



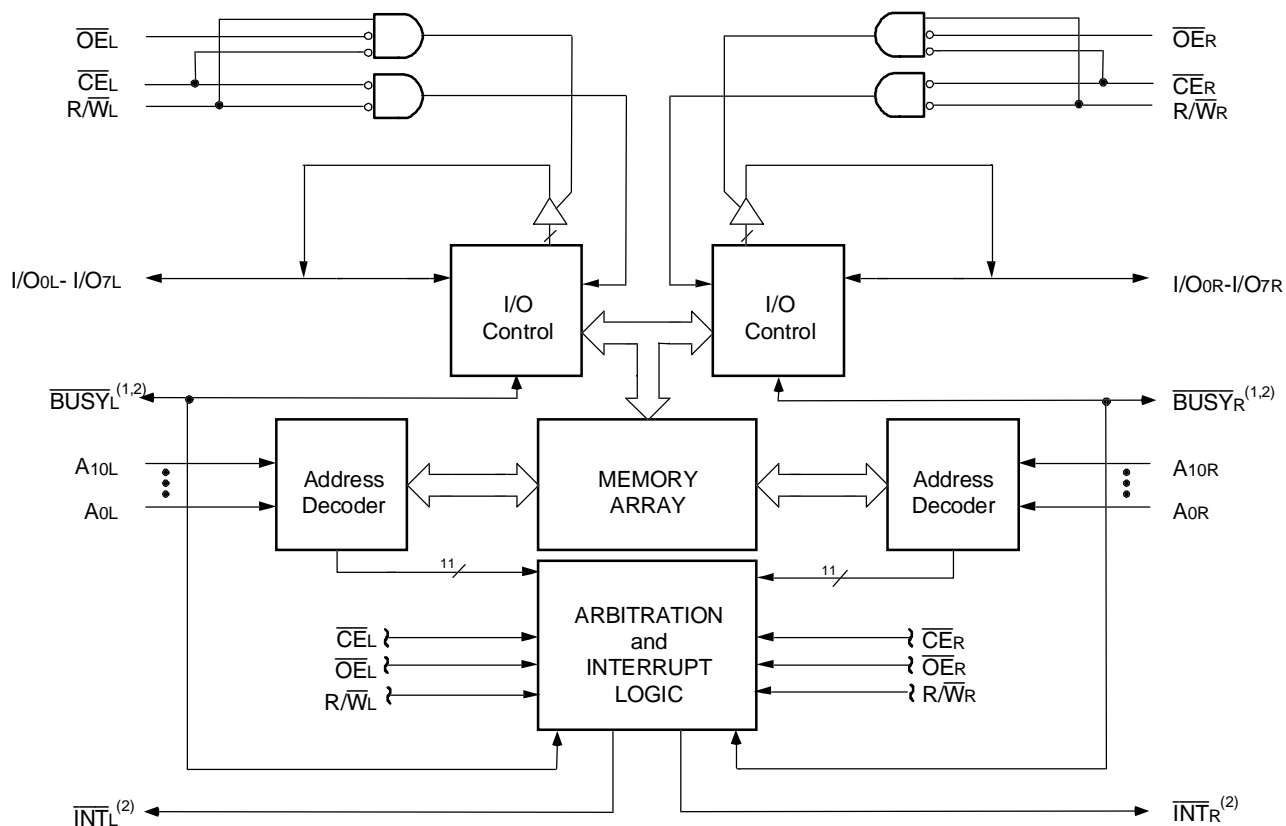
# HIGH SPEED 2K X 8 DUAL-PORT STATIC RAM WITH INTERRUPTS

**IDT71321SA/LA  
IDT71421SA/LA**

## Features

- ◆ **High-speed access**
  - Commercial: 20/25/35/55ns (max.)
  - Industrial: 55ns (max.)
- ◆ **Low-power operation**
  - IDT71321/IDT71421SA  
Active: 325mW (typ.)  
Standby: 5mW (typ.)
  - IDT71321/421LA  
Active: 325mW (typ.)  
Standby: 1mW (typ.)
- ◆ **Two  $\overline{\text{INT}}$  flags for port-to-port communications**
- ◆ **MASTER IDT71321 easily expands data bus width to 16-or-more-bits using SLAVE IDT71421**
- ◆ **On-chip port arbitration logic (IDT71321 only)**
- ◆  **$\overline{\text{BUSY}}$  output flag on IDT71321;  $\overline{\text{BUSY}}$  input on IDT71421**
- ◆ **Fully asynchronous operation from either port**
- ◆ **Battery backup operation – 2V data retention (LA only)**
- ◆ **TTL-compatible, single 5V  $\pm 10\%$  power supply**
- ◆ **Available in 52-Pin PLCC, 64-Pin TQFP, and 64-Pin STQFP**
- ◆ **Industrial temperature range ( $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ) is available for selected speeds**

## Functional Block Diagram



### NOTES:

1. IDT71321 (MASTER):  $\overline{\text{BUSY}}$  is open drain output and requires pullup resistor of 270 $\Omega$ .  
IDT71421 (SLAVE):  $\overline{\text{BUSY}}$  is input.
2. Open drain output: requires pullup resistor of 270 $\Omega$ .

**MARCH 1999**

## Description

The IDT71321/IDT71421 are high-speed 2K x 8 Dual-Port Static RAMs with internal interrupt logic for interprocessor communications. The IDT71321 is designed to be used as a stand-alone 8-bit Dual-Port Static RAM or as a "MASTER" Dual-Port Static RAM together with the IDT71421 "SLAVE" Dual-Port in 16-bit-or-more word width systems. Using the IDT MASTER/SLAVE Dual-Port Static RAM approach in 16-or-more-bit memory system applications results in full speed, error-free operation without the need for additional discrete logic.

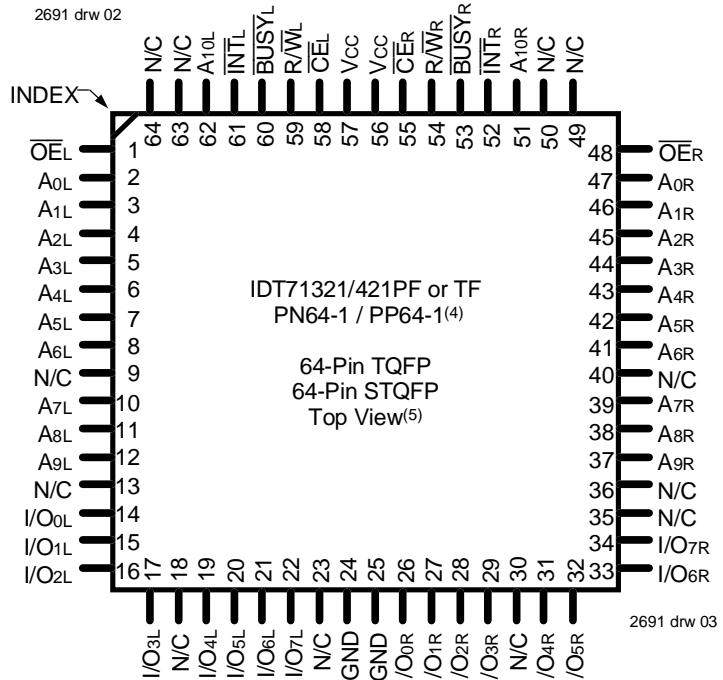
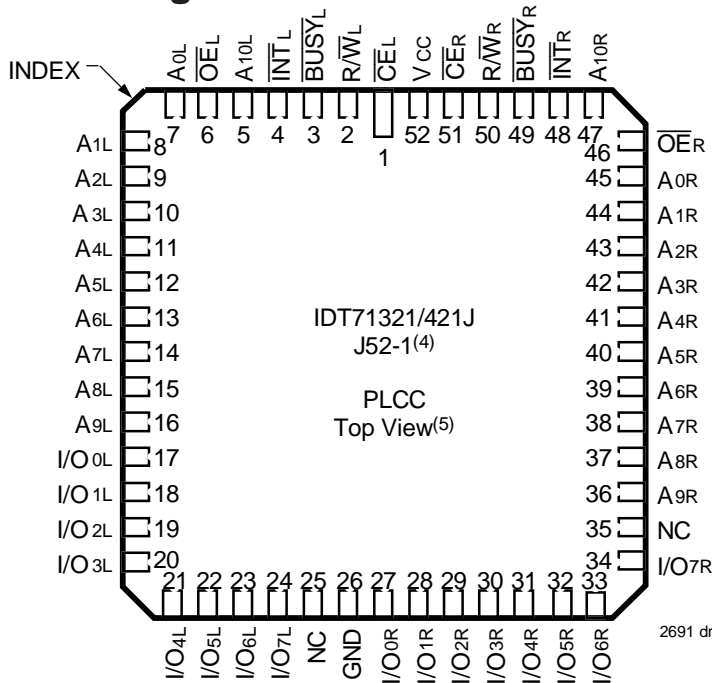
Both devices provide two independent ports with separate control,

address, and I/O pins that permit independent, asynchronous access for reads or writes to any location in memory. An automatic power down feature, controlled by  $\overline{CE}$ , permits the on chip circuitry of each port to enter a very low standby power mode.

Fabricated using IDT's CMOS high-performance technology, these devices typically operate on only 325mW of power. Low-power (LA) versions offer battery backup data retention capability, with each Dual-Port typically consuming 200 $\mu$ W from a 2V battery.

The IDT71321/IDT71421 devices are packaged in 52-pin PLCCs, 64-pin TQFPs, and 64-pin STQFPs.

## Pin Configurations<sup>(1,2,3)</sup>



### NOTES:

1. All Vcc pins must be connected to power supply.
2. All GND pins must be connected to ground supply.
3. J52-1 package body is approximately .75 in x .75 in x .17 in.  
PN64-1 package body is approximately 14mm x 14mm x 1.4mm.  
PP64-1 package body is approximately 10mm x 10mm x 1.4mm.
4. This package code is used to reference the package diagram.
5. This text does not indicate orientation of the actual part-marking.

## Capacitance<sup>(1)</sup> (TA = +25°C, f = 1.0MHz) TQFP Only

Symbol	Parameter	Conditions <sup>(2)</sup>	Max.	Unit
CIN	Input Capacitance	V <sub>IN</sub> = 3dV	9	pF
COUT	Output Capacitance	V <sub>OUT</sub> = 3dV	10	pF

2691 tbl 00

### NOTES:

1. This parameter is determined by device characterization but is not production tested.
2. 3dV references the interpolated capacitance when the input and output signals switch from 0V to 3V or from 3V to 0V.

## Recommended Operating Temperature and Supply Voltage<sup>(1,2)</sup>

Grade	Ambient Temperature	GND	V <sub>CC</sub>
Commercial	0°C to +70°C	0V	5.0V ± 10%
Industrial	-40°C to +85°C	0V	5.0V ± 10%

2691 tbl 02

### NOTES:

1. This is the parameter TA.
2. Industrial temperature: for specific speeds, packages and powers contact your sales office.

## Absolute Maximum Ratings<sup>(1)</sup>

Symbol	Rating	Commercial & Industrial	Unit
V <sub>TERM</sub> <sup>(2)</sup>	Terminal Voltage with Respect to GND	-0.5 to +7.0	V
T <sub>BIAS</sub>	Temperature Under Bias	-55 to +125	°C
T <sub>STG</sub>	Storage Temperature	-55 to +125	°C
I <sub>OUT</sub>	DC Output Current	50	mA

2691 tbl 01

### NOTES:

1. Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
2. V<sub>TERM</sub> must not exceed V<sub>CC</sub> + 10% for more than 25% of the cycle time or 10ns maximum, and is limited to ≤ 20mA for the period of V<sub>TERM</sub> ≥ V<sub>CC</sub> + 10%.

## Recommended DC Operating Conditions

Symbol	Parameter	Min.	Typ.	Max.	Unit
V <sub>CC</sub>	Supply Voltage	4.5	5.0	5.5	V
GND	Ground	0	0	0	V
V <sub>IH</sub>	Input High Voltage	2.2	—	6.0 <sup>(2)</sup>	V
V <sub>IL</sub>	Input Low Voltage	-0.5 <sup>(1)</sup>	—	0.8	V

2691 tbl 03

### NOTES:

1. V<sub>IL</sub> (min.) = -1.5V for pulse width less than 10ns.
2. V<sub>TERM</sub> must not exceed V<sub>CC</sub> + 10%.

### DC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range<sup>(1,4,6)</sup> (V<sub>CC</sub> = 5.0V ± 10%)

Symbol	Parameter	Test Condition	Version		71321X20 71421X20 Com'l Only		71321X25 71421X25 Com'l Only		Unit
					Typ.	Max.	Typ.	Max.	
I <sub>CC</sub>	Dynamic Operating Current (Both Ports Active)	$\overline{CE}_L$ and $\overline{CE}_R = V_{IL}$ , Outputs Open $f = f_{MAX}^{(2)}$	COM'L	SA	110	250	110	220	mA
				LA	110	200	110	170	
I <sub>SB1</sub>	Standby Current (Both Ports - TTL Level Inputs)	$\overline{CE}_L$ and $\overline{CE}_R = V_{IH}$ $f = f_{MAX}^{(2)}$	COM'L	SA	30	65	30	65	mA
				LA	30	45	30	45	
I <sub>SB2</sub>	Standby Current (One Port - TTL Level Inputs)	$\overline{CE}^{A*} = V_{IL}$ and $\overline{CE}^{B*} = V_{IH}^{(6)}$ Active Port Outputs Open, $f = f_{MAX}^{(2)}$	COM'L	SA	65	165	65	150	mA
				LA	65	125	65	115	
I <sub>SB3</sub>	Full Standby Current (Both Ports - CMOS Level Inputs)	$\overline{CE}_L$ and $\overline{CE}_R \geq V_{CC} - 0.2V$ , $V_{IN} \geq V_{CC} - 0.2V$ or $V_{IN} \leq 0.2V$ , $f = 0^{(3)}$	COM'L	SA	1.0	15	1.0	15	mA
				LA	0.2	5	0.2	5	
I <sub>SB4</sub>	Full Standby Current (One Port - CMOS Level Inputs)	$\overline{CE}^{A*} \leq 0.2V$ and $\overline{CE}^{B*} \geq V_{CC} - 0.2V^{(6)}$ $V_{IN} \geq V_{CC} - 0.2V$ or $V_{IN} \leq 0.2V$ Active Port Outputs Open, $f = f_{MAX}^{(2)}$	COM'L	SA	60	155	60	145	mA
				LA	60	115	60	105	

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Symbol	Parameter	Test Condition	Version		71321X35 71421X35 Com'l Only		71321X55 71421X55 Com'l & Ind		Unit
					Typ.	Max.	Typ.	Max.	
I <sub>CC</sub>	Dynamic Operating Current (Both Ports Active)	$\overline{CE}_L$ and $\overline{CE}_R = V_{IL}$ , Outputs Open $f = f_{MAX}^{(2)}$	COM'L	SA	80	165	65	155	mA
				LA	80	120	65	110	
I <sub>SB1</sub>	Standby Current (Both Ports - TTL Level Inputs)	$\overline{CE}_L$ and $\overline{CE}_R = V_{IH}$ $f = f_{MAX}^{(2)}$	COM'L	SA	25	65	20	65	mA
				LA	25	45	20	35	
I <sub>SB2</sub>	Standby Current (One Port - TTL Level Inputs)	$\overline{CE}^{A*} = V_{IL}$ and $\overline{CE}^{B*} = V_{IH}^{(6)}$ Active Port Outputs Open, $f = f_{MAX}^{(2)}$	COM'L	SA	50	125	40	110	mA
				LA	50	90	40	75	
I <sub>SB3</sub>	Full Standby Current (Both Ports - CMOS Level Inputs)	$\overline{CE}_L$ and $\overline{CE}_R \geq V_{CC} - 0.2V$ , $V_{IN} \geq V_{CC} - 0.2V$ or $V_{IN} \leq 0.2V$ , $f = 0^{(3)}$	COM'L	SA	1.0	15	1.0	15	mA
				LA	0.2	4	0.2	4	
I <sub>SB4</sub>	Full Standby Current (One Port - CMOS Level Inputs)	$\overline{CE}^{A*} \leq 0.2V$ and $\overline{CE}^{B*} \geq V_{CC} - 0.2V^{(6)}$ $V_{IN} \geq V_{CC} - 0.2V$ or $V_{IN} \leq 0.2V$ Active Port Outputs Open, $f = f_{MAX}^{(2)}$	COM'L	SA	45	110	40	100	mA
				LA	45	85	40	70	

2691 tbl 04b

**NOTES:**

- 'X' in part numbers indicates power rating (SA or LA).
- At  $f = f_{MAX}$ , address and control lines (except Output Enable) are cycling at the maximum frequency read cycle of  $1/t_{rc}$ , and using "AC TEST CONDITIONS" of input levels of GND to 3V.
- $f = 0$  means no address or control lines change. Applies only to inputs at CMOS level standby.
- $V_{CC} = 5V$ ,  $T_A = +25^\circ C$  for Typ and is not production tested.  $V_{CC\ DC} = 100mA$  (Typ)
- Port "A" may be either left or right port. Port "B" is opposite from port "A".
- Industrial temperature: for other speeds, packages and powers contact your sales office.

## DC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range ( $V_{CC} = 5.0V \pm 10\%$ )

Symbol	Parameter	Test Conditions	71321SA 71421SA		71321LA 71421LA		Unit
			Min.	Max.	Min.	Max.	
$ I_{L} $	Input Leakage Current <sup>(1)</sup>	$V_{CC} = 5.5V, V_{IN} = 0V \text{ to } V_{CC}$	—	10	—	5	$\mu A$
$ I_{O} $	Output Leakage Current <sup>(1)</sup>	$\overline{CE} = V_{IH}, V_{OUT} = 0V \text{ to } V_{CC}, V_{CC} = 5.5V$	—	10	—	5	$\mu A$
$V_{OL}$	Output Low Voltage ( $I_{O0}$ - $I_{O7}$ )	$I_{OL} = 4mA$	—	0.4	—	0.4	V
$V_{OL}$	Open Drain Output Low Voltage ( $\overline{BUSY}/\overline{INT}$ )	$I_{OL} = 16mA$	—	0.5	—	0.5	V
$V_{OH}$	Output High Voltage	$I_{OH} = -4mA$	2.4	—	2.4	—	V

2691 tbl 05

**NOTE:**

- At  $V_{CC} \leq 2.0V$  leakages are undefined.

## Data Retention Characteristics (LA Version Only)

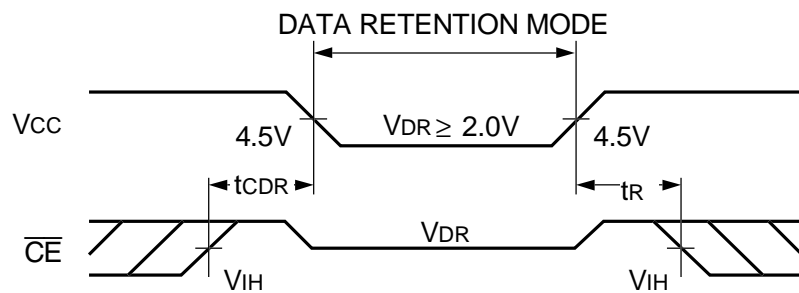
Symbol	Parameter	Test Condition	Min.	Typ. <sup>(1)</sup>	Max.	Unit	
$V_{DR}$	$V_{CC}$ for Data Retention		2.0	—	0	V	
$I_{CCDR}$	Data Retention Current	$V_{CC} = 2.0V, \overline{CE} \geq V_{CC} - 0.2V$ $V_{IN} \geq V_{CC} - 0.2V \text{ or } V_{IN} \leq 0.2V$	COM'L	—	100	1500	$\mu A$
			IND	—	100	4000	$\mu A$
$t_{CDR}^{(3)}$	Chip Deselect to Data Retention Time		0	—	—	ns	
$t_R^{(3)}$	Operation Recovery Time		$t_{RC}^{(2)}$	—	—	ns	

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**NOTES:**

- $V_{CC} = 2V, T_A = +25^\circ C$ , and is not production tested.
- $t_{RC}$  = Read Cycle Time
- This parameter is guaranteed but not production tested.

## Data Retention Waveform

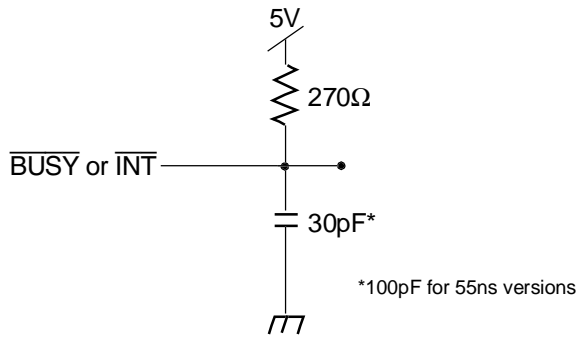
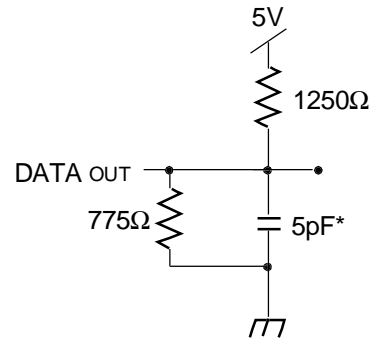
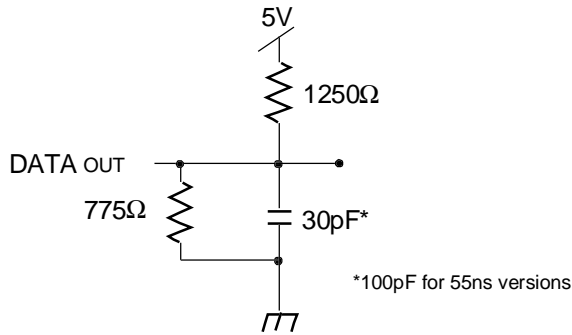


2691 drw 04

## AC Test Conditions

Input Pulse Levels	GND to 3.0V
Input Rise/Fall Times	5ns
Input Timing Reference Levels	1.5V
Output Reference Levels	1.5V
Output Load	Figures 1,2 and 3

2691 tbl 07



2691 drw 05

## AC Electrical Characteristics Over the Operating Temperature Supply Voltage Range<sup>(2,4)</sup>

Symbol	Parameter	71321X20 71421X20 Com'l Only		71321X25 71421X25 Com'l Only		Unit
		Min.	Max.	Min.	Max.	
<b>READ CYCLE</b>						
t <sub>RC</sub>	Read Cycle Time	20	—	25	—	ns
t <sub>AA</sub>	Address Access Time	—	20	—	25	ns
t <sub>ACE</sub>	Chip Enable Access Time	—	20	—	25	ns
t <sub>AOE</sub>	Output Enable Access Time	—	11	—	12	ns
t <sub>OH</sub>	Output Hold from Address Change	3	—	3	—	ns
t <sub>LZ</sub>	Output Low-Z Time <sup>(1,3)</sup>	0	—	0	—	ns
t <sub>HZ</sub>	Output High-Z Time <sup>(1,3)</sup>	—	10	—	10	ns
t <sub>PU</sub>	Chip Enable to Power Up Time <sup>(3)</sup>	0	—	0	—	ns
t <sub>PD</sub>	Chip Disable to Power Down Time <sup>(3)</sup>	—	20	—	25	ns

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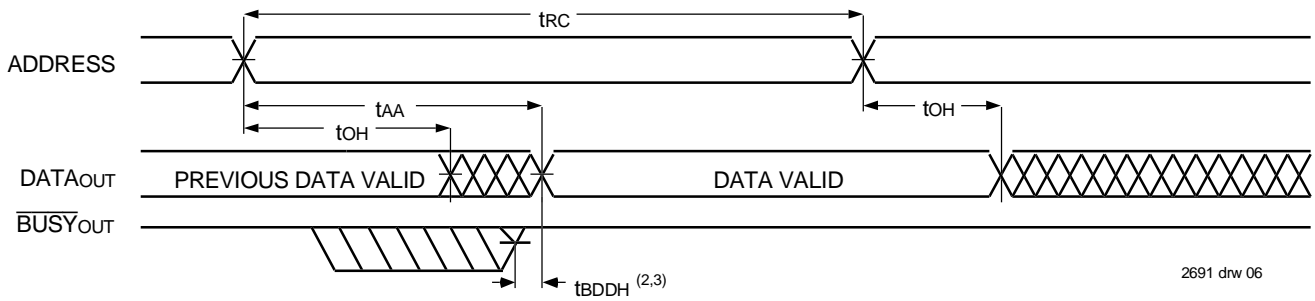
Symbol	Parameter	71321X35 71421X35 Com'l Only		71321X55 71421X55 Com'l & Ind		Unit
		Min.	Max.	Min.	Max.	
<b>READ CYCLE</b>						
t <sub>RC</sub>	Read Cycle Time	35	—	55	—	ns
t <sub>AA</sub>	Address Access Time	—	35	—	55	ns
t <sub>ACE</sub>	Chip Enable Access Time	—	35	—	55	ns
t <sub>AOE</sub>	Output Enable Access Time	—	20	—	25	ns
t <sub>OH</sub>	Output Hold from Address Change	3	—	3	—	ns
t <sub>LZ</sub>	Output Low-Z Time <sup>(1,3)</sup>	0	—	5	—	ns
t <sub>HZ</sub>	Output High-Z Time <sup>(1,3)</sup>	—	15	—	25	ns
t <sub>PU</sub>	Chip Enable to Power Up Time <sup>(3)</sup>	0	—	0	—	ns
t <sub>PD</sub>	Chip Disable to Power Down Time <sup>(3)</sup>	—	35	—	50	ns

2691 tbl 08b

**NOTES:**

1. Transition is measured  $\pm 500\text{mV}$  from Low or High-impedance voltage Output Test Load (Figure 2).
2. 'X' in part numbers indicates power rating (SA or LA).
3. This parameter is guaranteed by device characterization, but is not production tested.
4. Industrial temperature: for other speeds, packages and powers contact your sales office.

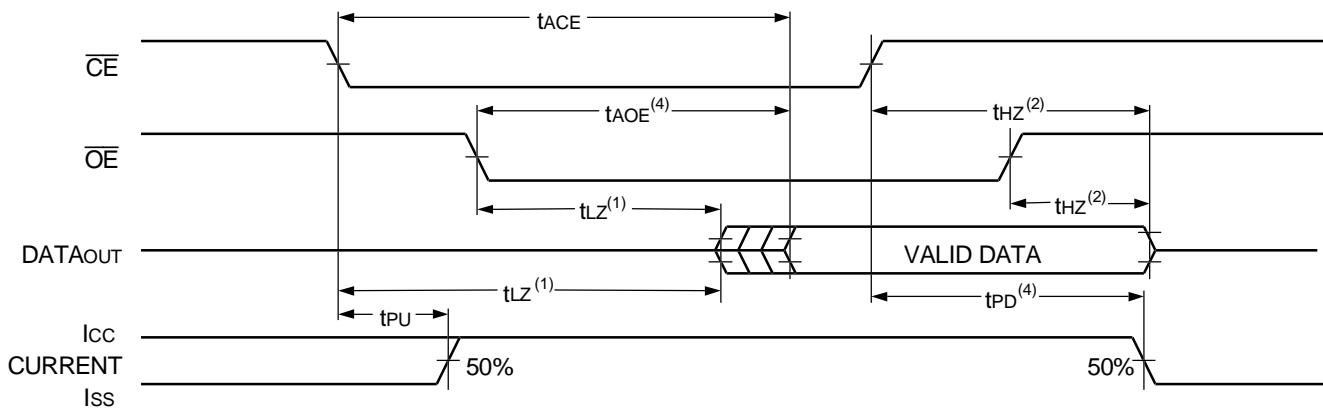
### Timing Waveform of Read Cycle No. 1, Either Side<sup>(1)</sup>



**NOTES:**

1.  $R/\bar{W} = V_{IH}$ ,  $\bar{CE} = V_{IL}$ , and is  $\bar{OE} = V_{IL}$ . Address is valid prior to the coincidental with  $\bar{CE}$  transition LOW.
2.  $t_{BDD}$  delay is required only in the case where the opposite port is completing a write operation to the same address location. For simultaneous read operations  $\bar{BUSY}$  has no relationship to valid output data.
3. Start of valid data depends on which timing becomes effective last  $t_{AOE}$ ,  $t_{ACE}$ ,  $t_{AA}$ , and  $t_{BDD}$ .

### Timing Waveform of Read Cycle No. 2, Either Side<sup>(3)</sup>



**NOTES:**

1. Timing depends on which signal is asserted last,  $\bar{OE}$  or  $\bar{CE}$ .
2. Timing depends on which signal is de-asserted first,  $\bar{OE}$  or  $\bar{CE}$ .
3.  $R/\bar{W} = V_{IH}$  and  $\bar{OE} = V_{IL}$ , and the address is valid prior to or coincidental with  $\bar{CE}$  transition LOW.
4. Start of valid data depends on which timing becomes effective last  $t_{AOE}$ ,  $t_{ACE}$ ,  $t_{AA}$ , and  $t_{BDD}$ .



## AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range<sup>(4,5)</sup>

Symbol	Parameter	71321X20 71421X20 Com'l Only		71321X25 71421X25 Com'l Only		Unit
		Min.	Max.	Min.	Max.	
<b>WRITE CYCLE</b>						
t <sub>WC</sub>	Write Cycle Time <sup>(2)</sup>	20	—	25	—	ns
t <sub>EW</sub>	Chip Enable to End-of-Write	15	—	20	—	ns
t <sub>AW</sub>	Address Valid to End-of-Write	15	—	20	—	ns
t <sub>AS</sub>	Address Set-up Time	0	—	0	—	ns
t <sub>WP</sub>	Write Pulse Width <sup>(3)</sup>	15	—	15	—	ns
t <sub>WR</sub>	Write Recovery Time	0	—	0	—	ns
t <sub>DW</sub>	Data Valid to End-of-Write	10	—	12	—	ns
t <sub>HZ</sub>	Output High-Z Time <sup>(1)</sup>	—	10	—	10	ns
t <sub>DH</sub>	Data Hold Time	0	—	0	—	ns
t <sub>WZ</sub>	Write Enable to Output in High-Z <sup>(1)</sup>	—	10	—	10	ns
t <sub>OW</sub>	Output Active from End-of-Write <sup>(1)</sup>	0	—	0	—	ns

2691 tbl 09a

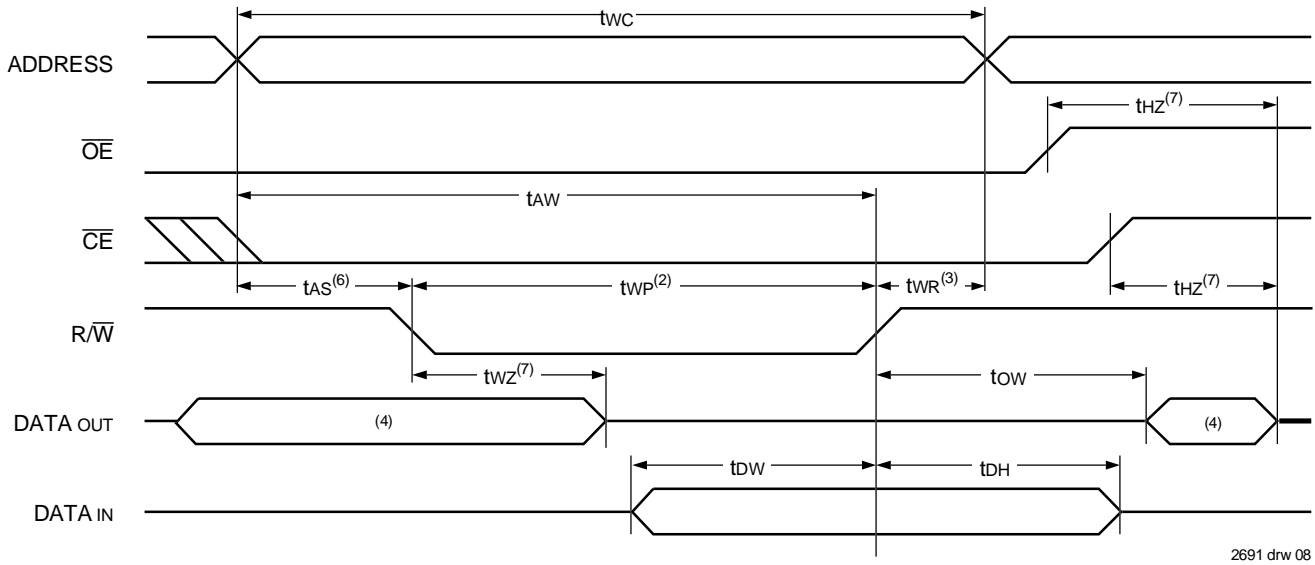
Symbol	Parameter	71321X35 71421X35 Com'l Only		71321X55 71421X55 Com'l & Ind		Unit
		Min.	Max.	Min.	Max.	
<b>WRITE CYCLE</b>						
t <sub>WC</sub>	Write Cycle Time <sup>(2)</sup>	35	—	55	—	ns
t <sub>EW</sub>	Chip Enable to End-of-Write	30	—	40	—	ns
t <sub>AW</sub>	Address Valid to End-of-Write	30	—	40	—	ns
t <sub>AS</sub>	Address Set-up Time	0	—	0	—	ns
t <sub>WP</sub>	Write Pulse Width <sup>(3)</sup>	25	—	30	—	ns
t <sub>WR</sub>	Write Recovery Time	0	—	0	—	ns
t <sub>DW</sub>	Data Valid to End-of-Write	15	—	20	—	ns
t <sub>HZ</sub>	Output High-Z Time <sup>(1)</sup>	—	15	—	25	ns
t <sub>DH</sub>	Data Hold Time	0	—	0	—	ns
t <sub>WZ</sub>	Write Enable to Output in High-Z <sup>(1)</sup>	—	15	—	30	ns
t <sub>OW</sub>	Output Active from End-of-Write <sup>(1)</sup>	0	—	0	—	ns

2691 tbl 09b

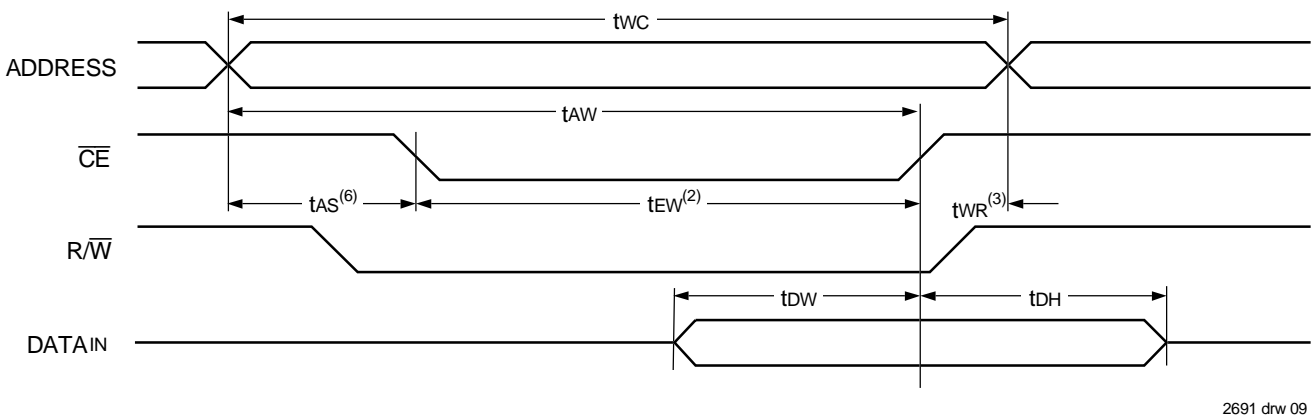
### NOTES:

1. Transition is measured  $\pm 500\text{mV}$  from Low or High-impedance voltage with Output Test Load (Figure 2). This parameter is guaranteed by device characterization but is not production tested.
2. For Master/Slave combination,  $t_{WC} = t_{BAA} + t_{WP}$ , since  $R/\bar{W} = V_{IL}$  must occur after  $t_{BAA}$ .
3. If  $\overline{OE}$  is LOW during a  $R/\bar{W}$  controlled write cycle, the write pulse width must be the larger of  $t_{WP}$  or  $(t_{WZ} + t_{DW})$  to allow the I/O drivers to turn off data to be placed on the bus for the required  $t_{DW}$ . If  $\overline{OE}$  is HIGH during a  $R/\bar{W}$  controlled write cycle, this requirement does not apply and the write pulse can be as short as the specified  $t_{WP}$ .
4. 'X' in part numbers indicates power rating (SA or LA).
5. Industrial temperature: for other speeds, packages and powers contact your sales office.

### Timing Waveform of Write Cycle No. 1, ( $\overline{R/\overline{W}}$ Controlled Timing)<sup>(1,5,8)</sup>



### Timing Waveform of Write Cycle No. 2, ( $\overline{CE}$ Controlled Timing)<sup>(1,5)</sup>



**NOTES:**

1.  $\overline{R/\overline{W}}$  or  $\overline{CE}$  must be HIGH during all address transitions.
2. A write occurs during the overlap ( $t_{EW}$  or  $t_{WP}$ ) of  $\overline{CE} = V_{IL}$  and  $\overline{R/\overline{W}} = V_{IL}$ .
3.  $t_{WR}$  is measured from the earlier of  $\overline{CE}$  or  $\overline{R/\overline{W}}$  going HIGH to the end of the write cycle.
4. During this period, the I/O pins are in the output state and input signals must not be applied.
5. If the  $\overline{CE}$  LOW transition occurs simultaneously with or after the  $\overline{R/\overline{W}}$  LOW transition, the outputs remain in the High-impedance state.
6. Timing depends on which enable signal ( $\overline{CE}$  or  $\overline{R/\overline{W}}$ ) is asserted last.
7. This parameter is determined to be device characterization, but is not production tested. Transition is measured  $\pm 500\text{mV}$  from steady state with the Output Test Load (Figure 2).
8. If  $\overline{OE}$  is LOW during a  $\overline{R/\overline{W}}$  controlled write cycle, the write pulse width must be the larger of  $t_{WP}$  or  $(t_{WZ} + t_{DW})$  to allow the I/O drivers to turn off data to be placed on the bus for the required  $t_{DW}$ . If  $\overline{OE}$  is HIGH during a  $\overline{R/\overline{W}}$  controlled write cycle, this requirement does not apply and the write pulse can be as short as the specified  $t_{WP}$ .

## AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range<sup>(6,7)</sup>

Symbol	Parameter	71321X20 71421X20 Com'l Only		71321X25 71421X25 Com'l Only		Unit
		Min.	Max.	Min.	Max.	
<b>BUSY TIMING (For MASTER 71321)</b>						
t <sub>BAA</sub>	$\overline{\text{BUSY}}$ Access Time from Address	—	20	—	20	ns
t <sub>BDA</sub>	$\overline{\text{BUSY}}$ Disable Time from Address	—	20	—	20	ns
t <sub>BAC</sub>	$\overline{\text{BUSY}}$ Access Time from Chip Enable	—	20	—	20	ns
t <sub>BDC</sub>	$\overline{\text{BUSY}}$ Disable Time from Chip Enable	—	20	—	20	ns
t <sub>WH</sub>	Write Hold After $\overline{\text{BUSY}}$ <sup>(6)</sup>	12	—	15	—	ns
t <sub>WDD</sub>	Write Pulse to Data Delay <sup>(1)</sup>	—	50	—	50	ns
t <sub>DDD</sub>	Write Data Valid to Read Data Delay <sup>(1)</sup>	—	35	—	35	ns
t <sub>APS</sub>	Arbitration Priority Set-up Time <sup>(2)</sup>	5	—	5	—	ns
t <sub>BDD</sub>	$\overline{\text{BUSY}}$ Disable to Valid Data <sup>(3)</sup>	—	25	—	35	ns
<b>BUSY INPUT TIMING (For SLAVE 71421)</b>						
t <sub>WB</sub>	Write to $\overline{\text{BUSY}}$ Input <sup>(4)</sup>	0	—	0	—	ns
t <sub>WH</sub>	Write Hold After $\overline{\text{BUSY}}$ <sup>(6)</sup>	12	—	15	—	ns
t <sub>WDD</sub>	Write Pulse to Data Delay <sup>(1)</sup>	—	40	—	50	ns
t <sub>DDD</sub>	Write Data Valid to Read Data Delay <sup>(1)</sup>	—	30	—	35	ns

2691 tbl 10a

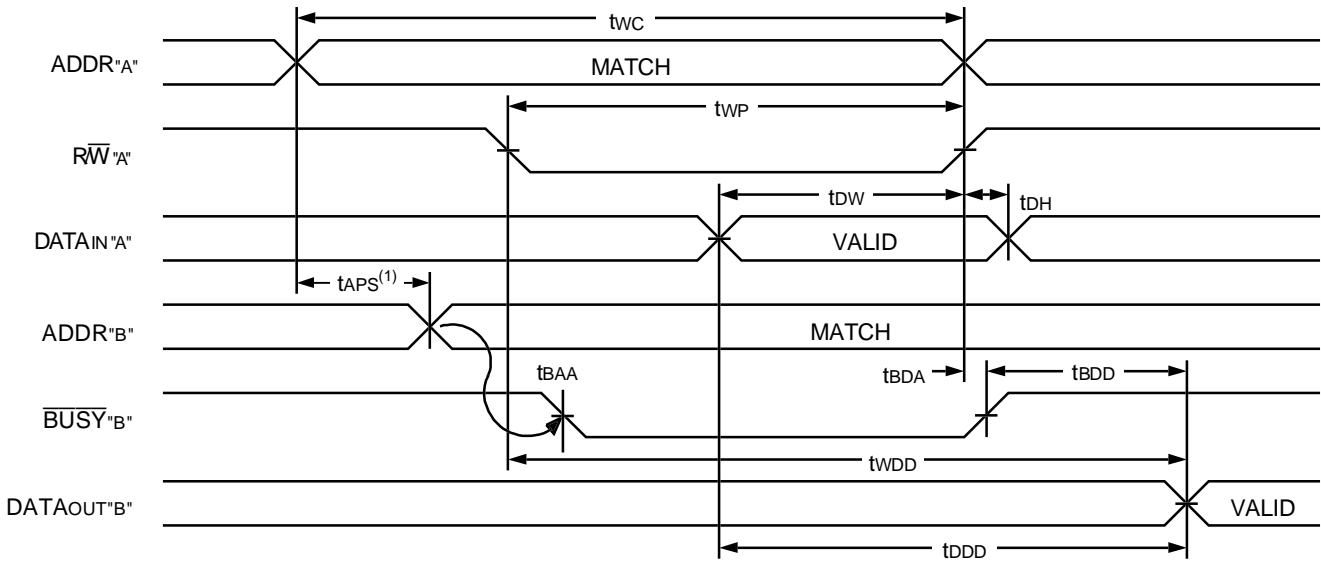
Symbol	Parameter	71321X35 71421X35 Com'l Only		71321X55 71421X55 Com'l & Ind		Unit
		Min.	Max.	Min.	Max.	
<b>BUSY TIMING (For MASTER 71321)</b>						
t <sub>BAA</sub>	$\overline{\text{BUSY}}$ Access Time from Address	—	20	—	30	ns
t <sub>BDA</sub>	$\overline{\text{BUSY}}$ Disable Time from Address	—	20	—	30	ns
t <sub>BAC</sub>	$\overline{\text{BUSY}}$ Access Time from Chip Enable	—	20	—	30	ns
t <sub>BDC</sub>	$\overline{\text{BUSY}}$ Disable Time from Chip Enable	—	20	—	30	ns
t <sub>WH</sub>	Write Hold After $\overline{\text{BUSY}}$ <sup>(6)</sup>	20	—	20	—	ns
t <sub>WDD</sub>	Write Pulse to Data Delay <sup>(1)</sup>	—	60	—	80	ns
t <sub>DDD</sub>	Write Data Valid to Read Data Delay <sup>(1)</sup>	—	35	—	55	ns
t <sub>APS</sub>	Arbitration Priority Set-up Time <sup>(2)</sup>	5	—	5	—	ns
t <sub>BDD</sub>	$\overline{\text{BUSY}}$ Disable to Valid Data <sup>(3)</sup>	—	35	—	50	ns
<b>BUSY INPUT TIMING (For SLAVE 71421)</b>						
t <sub>WB</sub>	Write to $\overline{\text{BUSY}}$ Input <sup>(4)</sup>	0	—	0	—	ns
t <sub>WH</sub>	Write Hold After $\overline{\text{BUSY}}$ <sup>(6)</sup>	20	—	20	—	ns
t <sub>WDD</sub>	Write Pulse to Data Delay <sup>(1)</sup>	—	60	—	80	ns
t <sub>DDD</sub>	Write Data Valid to Read Data Delay <sup>(1)</sup>	—	35	—	55	ns

2691 tbl 10b

### NOTES:

- Port-to-port delay through RAM cells from the writing port to the reading port, refer to "Timing Waveform of Write with Port-to-Port Read and BUSY."
- To ensure that the earlier of the two ports wins.
- t<sub>BDD</sub> is a calculated parameter and is the greater of 0, t<sub>WDD</sub> – t<sub>WP</sub> (actual) or t<sub>DDD</sub> – t<sub>DW</sub> (actual).
- To ensure that a write cycle is inhibited on port "B" during contention on port "A".
- To ensure that a write cycle is completed on port "B" after contention on port "A".
- 'X' in part numbers indicates power rating (SA or LA).
- Industrial temperature: for other speeds, packages and powers contact your sales office.

### Timing Waveform of Write with Port-to-Port Read and $\overline{\text{BUSY}}^{(2,3,4)}$

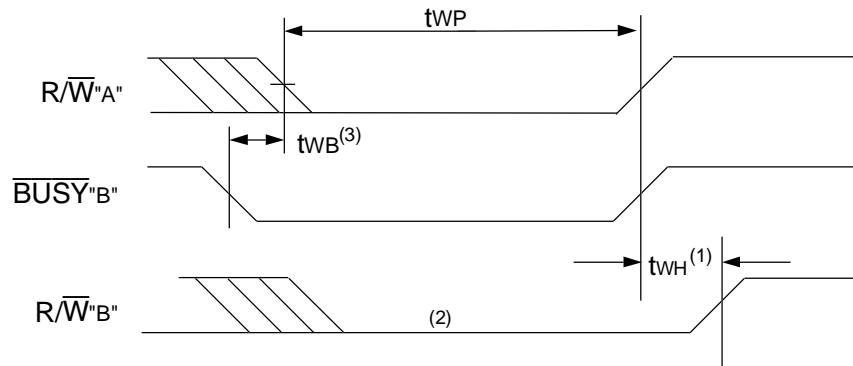


**NOTES:**

- To ensure that the earlier of the two ports wins. tAPS is ignored for Slave (71421).
- $\overline{\text{CEL}} = \overline{\text{CER}} = \text{VIL}$
- $\overline{\text{OE}} = \text{VIL}$  for the reading port.
- All timing is the same for the left and right ports. Port "A" may be either the left or right port. Port "B" is opposite from port "A".

2691 drw 10

### Timing Waveform of Write with $\overline{\text{BUSY}}^{(4)}$

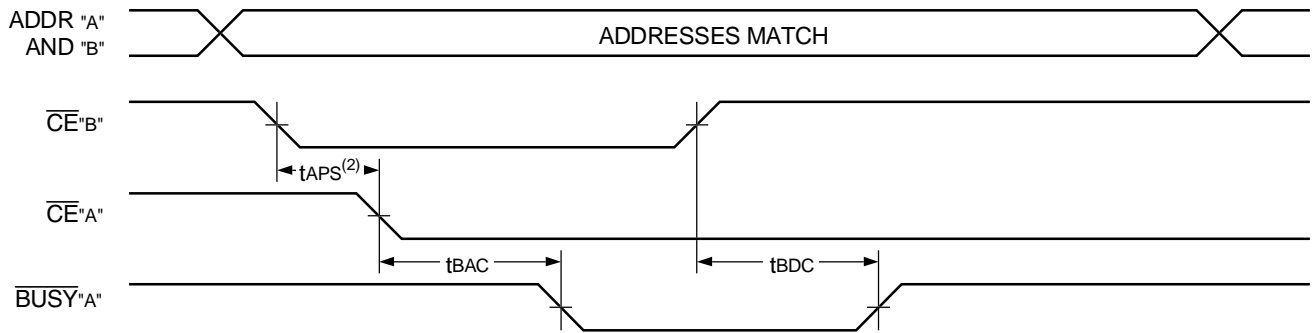


**NOTES:**

- tWH must be met for both  $\overline{\text{BUSY}}$  input (71421, slave) or output (71321, Master).
- $\overline{\text{BUSY}}$  is asserted on port "B" blocking  $\overline{\text{RW}}^{\text{B}}$ , until  $\overline{\text{BUSY}}^{\text{B}}$  goes HIGH.
- tWB is only for the slave version (71421).
- All timing is the same for the left and right ports. Port "A" may be either the left or right port. Port "B" is opposite from port "A".

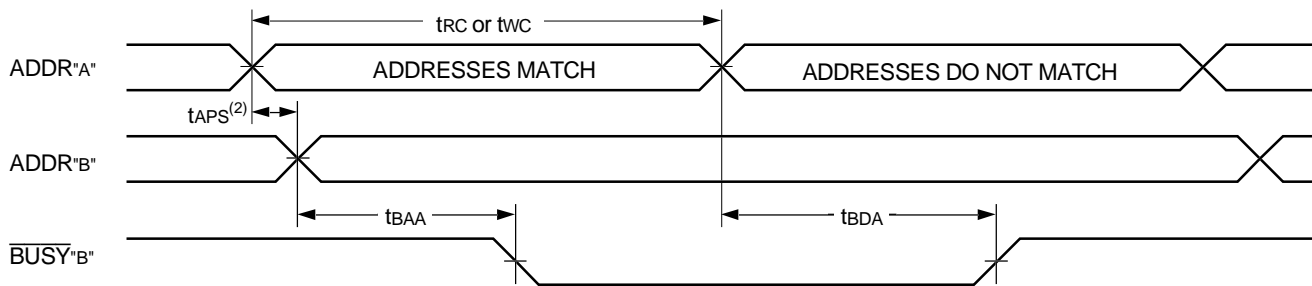
2691 drw 11

## Timing Waveform of $\overline{\text{BUSY}}$ Arbitration Controlled by $\overline{\text{CE}}$ Timing<sup>(1)</sup>



2691 drw 12

## Timing Waveform of $\overline{\text{BUSY}}$ Arbitration Controlled by Address Match Timing<sup>(1)</sup>



2691 drw 13

### NOTES:

1. All timing is the same for left and right ports. Port "A" may be either left or right port. Port "B" is the opposite from port "A".
2. If tAPS is not satisfied, the  $\overline{\text{BUSY}}$  will be asserted on one side or the other, but there is no guarantee on which side  $\overline{\text{BUSY}}$  will be asserted (71321 only).

## AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range<sup>(1,2)</sup>

Symbol	Parameter	71321X20 71421X20 Com'l Only		71321X25 71421X25 Com'l Only		Unit
		Min.	Max.	Min.	Max.	
<b>INTERRUPT TIMING</b>						
tAS	Address Set-up Time	0	—	0	—	ns
tWR	Write Recovery Time	0	—	0	—	ns
tNS	Interrupt Set Time	—	20	—	25	ns
tNR	Interrupt Reset Time	—	20	—	25	ns

2691 tbl 11a

### NOTES:

1. 'X' in part numbers indicates power rating (SA or LA).
2. Industrial temperature: for other speeds, packages and powers contact your sales office.

## AC Electrical Characteristics Over the Operating Temperature Supply Voltage Range<sup>(1,2)</sup>

Symbol	Parameter	71321X35 71421X35 Com'l Only		71321X55 71421X55 Com'l & Ind		Unit
		Min.	Max.	Min.	Max.	
<b>INTERRUPT TIMING</b>						
t <sub>AS</sub>	Address Set-up Time	0	—	0	—	ns
t <sub>WR</sub>	Write Recovery Time	0	—	0	—	ns
t <sub>INS</sub>	Interrupt Set Time	—	25	—	45	ns
t <sub>NR</sub>	Interrupt Reset Time	—	25	—	45	ns

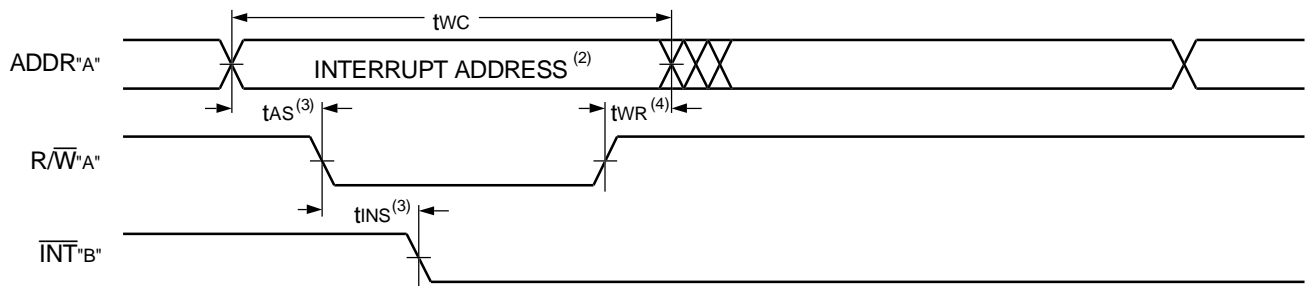
2691 tbl 11b

**NOTES:**

- 'X' in part numbers indicates power rating (SA or LA).
- Industrial temperature: for other speeds, packages and powers contact your sales office.

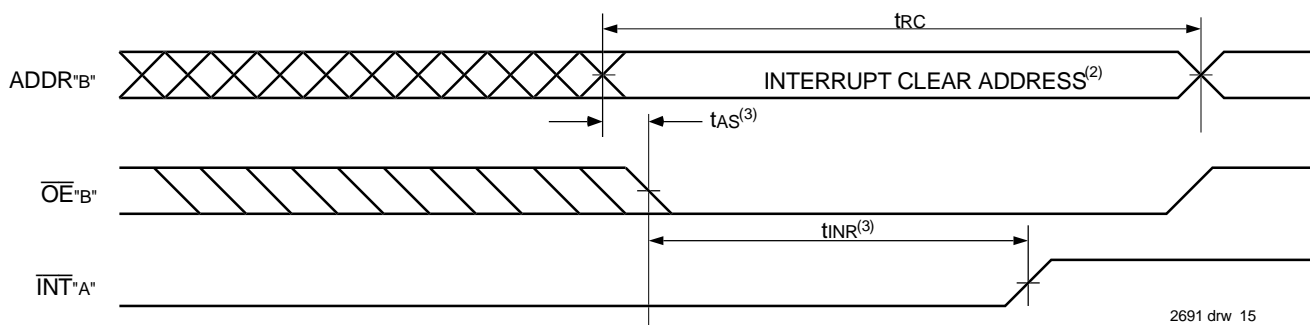
### Timing Waveform of Interrupt Mode<sup>(1)</sup>

#### SET $\overline{\text{INT}}$



2691 drw 14

#### CLEAR $\overline{\text{INT}}$



2691 drw 15

**NOTES:**

- All timing is the same for left and right ports. Port "A" may be either left or right port. Port "B" is the opposite from port "A".
- See Interrupt Truth Table.
- Timing depends on which enable signal ( $\overline{\text{CE}}$  or  $\text{R}/\overline{\text{W}}$ ) is asserted last.
- Timing depends on which enable signal ( $\overline{\text{CE}}$  or  $\text{R}/\overline{\text{W}}$ ) is de-asserted first.

## Truth Tables

### Truth Table I. Non-Contention Read/Write Control<sup>(4)</sup>

Left or Right Port <sup>(1)</sup>				Function
R/W	$\overline{CE}$	$\overline{OE}$	D0-7	
X	H	X	Z	Port Disabled and in Power-Down Mode, ISB <sub>2</sub> or ISB <sub>4</sub>
X	H	X	Z	$\overline{CE}_R = \overline{CE}_L = V_H$ , Power-Down Mode, ISB <sub>1</sub> or ISB <sub>3</sub>
L	L	X	DATA <sub>IN</sub>	Data on Port Written Into Memory <sup>(2)</sup>
H	L	L	DATA <sub>OUT</sub>	Data in Memory Output on Port <sup>(3)</sup>
H	L	H	Z	High Impedance Outputs

2691 tbl 12

#### NOTES:

1. A<sub>0L</sub> - A<sub>10L</sub> ≠ A<sub>0R</sub> - A<sub>10R</sub>.
2. If  $\overline{BUSY} = L$ , data is not written.
3. If  $\overline{BUSY} = L$ , data may not be valid, see twDD and tdDD timing.
4. 'H' = V<sub>H</sub>, 'L' = V<sub>IL</sub>, 'X' = DON'T CARE, 'Z' = HIGH IMPEDANCE

### Truth Table II. Interrupt Flag<sup>(1,4)</sup>

Left Port					Right Port					Function
R/WL	$\overline{CE}_L$	$\overline{OE}_L$	A <sub>10L</sub> -A <sub>0L</sub>	$\overline{INT}_L$	R/W <sub>R</sub>	$\overline{CE}_R$	$\overline{OE}_R$	A <sub>10R</sub> -A <sub>0R</sub>	$\overline{INT}_R$	
L	L	X	7FF	X	X	X	X	X	L <sup>(2)</sup>	Set Right $\overline{INT}_R$ Flag
X	X	X	X	X	X	L	L	7FF	H <sup>(3)</sup>	Reset Right $\overline{INT}_R$ Flag
X	X	X	X	L <sup>(3)</sup>	L	L	X	7FE	X	Set Left $\overline{INT}_L$ Flag
X	L	L	7FE	H <sup>(2)</sup>	X	X	X	X	X	Reset Left $\overline{INT}_L$ Flag

2691 tbl 13

#### NOTES:

1. Assumes  $\overline{BUSY}_L = \overline{BUSY}_R = V_H$
2. If  $\overline{BUSY}_L = V_{IL}$ , then No Change.
3. If  $\overline{BUSY}_R = V_{IL}$ , then No Change.
4. 'H' = HIGH, 'L' = LOW, 'X' = DON'T CARE

### Truth Table III — Address $\overline{BUSY}$ Arbitration

Inputs			Outputs		Function
$\overline{CE}_L$	$\overline{CE}_R$	A <sub>0L</sub> -A <sub>10L</sub> A <sub>0R</sub> -A <sub>10R</sub>	$\overline{BUSY}_L$ <sup>(1)</sup>	$\overline{BUSY}_R$ <sup>(1)</sup>	
X	X	NO MATCH	H	H	Normal
H	X	MATCH	H	H	Normal
X	H	MATCH	H	H	Normal
L	L	MATCH	(2)	(2)	Write Inhibit <sup>(3)</sup>

2691 tbl 14

#### NOTES:

1. Pins  $\overline{BUSY}_L$  and  $\overline{BUSY}_R$  are both outputs for 71321 (Master). Both are inputs for 71421 (Slave).  $\overline{BUSY}_x$  outputs on the 71321 are open drain, not push-pull outputs. On slaves the  $\overline{BUSY}_x$  input internally inhibits writes.
2. 'L' if the inputs to the opposite port were stable prior to the address and enable inputs of this port. 'H' if the inputs to the opposite port became stable after the address and enable inputs of this port. If t<sub>APS</sub> is not met, either  $\overline{BUSY}_L$  or  $\overline{BUSY}_R = LOW$  will result.  $\overline{BUSY}_L$  and  $\overline{BUSY}_R$  outputs can not be LOW simultaneously.
3. Writes to the left port are internally ignored when  $\overline{BUSY}_L$  outputs are driving LOW regardless of actual logic level on the pin. Writes to the right port are internally ignored when  $\overline{BUSY}_R$  outputs are driving LOW regardless of actual logic level on the pin.

## Functional Description

The IDT71321/IDT71421 provides two ports with separate control, address and I/O pins that permit independent access for reads or writes to any location in memory. The IDT71321/IDT71421 has an automatic power down feature controlled by  $\overline{CE}$ . The  $\overline{CE}$  controls on-chip power down circuitry that permits the respective port to go into a standby mode when not selected ( $\overline{CE} = V_{IH}$ ). When a port is enabled, access to the entire memory array is permitted.

## Interrupts

If the user chooses the interrupt function, a memory location (mail box or message center) is assigned to each port. The left port interrupt flag ( $\overline{INTL}$ ) is asserted when the right port writes to memory location 7FE (HEX), where a write is defined as the  $\overline{CE}_R = R/\overline{WR} = V_{IL}$ , per Truth Table II. The left port clears the interrupt by accessing address location 7FE when  $\overline{CEL} = \overline{OEL} = V_{IL}$ , R/W is a "don't care". Likewise, the right port interrupt flag ( $\overline{INTR}$ ) is asserted when the left port writes to memory location 7FF (HEX) and to clear the interrupt flag ( $\overline{INTR}$ ), the right port must access the memory location 7FF. The message (8 bits) at 7FE or 7FF is user-defined, since it is an addressable SRAM location. If the interrupt function is not used, address locations 7FE and 7FF are not used as mail boxes, but as part of the random access memory. Refer to Truth Table II for the interrupt operation.

## Busy Logic

Busy Logic provides a hardware indication that both ports of the RAM have accessed the same location at the same time. It also allows one of the two accesses to proceed and signals the other side that the RAM is "Busy". The  $\overline{BUSY}$  pin can then be used to stall the access until the operation on the other side is completed. If a write operation has been attempted from the side that receives a busy indication, the write signal is gated internally to prevent the write from proceeding.

The use of  $\overline{BUSY}$  Logic is not required or desirable for all applications. In some cases it may be useful to logically OR the  $\overline{BUSY}$  outputs together and use any  $\overline{BUSY}$  indication as an interrupt source to flag the event of an illegal or illogical operation. In slave mode the  $\overline{BUSY}$  pin operates solely as a write inhibit input pin. Normal operation can be programmed by tying the  $\overline{BUSY}$  pins HIGH. If desired, unintended write operations can be prevented to a port by tying the  $\overline{BUSY}$  pin for that port LOW.

The  $\overline{BUSY}$  outputs on the IDT71321 (Master) are open drain type outputs and require open drain resistors to operate. If these SRAMs are

being expanded in depth, then the  $\overline{BUSY}$  indication for the resulting array does not require the use of an external AND gate.

## Width Expansion with Busy Logic Master/Slave Arrays

When expanding an SRAM array in width while using  $\overline{BUSY}$  logic, one master part is used to decide which side of the SRAM array will receive a  $\overline{BUSY}$  indication, and to output that indication. Any number of slaves to be addressed in the same address range as the master, use the  $\overline{BUSY}$  signal as a write inhibit signal. Thus on the IDT71321/IDT71421 SRAMs the  $\overline{BUSY}$  pin is an output if the part is Master (IDT7132), and the  $\overline{BUSY}$  pin is an input if the part is a Slave (IDT7142) as shown in Figure 3.

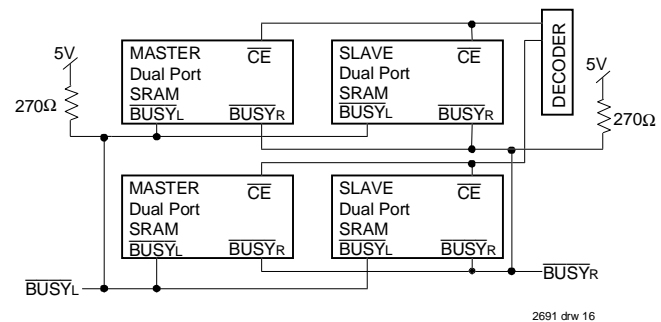


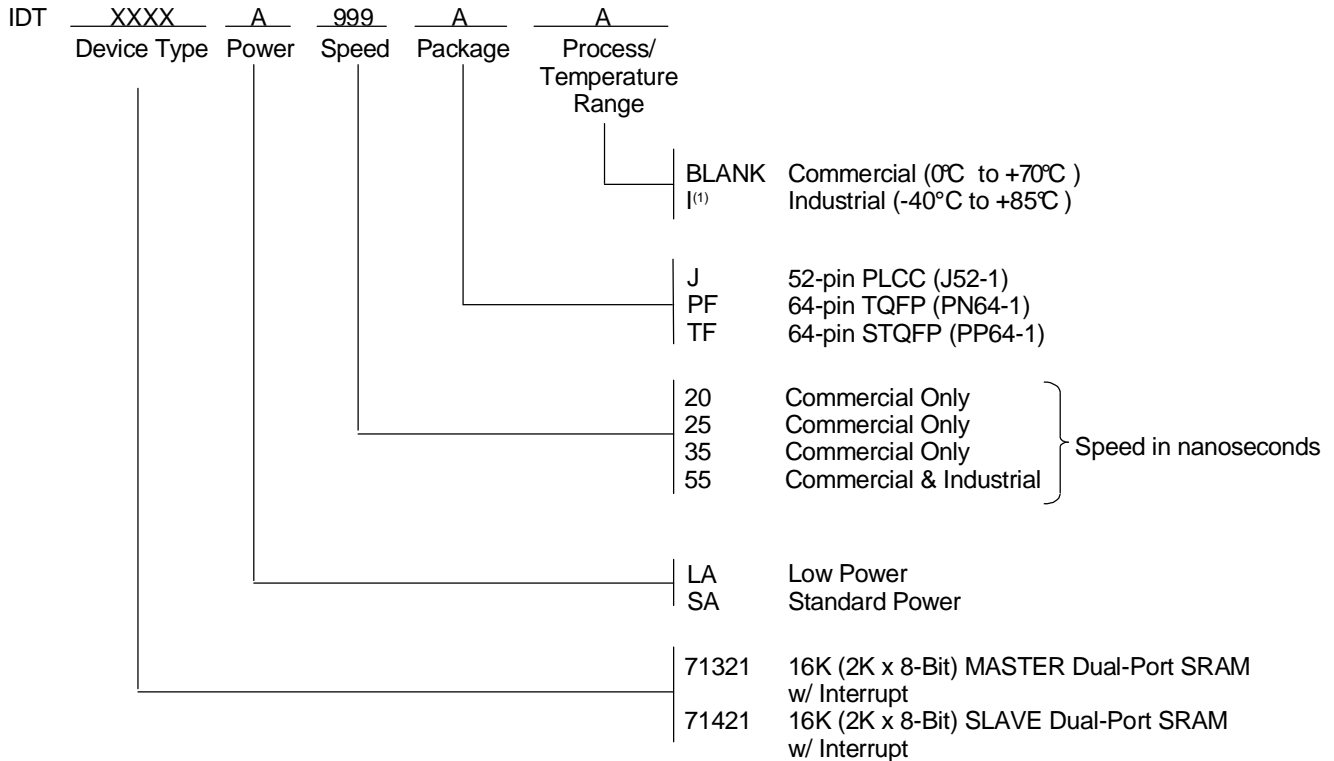
Figure 3. Busy and chip enable routing for both width and depth expansion with IDT71321 (Master) and (Slave) IDT71421 SRAMs.

If two or more master parts were used when expanding in width, a split decision could result with one master indicating  $\overline{BUSY}$  on one side of the array and another master indicating  $\overline{BUSY}$  on one other side of the array. This would inhibit the write operations from one port for part of a word and inhibit the write operations from the other port for the other part of the word.

The  $\overline{BUSY}$  arbitration, on a Master, is based on the chip enable and address signals only. It ignores whether an access is a read or write. In a master/slave array, both address and chip enable must be valid long enough for a  $\overline{BUSY}$  flag to be output from the master before the actual write pulse can be initiated with either the  $R/\overline{W}$  signal or the byte enables. Failure to observe this timing can result in a glitched internal write inhibit signal and corrupted data in the slave.



## Ordering Information



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### NOTE:

- Industrial temperature range is available in selected PLCC packages in standard power. For other speeds, packages and powers contact your sales office.

## Datasheet Document History

- 3/24/99: Initiated datasheet document history  
Converted to new format  
Cosmetic typographical corrections  
Pages 2 and 3 Added additional notes to pin configurations
- 6/7/99: Changed drawing format



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