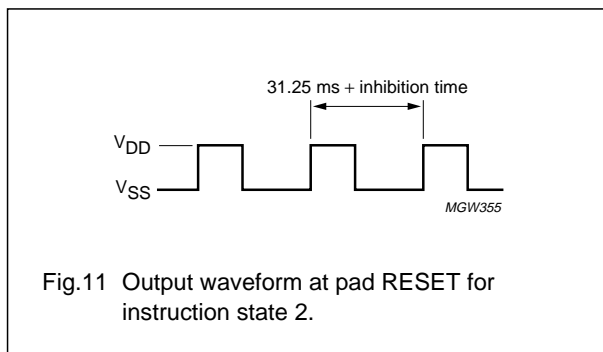


Fig.11 Output waveform at pad RESET for instruction state 2.

### Customer testing

Connecting pad RESET to V<sub>SS</sub> activates the test mode. In this test mode, the motor output frequency is 8 Hz; the duty cycle reduction and battery check occurs every second, instead of every 4 minutes. If the supply voltage drops below the EOL threshold voltage, the motor output frequency is 32 Hz with the highest driving level.

### EOL of battery

The supply voltage is checked every 4 minutes. If it drops below the EOL reference (1.38 V for silver-oxide, 2.5 V for lithium batteries), the motor steps change from one pulse per second to a burst of four pulses every 4 seconds. The step detection is switched off, and the motor is driven with the highest pulse level.

Only the PCA2000 has an EOL function.

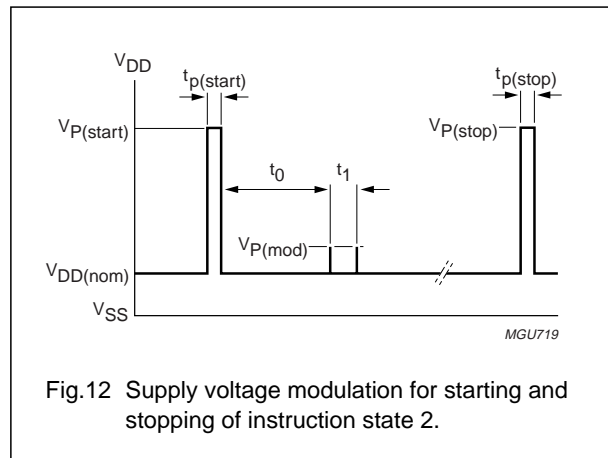


Fig.12 Supply voltage modulation for starting and stopping of instruction state 2.

## 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

### LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 60134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
$V_{DD}$	supply voltage	$V_{SS} = 0$ V; notes 1 and 2	-1.8	+7.0	V
$V_i$	all input voltages		$V_{SS} - 0.5$	$V_{DD} + 0.5$	V
$T_{amb}$	ambient temperature		-10	+60	°C
$T_{stg}$	storage temperature		-30	+100	°C
$t_{o(sc)}$	output short-circuit duration		indefinite		s

### Notes

- For writing to the OTP cells, the supply voltage  $V_{DD}$  can be raised to a maximum of 12 V for a period of 1 second.
- Connecting the battery with reversed polarity does not destroy the circuit, but in this condition a large current flows, which rapidly discharges the battery.

### HANDLING

Inputs and outputs are protected against electrostatic discharges in normal handling. However to be totally safe, it is advised to undertake handling precautions appropriate to handling MOS devices. Advice can be found in "Data handbook IC16: General; handling MOS devices".

### CHARACTERISTICS

$V_{DD} = 1.55$  V;  $V_{SS} = 0$  V;  $f_{osc} = 32.768$  kHz;  $T_{amb} = 25$  °C; quartz crystal:  $R_S = 40$  k $\Omega$ ,  $C_1 = 2$  to 3 fF,  $C_L = 8.2$  pF; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
<b>Supply</b>						
$V_{DD}$	supply voltage	normal operating mode; $T_{amb} = -10$ to $+60$ °C	1.10	1.55	3.60	V
$\Delta V_{DD}$	supply voltage variation	$\Delta V/\Delta t = 1$ V/ $\mu$ s	-	-	0.25	V
$I_{DD}$	supply current	between motor pulses	-	90	120	nA
		between motor pulses at $V_{DD} = 3.5$ V	-	120	180	nA
		$T_{amb} = -10$ to $+60$ °C	-	-	200	nA
		stop mode; pad RESET connected to $V_{DD}$	-	100	135	nA
<b>Motor output</b>						
$V_{sat}$	saturation voltage	$R_M = 2$ k $\Omega$ ; $T_{amb} = -10$ to $+60$ °C; note 1	-	150	200	mV
$Z_{sc}$	short-circuit impedance	between motor pulses; $I_{motor} < 1$ mA	-	200	300	$\Omega$
<b>Oscillator</b>						
$V_{start}$	starting voltage		1.1	-	-	V
$g_m$	transconductance	$V_{OSCIN} \leq 50$ mV (p-p)	5	10	-	$\mu$ S
$t_{osc}$	start-up time		-	0.3	0.9	s
$\Delta f/f$	frequency stability	$\Delta V_{DD} = 100$ mV	-	0.05	0.20	ppm
$C_{int}$	integrated load capacitance		4.3	5.2	6.3	pF
$R_{par}$	parasitic resistance	allowed resistance between adjacent pads	20	-	-	M $\Omega$

## 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
<b>Voltage level detector</b>						
$V_{th(EOL)}$	EOL threshold voltage	silver-oxide battery	1.30	1.38	1.46	V
		lithium battery	2.35	2.50	2.65	V
$TC_{EOL}$	temperature coefficient		–	–0.07	–	%/°C
<b>Pad RESET</b>						
$f_o$	output frequency		–	32	–	Hz
$\Delta V_o$	output voltage swing	$R_L = 1\text{ M}\Omega$ ; $C_L = 10\text{ pF}$ ; note 2	1.4	–	–	V
$t_r, t_f$	rise and fall time	$R_L = 1\text{ M}\Omega$ ; $C_L = 10\text{ pF}$ ; note 2	–	1	–	$\mu\text{s}$
$I_{i(AV)}$	average input current	pad RESET connected to $V_{DD}$ or $V_{SS}$	–	10	20	nA

**Notes**

- $\Sigma (P + N)$ .
- $R_L$  and  $C_L$  are a load resistor and load capacitor, externally connected to pad RESET.

**Table 6** Specifications for OTP programming (see Figs 7, 8 and 12).

SYMBOL	PARAMETER <sup>(1)</sup>	MIN.	TYP.	MAX.	UNIT
$V_{DD}$	supply voltage during programming procedure	1.5	–	3.0	V
$V_{P(start)}$	supply voltage for starting programming procedure	6.6	–	6.8	V
$V_{P(stop)}$	supply voltage for stopping programming procedure	6.2	–	6.4	V
$V_{P(mod)}$	supply voltage modulation for entering instructions	320	350	380	mV
$V_{pre-store}$	supply voltage for pre-store pulse	6.2	–	6.4	V
$V_{store}$	supply voltage for writing to the OTP cells	9.9	10.0	10.1	V
$I_{store}$	supply current for writing to the OTP cells	–	–	10	mA
$t_{p(start)}$	pulse width of start pulse	8	10	12	ms
$t_{p(stop)}$	pulse width of stop pulse	0.05	–	0.5	ms
$t_{mod}$	modulation pulse width	25	30	40	$\mu\text{s}$
$t_{pre-store}$	pulse width of pre-store pulse	0.05	–	0.5	ms
$t_{store}$	pulse width for writing to the OTP cells	95	100	110	ms
$t_0$	waiting time after start pulse	20	–	30	ms
$t_1$	pulse distance for incrementing the state counter	0.6	0.7	0.8	ms
$t_2$	pulse distance for clocking the data register with data = logic 0	1.6	1.7	1.8	ms
$t_3$	pulse distance for clocking the data register with data = logic 1	2.6	2.7	2.8	ms
$t_4$	waiting time for writing to OTP cells	0.1	0.2	0.3	ms
SR	slew rate for modulation of the supply voltage	0.5	–	5.0	V/ $\mu\text{s}$
$R_{read}$	supply current modulation read-out resistor	18	30	45	k $\Omega$

**Note**

- Program each word once only.

# 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

## BONDING PAD LOCATIONS

SYMBOL	PAD	COORDINATES <sup>(1)</sup>	
		x	y
V <sub>SS</sub> <sup>(3)</sup>	1	-480	+330
TEST <sup>(2)</sup>	2	-480	+160
OSCIN	3	-480	-160
OSCOU	4	-480	-330
V <sub>DD</sub>	5	+480	-330
MOT1	6	+480	-160
MOT2	7	+480	+160
RESET	8	+480	+330

### Notes

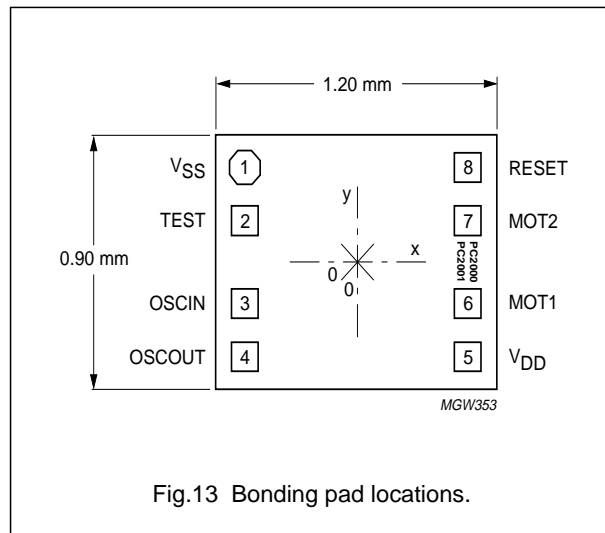
- All coordinates are referenced, in  $\mu\text{m}$ , to the centre of the die (see Fig.13).
- Pad TEST is used for factory tests; in normal operation it should be left open-circuit, and it has an internal pull-down resistance to V<sub>SS</sub>.
- The substrate (rear side of the chip) is connected to V<sub>SS</sub>. Therefore the die pad must be either floating or connected to V<sub>SS</sub>.

**Table 7** Mechanical chip data; note 1

PARAMETER	VALUE
Bonding pad: metal	96 × 96 $\mu\text{m}$
opening	86 × 86 $\mu\text{m}$
Thickness: chip for bonding	200 ±25 $\mu\text{m}$
chip for golden bumps	270 ±25 $\mu\text{m}$
Bumps: height	25 ±5 $\mu\text{m}$

### Note

- The substrate of the chip is connected to V<sub>SS</sub>.



# 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

## TRAY INFORMATION

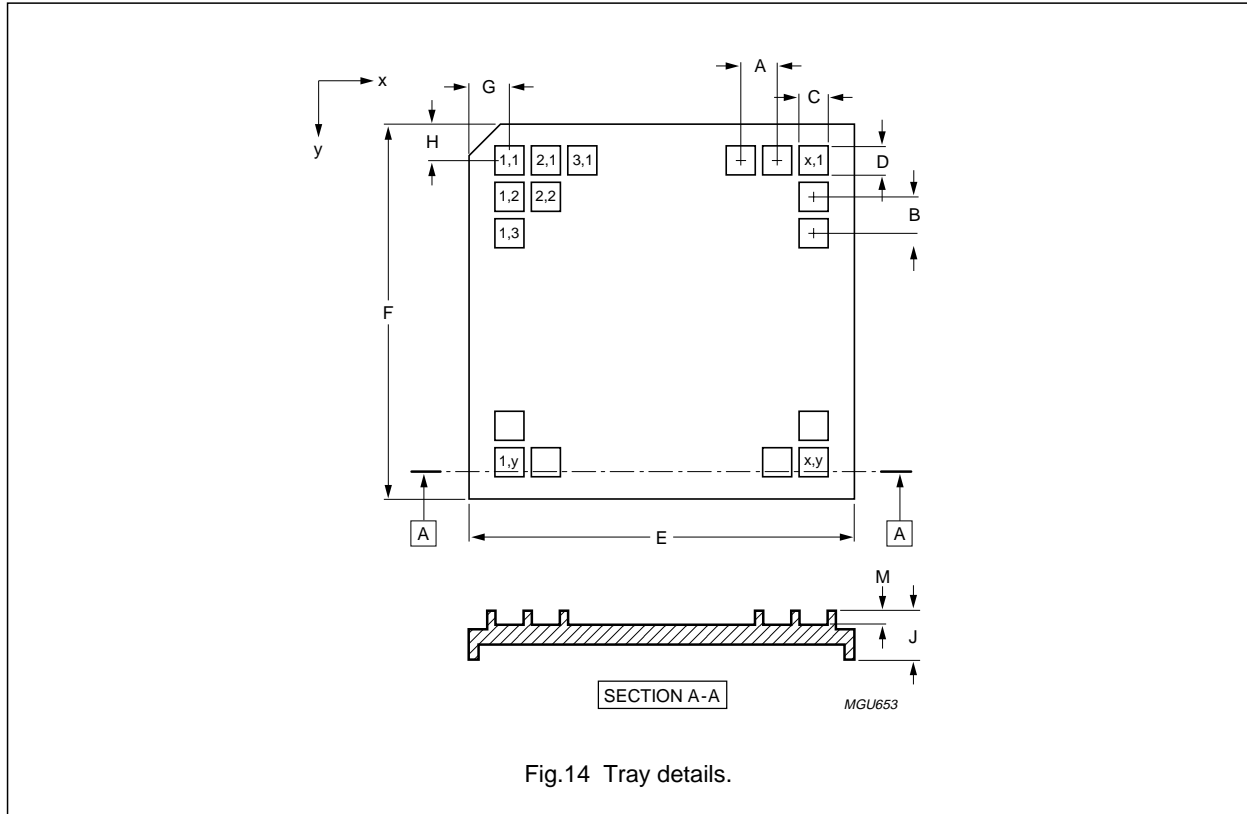


Fig.14 Tray details.

Table 8 Tray dimensions

DIMENSION	DESCRIPTION	VALUE
A	pocket pitch; x direction	2.15 mm
B	pocket pitch; y direction	2.43 mm
C	pocket width; x direction	1.01 mm
D	pocket width; y direction	1.39 mm
E	tray width; x direction	50.67 mm
F	tray width; y direction	50.67 mm
G	distance from cut corner to pocket (1, 1) centre	4.86 mm
H	distance from cut corner to pocket (1, 1) centre	4.66 mm
J	tray thickness	3.94 mm
M	pocket depth	0.61 mm
x	number of pockets in x direction	20
y	number of pockets in y direction	18

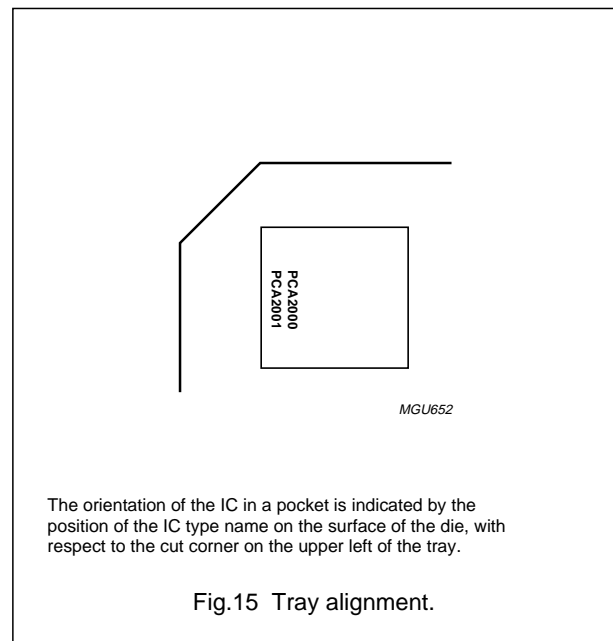


Fig.15 Tray alignment.



## 32 kHz watch circuit with programmable adaptive motor pulse

PCA2000; PCA2001

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LEVEL	DATA SHEET STATUS <sup>(1)</sup>	PRODUCT STATUS <sup>(2)(3)</sup>	DEFINITION
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For additional information please visit <http://www.semiconductors.philips.com>. Fax: **+31 40 27 24825**

For sales offices addresses send e-mail to: [sales.addresses@www.semiconductors.philips.com](mailto:sales.addresses@www.semiconductors.philips.com).

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