PRELIMINARY DATA SHEET



MOS INTEGRATED CIRCUIT

μ PD45128441-I, 45128841-I, 45128163-I

128M-bit Synchronous DRAM 4-bank, LVTTL WTR (Wide Temperature Range)

Description

The μ PD45128441, 45128841, 45128163 are high-speed 134,217,728-bit synchronous dynamic random-access memories, organized as 8,388,608 \times 4 \times 4, 4,194,304 \times 8 \times 4, 2,097,152 \times 16 \times 4 (word \times bit \times bank), respectively.

The synchronous DRAMs achieved high-speed data transfer using the pipeline architecture.

All inputs and outputs are synchronized with the positive edge of the clock.

The synchronous DRAMs are compatible with Low Voltage TTL (LVTTL).

These products are packaged in 54-pin TSOP (II).

Features

- Fully Synchronous Dynamic RAM, with all signals referenced to a positive clock edge
- Pulsed interface
- Possible to assert random column address in every cycle
- Quad internal banks controlled by BA0(A13) and BA1(A12)
- Byte control (×16) by LDQM and UDQM
- Programmable Wrap sequence (Sequential / Interleave)
- Programmable burst length (1, 2, 4, 8 and full page)
- Programmable /CAS latency (2 and 3)
- Ambient temperature (T_A): -40 to + 85°C
- Automatic precharge and controlled precharge
- CBR (Auto) refresh and self refresh
- ×4, ×8, ×16 organization
- Single 3.3 V ± 0.3 V power supply
- LVTTL compatible inputs and outputs
- 4,096 refresh cycles / 64 ms
- Burst termination by Burst stop command and Precharge command

The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version. Not all devices/types available in every country. Please check with local Elpida Memory, Inc. for availability and additional information.

Document No. E0233N10 (Ver. 1.0)
Date Published November 2001 (K) Japa

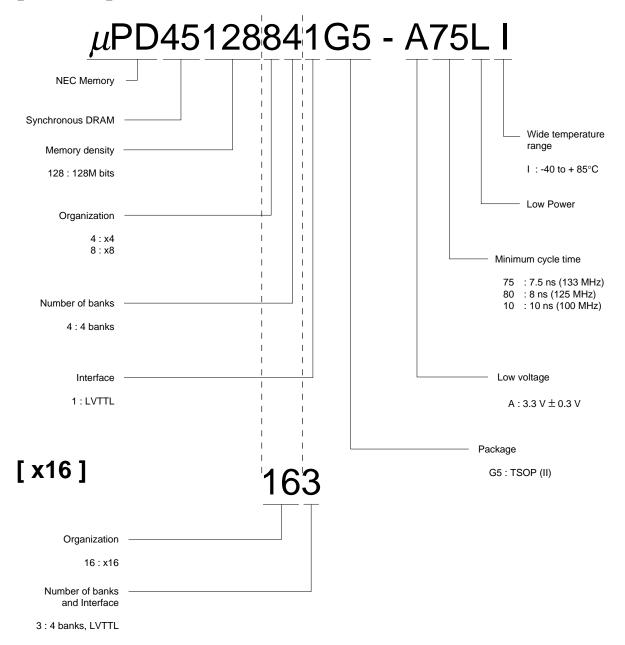
© Elpida Memory, Inc. 2001

Ordering Information

Part number	Organization (word \times bit \times bank)	Clock frequency MHz (MAX.)	Package	Note
μPD45128441G5-A75I-9JF	$8M \times 4 \times 4$	133	54-pin Plastic TSOP (II)	Ambient temperature
μPD45128441G5-A80I-9JF		125	(10.16mm (400))	$T_A = -40 \text{ to } + 85^{\circ}\text{C}$
μPD45128441G5-A10I-9JF		100		
μPD45128841G5-A75I-9JF	$4M \times 8 \times 4$	133		
μPD45128841G5-A80I-9JF		125		
μPD45128841G5-A10I-9JF		100		
μPD45128163G5-A75I-9JF	$2M \times 16 \times 4$	133		
μPD45128163G5-A80I-9JF		125		
μPD45128163G5-A10I-9JF		100		
μPD45128441G5-A75LI-9JF	$8M \times 4 \times 4$	133		
μPD45128441G5-A80LI-9JF		125		
μPD45128441G5-A10LI-9JF		100		
μPD45128841G5-A75LI-9JF	$4M \times 8 \times 4$	133		
μPD45128841G5-A80LI-9JF		125		
μPD45128841G5-A10LI-9JF		100		
μPD45128163G5-A75LI-9JF	$2M\times16\times4$	133		
μPD45128163G5-A80LI-9JF		125		
μPD45128163G5-A10LI-9JF		100		

Part Number

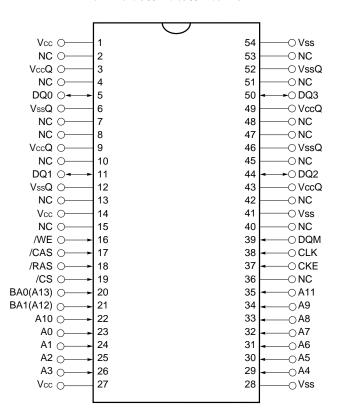
[x4, x8]



Pin Configurations

/xxx indicates active low signal.

[μPD45128441] 54-pin Plastic TSOP (II) (10.16mm (400)) 8M words × 4 bits × 4 banks



A0 to A11 Note: Address inputs BA0(A13), BA1(A12): Bank select

DQ0 to DQ3 : Data inputs / outputs

CLK : Clock input
CKE : Clock enable
/CS : Chip select

/RAS : Row address strobe
/CAS : Column address strobe

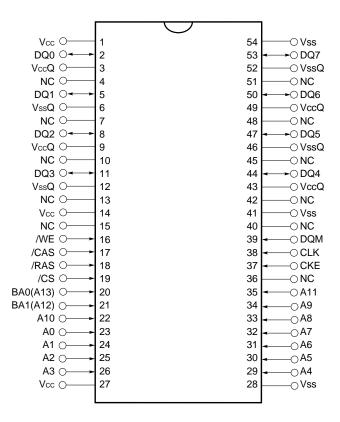
/WE : Write enableDQM : DQ mask enableVcc : Supply voltage

Vss : Ground

VccQ : Supply voltage for DQ Note A0 to A11 : Row address inputs
VssQ : Ground for DQ A0 to A9, A11 : Column address inputs

NC : No connection

[μPD45128841] 54-pin Plastic TSOP (II) (10.16mm (400)) 4M words × 8 bits × 4 banks



A0 to A11 Note: Address inputs BA0(A13), BA1(A12): Bank select

DQ0 to DQ7 : Data inputs / outputs

CLK : Clock input
CKE : Clock enable
/CS : Chip select

/RAS : Row address strobe
/CAS : Column address strobe

/WE : Write enable

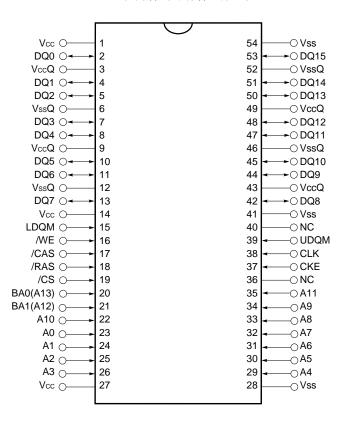
DQM : DQ mask enable

Vcc : Supply voltage

Vss : Ground Note A0 to A11 : Row address inputs
VccQ : Supply voltage for DQ A0 to A9 : Column address inputs

VssQ : Ground for DQ NC : No connection

[μPD45128163] 54-pin Plastic TSOP (II) (10.16mm (400)) 2M words × 16 bits × 4 banks



A0 to A11 Note: Address inputs BA0(A13), BA1(A12): Bank select

DQ0 to DQ15 : Data inputs / outputs

CLK : Clock input
CKE : Clock enable
/CS : Chip select

/RAS : Row address strobe
/CAS : Column address strobe

/WE : Write enable

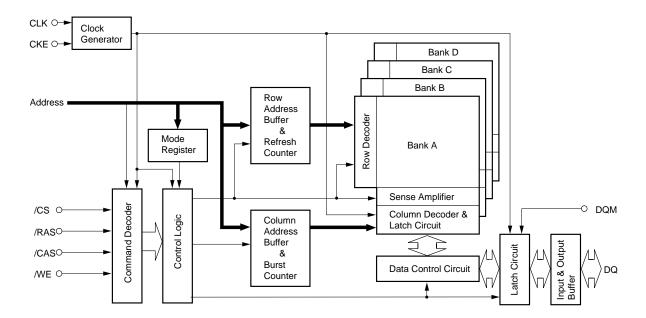
LDQM : Lower DQ mask enable
UDQM : Upper DQ mask enable

Vcc : Supply voltage

Vss : Ground Note A0 to A11 : Row address inputs
VccQ : Supply voltage for DQ A0 to A8 : Column address inputs

VssQ : Ground for DQ NC : No connection

Block Diagram



CONTENTS

1.	Input	t / Output Pin Function	. 10
2.	Com	mands	. 11
3.	Simp	olified State Diagram	. 14
4.	Truth	n Table	. 15
	4.1 (Command Truth Table	15
	4.2	DQM Truth Table	15
	4.3	CKE Truth Table	15
	4.4	Operative Command Table	16
	4.5	Command Truth Table for CKE	19
5.	Initia	lization	. 20
6.	Prog	ramming the Mode Register	. 21
7.	Mode	e Register	. 22
	7.1 E	Burst Length and Sequence	23
8.	Addr	ess Bits of Bank-Select and Precharge	. 24
9.	Preci	harge	. 25
10.	Auto	Precharge	. 26
	10.1	Read with Auto Precharge	26
	10.2	Write with Auto Precharge	27
11.	Read	I / Write Command Interval	. 28
	11.1	Read to Read Command Interval	28
	11.2	Write to Write Command Interval	28
	11.3	Write to Read Command Interval	29
	11.4	Read to Write Command Interval	30
12.	Burs	t Termination	
	12.1	Burst Stop Command	31
	12.2	Precharge Termination	
		12.2.1 Precharge Termination in READ Cycle	32
		12.2.2 Precharge Termination in WRITE Cycle	33

13.	Elect	rical Specifications	34
	13.1	AC Parameters for Read Timing	39
	13.2	AC Parameters for Write Timing	41
	13.3	Relationship between Frequency and Latency	42
	13.4	Mode Register Set	43
	13.5	Power on Sequence and CBR (Auto) Refresh	44
	13.6	/CS Function	45
	13.7	Clock Suspension during Burst Read (using CKE Function)	46
	13.8	Clock Suspension during Burst Write (using CKE Function)	48
	13.9	Power Down Mode and Clock Mask	50
	13.10	CBR (Auto) Refresh	51
	13.11	Self Refresh (Entry and Exit)	52
	13.12	Random Column Read (Page with Same Bank)	53
	13.13	Random Column Write (Page with Same Bank)	55
	13.14	Random Row Read (Ping-Pong Banks)	57
	13.15	Random Row Write (Ping-Pong Banks)	59
	13.16	Read and Write	61
	13.17	Interleaved Column Read Cycle	63
	13.18	Interleaved Column Write Cycle	65
	13.19	Auto Precharge after Read Burst	67
	13.20	Auto Precharge after Write Burst	69
	13.21	Full Page Read Cycle	71
	13.22	Full Page Write Cycle	73
	13.23	Byte Write Operation	75
	13.24	Burst Read and Single Write (Option)	77
	13.25	Full Page Random Column Read	79
	13.26	Full Page Random Column Write	81
	13.27	PRE (Precharge) Termination of Burst	83
14.	Packa	age Drawing	85
15.	Reco	mmended Soldering Conditions	86
16.	Revis	ion History	87

1. Input / Output Pin Function

Pin name	Input / Output	Function
CLK	Input	CLK is the master clock input. Other inputs signals are referenced to the CLK rising edge.
CKE	Input	CKE determine validity of the next CLK (clock). If CKE is high, the next CLK rising edge is valid; otherwise it is invalid. If the CLK rising edge is invalid, the internal clock is not issued and the μ PD45128xxx suspends operation. When the μ PD45128xxx is not in burst mode and CKE is negated, the device enters power down mode. During power down mode, CKE must remain low.
/CS	Input	/CS low starts the command input cycle. When /CS is high, commands are ignored but operations continue.
/RAS, /CAS, /WE	Input	/RAS, /CAS and /WE have the same symbols on conventional DRAM but different functions. For details, refer to the command table.
A0 - A11	Input	Row Address is determined by A0 - A11 at the CLK (clock) rising edge in the active command cycle. It does not depend on the bit organization. Column Address is determined by A0 - A9, A11 at the CLK rising edge in the read or write command cycle. It depends on the bit organization: A0 - A9, A11 for ×4 device, A0 - A9 for ×8 device, A0 - A8 for ×16 device. A10 defines the precharge mode. When A10 is high in the precharge command cycle, all banks are precharged; when A10 is low, only the bank selected by BA0(A13) and BA1(A12) is precharged. When A10 is high in read or write command cycle, the precharge starts automatically after the burst access.
BA0, BA1	Input	BA0(A13) and BA1(A12) are the bank select signal. In command cycle, BA0(A13) and BA1(A12) low select bank A, BA0(A13) high and BA1(A12) low select bank B, BA0(A13) low and BA1(A12) high select bank C and then BA0(A13) and BA1(A12) high select bank D.
DQM, UDQM, LDQM	Input	DQM controls I/O buffers. In ×16 products, UDQM and LDQM control upper byte and lower byte I/O buffers, respectively. In read mode, DQM controls the output buffers like a conventional /OE pin. DQM high and DQM low turn the output buffers off and on, respectively. The DQM latency for the read is two clocks. In write mode, DQM controls the word mask. Input data is written to the memory cell if DQM is low but not if DQM is high. The DQM latency for the write is zero.
DQ0 - DQ15	Input / Output	DQ pins have the same function as I/O pins on a conventional DRAM.
Vcc, Vss, VccQ, VssQ	(Power supply)	Vcc and Vss are power supply pins for internal circuits. VccQ and VssQ are power supply pins for the output buffers.

2. Commands

Mode register set command

The μ PD45128xxx has a mode register that defines how the device operates. In this command, A0 through A11, BA0(A13) and BA1(A12) are the data input pins. After power on, the mode register set command must be executed to initialize the device.

The mode register can be set only when all banks are in idle state. During 2 CLK (trsc) following this command, the μ PD45128xxx cannot accept any other commands.

Activate command

The μ PD45128xxx has four banks, each with 4,096 rows. This command activates the bank selected by BA0(A13) and BA1(A12) and a row address selected by A0 through A11.

This command corresponds to a conventional DRAM's /RAS falling.

Precharge command

This command begins precharge operation of the bank selected by BA0(A13) and BA1(A12). When A10 is High, all banks are precharged, regardless of BA0(A13) and BA1(A12). When A10 is Low, only the bank selected by BA0(A13) and BA1(A12) is precharged.

After this command, the μ PD45128xxx can't accept the activate command to the precharging bank during tRP (precharge to activate command period).

This command corresponds to a conventional DRAM's /RAS rising.

Fig.1 Mode register set command

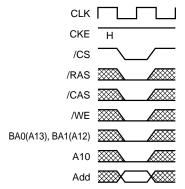


Fig.2 Row address strobe and bank activate command

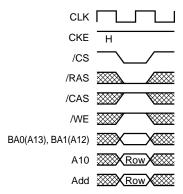
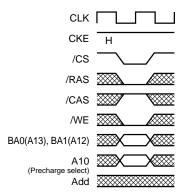


Fig.3 Precharge command



Write command

If the mode register is in the burst write mode, this command sets the burst start address given by the column address to begin the burst write operation. The first write data in burst mode can input with this command with subsequent data on following clocks.

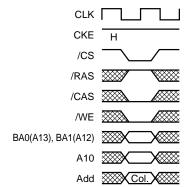


Fig.4 Column address and write command

Read command

Read data is available after /CAS latency requirements have been met. This command sets the burst start address given by the column address.

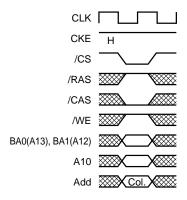


Fig.5 Column address and read command

CBR (auto) refresh command

This command is a request to begin the CBR (auto) refresh operation. The refresh address is generated internally.

Before executing CBR (auto) refresh, all banks must be precharged. After this cycle, all banks will be in the idle (precharged) state and ready for a row activate command.

During tRc period (from refresh command to refresh or activate command), the µPD45128xxx cannot accept any other command.

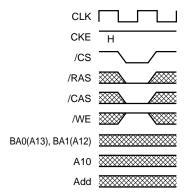


Fig.6 CBR (auto) refresh command

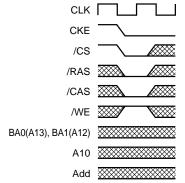
Self refresh entry command

After the command execution, self refresh operation continues while CKE remains low. When CKE goes high, the μ PD45128xxx exits the self refresh mode.

During self refresh mode, refresh interval and refresh operation are performed internally, so there is no need for external control.

Before executing self refresh, all banks must be precharged.

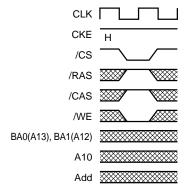
Fig.7 Self refresh entry command



Burst stop command

This command can stop the current burst operation.

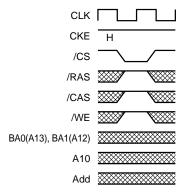
Fig.8 Burst stop command in Full Page Mode



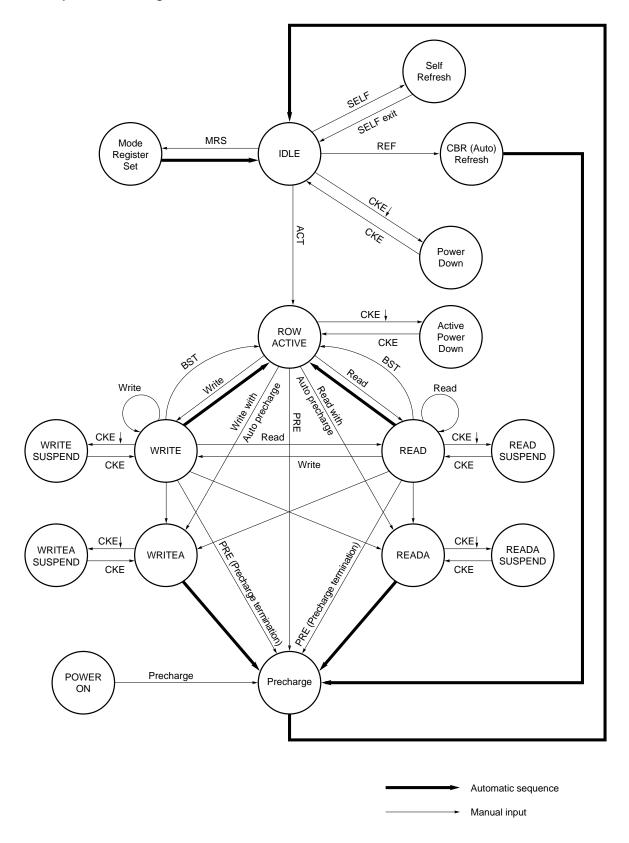
No operation

This command is not an execution command. No operations begin or terminate by this command.

Fig.9 No operation



3. Simplified State Diagram



4. Truth Table

4.1 Command Truth Table

Function	Symbol	CI	KE	/CS	/RAS	/CAS	/WE	BA1,	A10	A11,
		n – 1	n					BA0		A9 - A0
Device deselect	DESL	Н	×	Н	×	×	×	×	×	×
No operation	NOP	Н	×	L	Н	Н	Н	×	×	×
Burst stop	BST	Н	×	L	Н	Н	L	×	×	×
Read	READ	Н	×	L	Н	L	Н	V	L	V
Read with auto precharge	READA	Н	×	L	Н	L	Н	V	Н	٧
Write	WRIT	Н	×	L	Н	L	L	V	L	٧
Write with auto precharge	WRITA	Н	×	L	Н	L	L	V	Н	V
Bank activate	ACT	Н	×	L	L	Н	Н	V	V	V
Precharge select bank	PRE	Н	×	L	L	Н	L	٧	L	×
Precharge all banks	PALL	Н	×	L	L	Н	L	×	Н	×
Mode register set	MRS	Н	×	L	L	L	L	L	L	V

Remark H = High level, L = Low level, × = High or Low level (Don't care), V = Valid data input

4.2 DQM Truth Table

Function	Symbol	Cl	ΚE	DQM				
		n – 1	n	U	L			
Data write / output enable	ENB	Н	×	l	-			
Data mask / output disable	MASK	Н	×	Н				
Upper byte write enable / output enable	ENBU	Н	×	L	×			
Lower byte write enable / output enable	ENBL	Н	×	×	L			
Upper byte write inhibit / output disable	MASKU	Н	×	Н	×			
Lower byte write inhibit / output disable	MASKL	Н	×	×	Н			

Remark $H = High level, L = Low level, <math>\times = High or Low level (Don't care)$

4.3 CKE Truth Table

Current state	Function	Symbol	CI	CKE		/RAS	/CAS	/WE	Address
			n – 1	n					
Activating	Clock suspend mode entry		Н	L	×	×	×	×	×
Any	Clock suspend mode		L	L	×	×	×	×	×
Clock suspend	Clock suspend mode exit		L	Н	×	×	×	×	×
Idle	CBR (auto) refresh command	REF	Н	Н	L	L	L	Н	×
Idle	Self refresh entry	SELF	Н	L	L	L	L	Н	×
Self refresh	Self refresh exit		L	Н	L	Н	Н	Н	×
			L	Н	Н	×	×	×	×
Idle	Power down entry		Н	L	×	×	×	×	×
Power down	Power down exit		L	Н	Н	×	×	×	×
			L	Н	L	Н	Н	Н	×

Remark $H = High level, L = Low level, <math>\times = High or Low level (Don't care)$

4.4 Operative Command Table Note1

(1/3)

Current state	/CS	/RAS	/CAS	/WE	Address	Command	Action	Notes
Idle	Н	×	×	×	×	DESL	Nop or power down	2
	L	Н	Н	×	×	NOP or BST	Nop or power down	2
	L	Н	L	Н	BA, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BA, RA	ACT	Row activating	
	L	L	Н	L	BA, A10	PRE/PALL	Nop	
	L	L	L	Н	×	REF/SELF	CBR (auto) refresh or self refresh	4
	L	L	L	L	Op-Code	MRS	Mode register accessing	
Row active	Н	×	×	×	×	DESL	Nop	
	L	Н	Н	×	×	NOP or BST	Nop	
	L	Н	L	Н	BA, CA, A10	READ/READA	Begin read : Determine AP	5
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	Begin write : Determine AP	5
	L	L	Н	Н	BA, RA	ACT	ILLEGAL	3
	L	L	Н	L	BA, A10	PRE/PALL	Precharge	6
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	
Read	Н	×	×	×	×	DESL	Continue burst to end \rightarrow Row active	
	L	Н	Н	Н	×	NOP	Continue burst to end \rightarrow Row active	
	L	Н	Н	L	×	BST	$Burststop\toRowactive$	
	L	Н	L	Н	BA, CA, A10	READ/READA	Terminate burst, new read : Determine AP	7
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	Terminate burst, start write : Determine AP	7, 8
	L	L	Н	Н	BA, RA	ACT	ILLEGAL	3
	L	L	Н	L	BA, A10	PRE/PALL	Terminate burst, precharging	
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	
Write	Н	×	×	×	×	DESL	Continue burst to end \rightarrow Write recovering	
	L	Н	Н	Н	×	NOP	Continue burst to end \rightarrow Write recovering	
	L	Н	Н	L	×	BST	$Burststop\toRowactive$	
	L	Н	L	Н	BA, CA, A10	READ/READA	Terminate burst, start read : Determine AP	7, 8
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	Terminate burst, new write : Determine AP	7
	L	L	Н	Н	BA, RA	ACT	ILLEGAL	3
	L	L	Н	L	BA, A10	PRE/PALL	Terminate burst, precharging	9
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	

(2/3)

Current etete	/CS	/DAC	/CAS	/\^/=	A ddroop	Command	Action	(2/3)
Current state					Address	Command		Notes
Read with auto	H .	×	×	×	×	DESL	Continue burst to end → Precharging	
precharge	_ L	H	Н	Н .	×	NOP	Continue burst to end → Precharging	
	L	Н	Н	L	X	BST	ILLEGAL	
	L	Н	L	Н	BA, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BA, RA	ACT	ILLEGAL	3
	L	L	Н	L	BA, A10	PRE/PALL	ILLEGAL	3
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	
Write with auto precharge	Н	×	×	×	×	DESL	Continue burst to end → Write recovering with auto precharge	
	L	Н	Н	Н	×	NOP	Continue burst to end → Write recovering with auto precharge	
	L	Н	Н	L	×	BST	ILLEGAL	
	L	Н	L	Н	BA, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Ι	BA, RA	ACT	ILLEGAL	3
	L	L	Н	L	BA, A10	PRE/PALL	ILLEGAL	3
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	
Precharging	Н	×	×	×	×	DESL	Nop → Enter idle after t _{RP}	
	L	Н	Н	Н	×	NOP	Nop → Enter idle after t _{RP}	
	L	Н	Н	L	×	BST	ILLEGAL	
	L	Н	L	Н	BA, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BA, RA	ACT	ILLEGAL	3
	L	L	Н	L	BA, A10	PRE/PALL	Nop → Enter idle after tRP	
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	
Row activating	Н	×	×	×	×	DESL	Nop → Enter bank active after t _{RCD}	
	L	Н	Н	Н	×	NOP	Nop → Enter bank active after t _{RCD}	
	L	Н	Н	L	×	BST	ILLEGAL	
	L	Н	L	Н	BA, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BA, RA	ACT	ILLEGAL	3, 10
	L	L	Н	L	BA, A10	PRE/PALL	ILLEGAL	3
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	

(3/3)

Current state	/CS	/RAS	/CAS	/WE	Address	Command	Action	Notes
Write recovering	Н	×	×	×	×	DESL	Nop → Enter row active after topL	
	L	Н	Н	Н	×	NOP	Nop → Enter row active after topL	
	L	Н	Н	L	×	BST	Nop → Enter row active after topL	
	L	Н	L	Н	BA, CA, A10	READ/READA	Start read, Determine AP	8
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	New write, Determine AP	
	L	L	Н	Н	BA, RA	ACT	ILLEGAL	3
	L	L	Н	L	BA, A10	PRE/PALL	ILLEGAL	3
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	
Write recovering	Н	×	×	×	×	DESL	Nop → Enter precharge after tdpl	
with auto precharge	L	Н	Н	Н	×	NOP	Nop → Enter precharge after topL	
	L	Н	Н	L	×	BST	Nop → Enter precharge after tdpL	
	L	Н	L	Н	BA, CA, A10	READ/READA	ILLEGAL	3, 8
	L	Н	L	L	BA, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BA, RA	ACT	ILLEGAL	3
	L	L	Н	L	BA, A10	PRE/PALL	ILLEGAL	
	L	L	L	Н	×	REF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS	ILLEGAL	
Refreshing	Н	×	×	×	×	DESL	Nop → Enter idle after tʀc	
	L	Н	Н	×	×	NOP/BST	$Nop \to Enter \ idle \ after \ t_RC$	
	L	Н	L	×	×	READ/WRIT	ILLEGAL	
	L	L	Н	×	×	ACT/PRE/PALL	ILLEGAL	
	L	L	L	×	×	REF/SELF/MRS	ILLEGAL	
Mode register	Н	×	×	×	×	DESL	Nop → Enter idle after t _{RSC}	
accessing	L	Н	Н	Н	×	NOP	Nop → Enter idle after trsc	
	L	Н	Н	L	×	BST	ILLEGAL	
	L	Н	L	×	×	READ/WRIT	ILLEGAL	
	L	L	×	×	×	ACT/PRE/PALL/ REF/SELF/MRS	ILLEGAL	

- Notes 1. All entries assume that CKE was active (High level) during the preceding clock cycle.
 - If all banks are idle, and CKE is inactive (Low level), μPD45128xxx will enter Power down mode.
 All input buffers except CKE will be disabled.
 - 3. Illegal to bank in specified states; Function may be legal in the bank indicated by Bank Address (BA), depending on the state of that bank.
 - **4.** If all banks are idle, and CKE is inactive (Low level), μPD45128xxx will enter Self refresh mode. All input buffers except CKE will be disabled.
 - 5. Illegal if tRCD is not satisfied.
 - 6. Illegal if tras is not satisfied.
 - 7. Must satisfy burst interrupt condition.
 - 8. Must satisfy bus contention, bus turn around, and/or write recovery requirements.
 - 9. Must mask preceding data which don't satisfy tDPL.
 - 10. Illegal if tred is not satisfied.

Remark H = High level, L = Low level, × = High or Low level (Don't care), V = Valid data

18

4.5 Command Truth Table for CKE

Current State	CI	KE	/CS	/RAS	/CAS	/WE	Address	Action	Notes
	n – 1	n							
Self refresh	Н	×	×	×	×	×	×	INVALID, CLK (n – 1) would exit self refresh	
	L	Н	Н	×	×	×	×	Self refresh recovery	
	L	Η	L	Н	Н	×	×	Self refresh recovery	
	L	Ι	L	Н	L	×	×	ILLEGAL	
	L	Ι	L	L	×	×	×	ILLEGAL	
	L	L	×	×	×	×	×	Maintain self refresh	
Self refresh recovery	Н	Н	Н	×	×	×	×	Idle after tRC	
	Н	Н	L	Н	Н	×	×	Idle after t _{RC}	
	Н	Н	L	Н	L	×	×	ILLEGAL	
	Н	Ι	L	L	×	×	×	ILLEGAL	
	Н	L	Н	×	×	×	×	ILLEGAL	
	Н	L	L	Н	Н	×	×	ILLEGAL	
	Н	L	L	Н	L	×	×	ILLEGAL	
	Н	L	L	L	×	×	×	ILLEGAL	
Power down	Н	×	×	×	×	×		INVALID, CLK (n – 1) would exit power down	
	L	Ι	Н	×	×	×	×	EXIT power down \rightarrow Idle	
	L	Ι	L	Н	Н	Н	×	EXIT power down \rightarrow Idle	
	L	L	×	×	×	×	×	Maintain power down mode	
All banks idle	Н	Н	Н	×	×	×		Refer to operations in Operative Command Table	
	Н	Н	L	Н	×	×		Refer to operations in Operative Command Table	
	Н	Н	L	L	Н	×		Refer to operations in Operative Command Table	
	Н	Н	L	L	L	Н	×	CBR (auto) Refresh	
	Н	Н	L	L	L	L	Op-Code	Refer to operations in Operative Command Table	
	Н	L	Н	×	×	×		Refer to operations in Operative Command Table	
	Н	L	L	Н	×	×		Refer to operations in Operative Command Table	
	Н	L	L	L	Н	×		Refer to operations in Operative Command Table	
	Н	L	L	L	L	Н	×	Self refresh	1
	Н	L	L	L	L	L	Op-Code	Refer to operations in Operative Command Table	
	L	×	×	×	×	×	×	Power down	1
Row active	Н	×	×	×	×	×	×	Refer to operations in Operative Command Table	
	L	×	×	×	×	×	×	Power down	1
Any state other than	Н	Н	×	×	×	×		Refer to operations in Operative Command Table	
listed above	Н	L	×	×	×	×	×	Begin clock suspend next cycle	2
	L	Н	×	×	×	×	×	Exit clock suspend next cycle	
	L	L	×	×	×	×	×	Maintain clock suspend	

Notes 1. Self refresh can be entered only from the all banks idle state. Power down can be entered only from all banks idle or row active state.

2. Must be legal command as defined in Operative Command Table.

Remark H = High level, L = Low level, × = High or Low level (Don't care)

5. Initialization

The synchronous DRAM is initialized in the power-on sequence according to the following.

- (1) To stabilize internal circuits, when power is applied, a 100 μ s or longer pause must precede any signal toggling.
- (2) After the pause, all banks must be precharged using the Precharge command (The Precharge all banks command is convenient).
- (3) Once the precharge is completed and the minimum trp is satisfied, the mode register can be programmed. After the mode register set cycle, trsc (2 CLK minimum) pause must be satisfied as well.
- (4) Two or more CBR (Auto) refresh must be performed.
- Remarks 1. The sequence of Mode register programming and Refresh above may be transposed.
 - 2. CKE and DQM must be held high until the Precharge command is issued to ensure data-bus Hi-Z.

6. Programming the Mode Register

The mode register is programmed by the Mode register set command using address bits A11 through A0, BA0(A13) and BA1(A12) as data inputs. The register retains data until it is reprogrammed or the device loses power.

The mode register has four fields;

Options: A11 through A7, BA0(A13), BA1(A12)

/CAS latency : A6 through A4

Wrap type : A3

Burst length : A2 through A0

Following mode register programming, no command can be issued before at least 2 CLK have elapsed.

/CAS Latency

/CAS latency is the most critical of the parameters being set. It tells the device how many clocks must elapse before the data will be available.

The value is determined by the frequency of the clock and the speed grade of the device. **13.3 Relationship between Frequency and Latency** shows the relationship of /CAS latency to the clock period and the speed grade of the device.

Burst Length

Burst Length is the number of words that will be output or input in a read or write cycle. After a read burst is completed, the output bus will become Hi-Z.

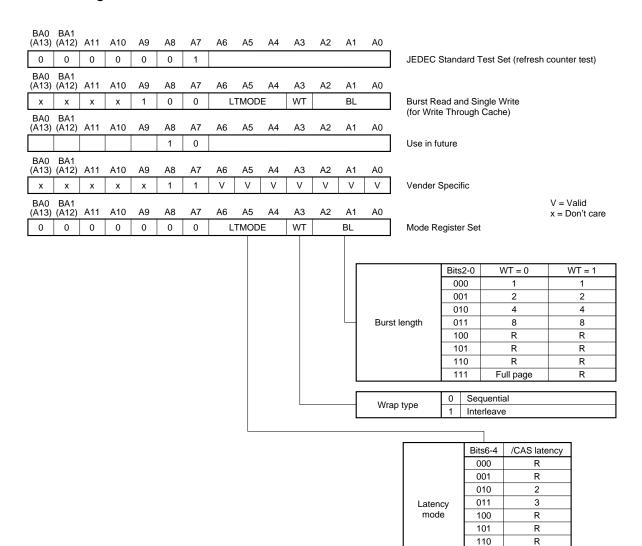
The burst length is programmable as 1, 2, 4, 8 or full page.

Wrap Type (Burst Sequence)

The wrap type specifies the order in which the burst data will be addressed. This order is programmable as either "Sequential" or "Interleave". The method chosen will depend on the type of CPU in the system.

Some microprocessor cache systems are optimized for sequential addressing and others for interleaved addressing. **7.1 Burst Length and Sequence** shows the addressing sequence for each burst length using them. Both sequences support bursts of 1, 2, 4 and 8. Additionally, sequence supports the full page length.

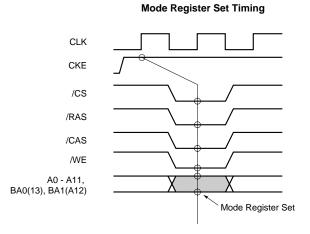
7. Mode Register



Remark R: Reserved

111

R



7.1 Burst Length and Sequence

[Burst of Two]

Starting address (column address A0, binary)	Sequential addressing sequence (decimal)	Interleave addressing sequence (decimal)		
0	0, 1	0, 1		
1	1, 0	1, 0		

[Burst of Four]

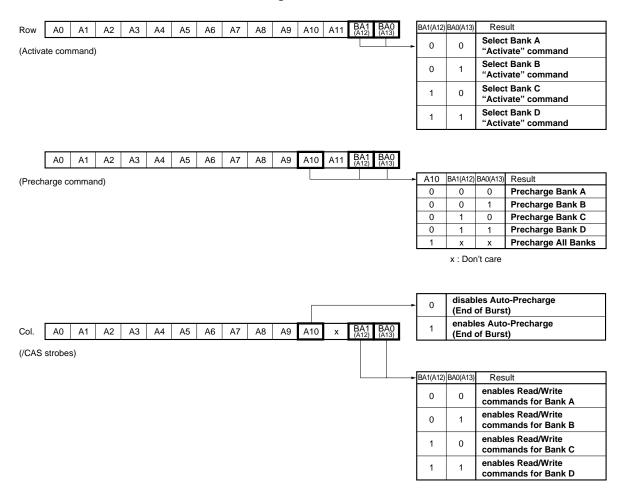
Starting address (column address A1 - A0, binary)	Sequential addressing sequence (decimal)	Interleave addressing sequence (decimal)
00	0, 1, 2, 3	0, 1, 2, 3
01	1, 2, 3, 0	1, 0, 3, 2
10	2, 3, 0, 1	2, 3, 0, 1
11	3, 0, 1, 2	3, 2, 1, 0

[Burst of Eight]

Starting address (column address A2 - A0, binary)	Sequential addressing sequence (decimal)	Interleave addressing sequence (decimal)
000	0, 1, 2, 3, 4, 5, 6, 7	0, 1, 2, 3, 4, 5, 6, 7
001	1, 2, 3, 4, 5, 6, 7, 0	1, 0, 3, 2, 5, 4, 7, 6
010	2, 3, 4, 5, 6, 7, 0, 1	2, 3, 0, 1, 6, 7, 4, 5
011	3, 4, 5, 6, 7, 0, 1, 2	3, 2, 1, 0, 7, 6, 5, 4
100	4, 5, 6, 7, 0, 1, 2, 3	4, 5, 6, 7, 0, 1, 2, 3
101	5, 6, 7, 0, 1, 2, 3, 4	5, 4, 7, 6, 1, 0, 3, 2
110	6, 7, 0, 1, 2, 3, 4, 5	6, 7, 4, 5, 2, 3, 0, 1
111	7, 0, 1, 2, 3, 4, 5, 6	7, 6, 5, 4, 3, 2, 1, 0

Full page burst is an extension of the above tables of sequential addressing, with the length being 2,048 (for $32M \times 4$ device), 1,024 (for $16M \times 8$ device), and 512 (for $8M \times 16$ device).

8. Address Bits of Bank-Select and Precharge



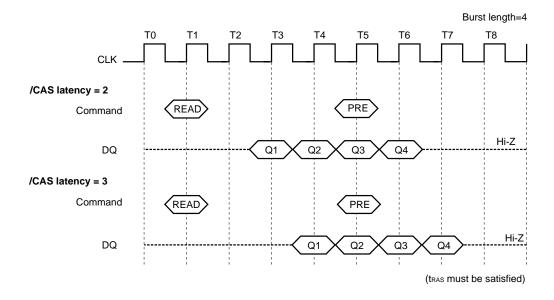
9. Precharge

The precharge command can be issued anytime after tras (MIN.) is satisfied.

Soon after the precharge command is issued, precharge operation performed and the synchronous DRAM enters the idle state after tree is satisfied. The parameter tree is the time required to perform the precharge.

The earliest timing in a read cycle that a precharge command can be issued without losing any data in the burst is as follows.

It is depending on the /CAS latency and clock cycle time.



In order to write all data to the memory cell correctly, the asynchronous parameter "tdpl" must be satisfied. The tdpl (MIN.) specification defines the earliest time that a precharge command can be issued. Minimum number of clocks is calculated by dividing tdpl (MIN.) with clock cycle time.

In summary, the precharge command can be issued relative to reference clock that indicates the last data word is valid. In the following table, minus means clocks before the reference; plus means time after the reference.

/CAS latency	Read	Write
2	–1	+topl (MIN.)
3	-2	+topl (MIN.)

10. Auto Precharge

During a read or write command cycle, A10 controls whether auto precharge is selected. A10 high in the Read or Write command (Read with Auto precharge command or Write with Auto precharge command), auto precharge is selected and begins automatically.

The tras must be satisfied with a read with auto precharge or a write with auto precharge operation. In addition, the next activate command to the bank being precharged cannot be executed until the precharge cycle ends.

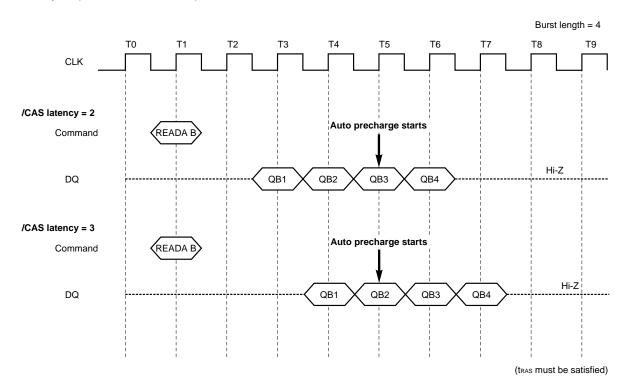
In read cycle, once auto precharge has started, an activate command to the bank can be issued after tRP has been satisfied.

In write cycle, the tDAL must be satisfied to issue the next activate command to the bank being precharged.

The timing that begins the auto precharge cycle depends on both the /CAS latency programmed into the mode register and whether read or write cycle.

10.1 Read with Auto Precharge

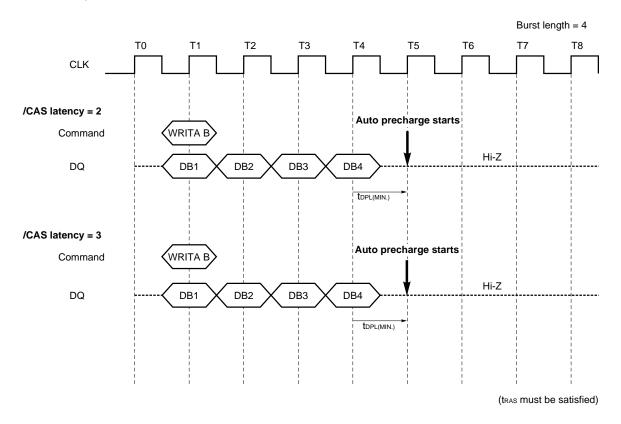
During a read cycle, the auto precharge begins one clock earlier (/CAS latency of 2) or two clocks earlier (/CAS latency of 3) the last data word output.



Remark READA means Read with Auto precharge

10.2 Write with Auto Precharge

During a write cycle, the auto precharge starts at the timing that is equal to the value of the tdpl (MIN.) after the last data word input to the device.



Remark WRITA means Write with Auto Precharge

In summary, the auto precharge begins relative to a reference clock that indicates the last data word is valid. In the table below, minus means clocks before the reference; plus means after the reference.

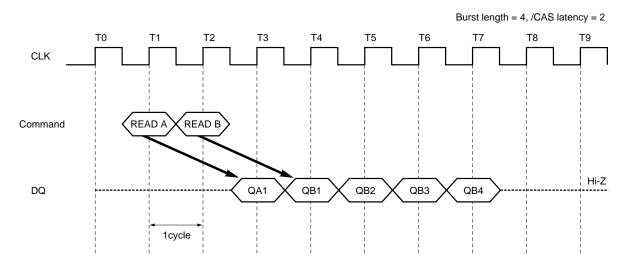
/CAS latency	Read	Write
2	–1	+tDPL (MIN.)
3	-2	+tDPL (MIN.)

11. Read / Write Command Interval

11.1 Read to Read Command Interval

During a read cycle, when new Read command is issued, it will be effective after /CAS latency, even if the previous read operation does not completed. READ will be interrupted by another READ.

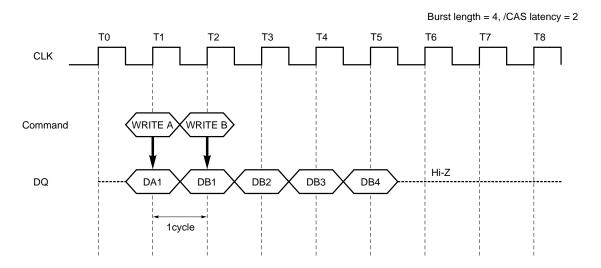
The interval between the commands is 1 cycle minimum. Each Read command can be issued in every clock without any restriction.



11.2 Write to Write Command Interval

During a write cycle, when a new Write command is issued, the previous burst will terminate and the new burst will begin with a new Write command. WRITE will be interrupted by another WRITE.

The interval between the commands is minimum 1 cycle. Each Write command can be issued in every clock without any restriction.

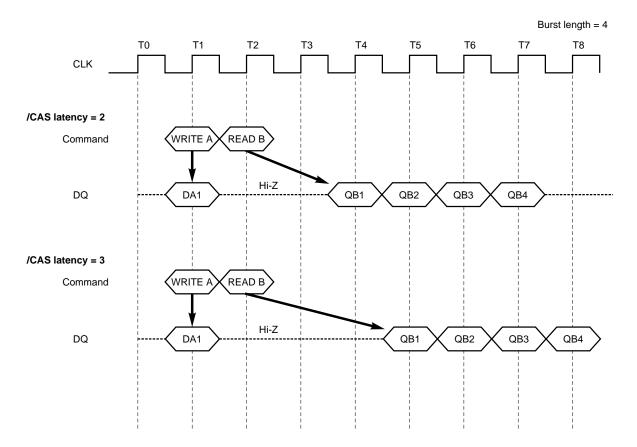


11.3 Write to Read Command Interval

Write command and Read command interval is also 1 cycle.

Only the write data before Read command will be written.

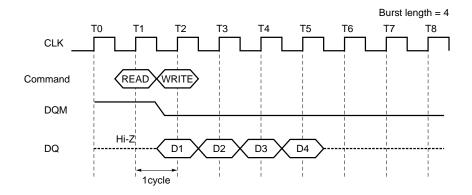
The data bus must be Hi-Z at least one cycle prior to the first Dout.



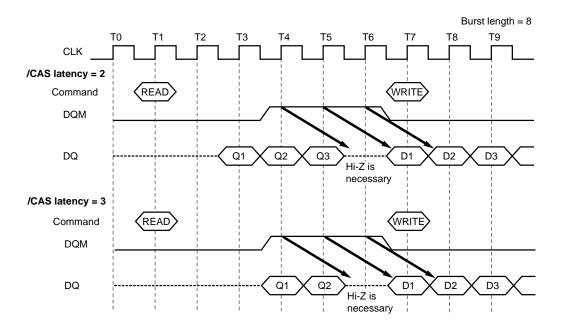
11.4 Read to Write Command Interval

During a read cycle, READ can be interrupted by WRITE.

The Read and Write command interval is 1 cycle minimum. There is a restriction to avoid data conflict. The Data bus must be Hi-Z using DQM before WRITE.



READ can be interrupted by WRITE. DQM must be High at least 3 clocks prior to the Write command.

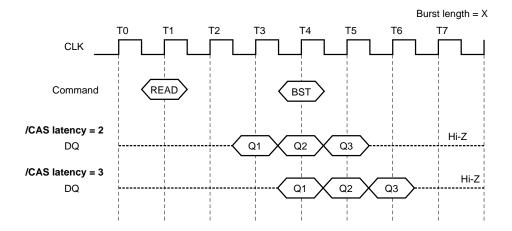


12. Burst Termination

There are two methods to terminate a burst operation other than using a Read or a Write command. One is the burst stop command and the other is the precharge command.

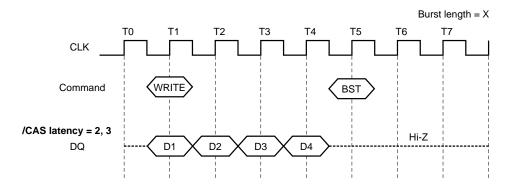
12.1 Burst Stop Command

During a read cycle, when the burst stop command is issued, the burst read data are terminated and the data bus goes to Hi-Z after the /CAS latency from the burst stop command.



Remark BST: Burst stop command

During a write cycle, when the burst stop command is issued, the burst write data are terminated and data bus goes to Hi-Z at the same clock with the burst stop command.



Remark BST: Burst stop command

12.2 Precharge Termination

12.2.1 Precharge Termination in READ Cycle

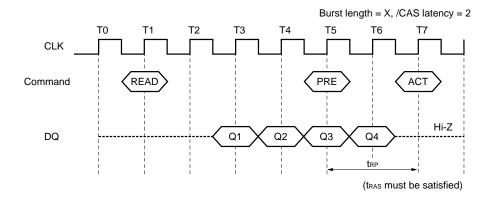
During a read cycle, the burst read operation is terminated by a precharge command.

When the precharge command is issued, the burst read operation is terminated and precharge starts.

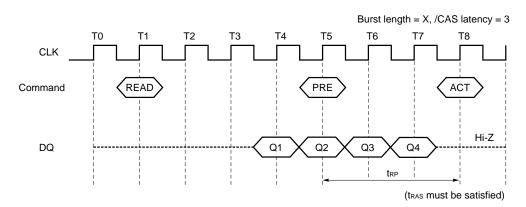
The same bank can be activated again after tRP from the precharge command.

To issue a precharge command, tras must be satisfied.

When /CAS latency is 2, the read data will remain valid until one clock after the precharge command.



When /CAS latency is 3, the read data will remain valid until two clocks after the precharge command.



12.2.2 Precharge Termination in WRITE Cycle

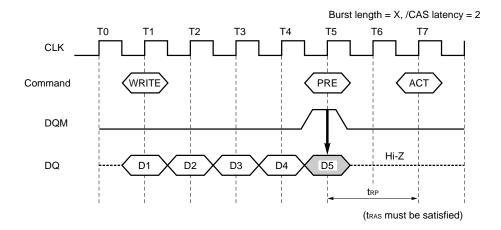
During a write cycle, the burst write operation is terminated by a precharge command.

When the precharge command is issued, the burst write operation is terminated and precharge starts.

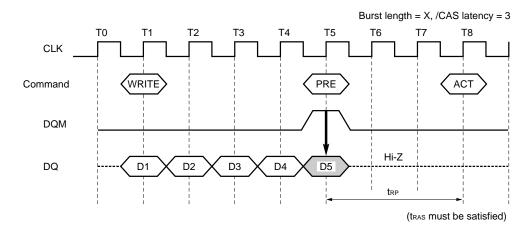
The same bank can be activated again after tRP from the precharge command.

To issue a precharge command, tras must be satisfied.

When /CAS latency is 2, the write data written prior to the precharge command will be correctly stored. However, invalid data may be written at the same clock as the precharge command. To prevent this from happening, DQM must be high at the same clock as the precharge command. This will mask the invalid data.



When /CAS latency is 3, the write data written prior to the precharge command will be correctly stored. However, invalid data may be written at the same clock as the precharge command. To prevent this from happening, DQM must be high at the same clock as the precharge command. This will mask the invalid data.



13. Electrical Specifications

- All voltages are referenced to Vss (GND).
- After power up, wait more than 100 μs and then, execute Power on sequence and CBR (auto) Refresh before
 proper device operation is achieved.

Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating	Unit
Voltage on power supply pin relative to GND	Vcc, VccQ		-0.5 to +4.6	V
Voltage on any pin relative to GND	VT		-0.5 to +4.6	V
Short circuit output current	lo		50	mA
Power dissipation	Po		1	W
Operating ambient temperature	TA		-40 to + 85	°C
Storage temperature	T _{stg}		-55 to + 125	°C

Caution Exposing the device to stress above those listed in Absolute Maximum Ratings could cause permanent damage. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

Recommended Operating Conditions

Recommended operating contained								
Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit		
Supply voltage	Vcc, VccQ		3.0	3.3	3.6	V		
High level input voltage	VIH		2.0		Vcc+0.3 ^{Note1}	V		
Low level input voltage	VIL		-0.3 ^{Note2}		+0.8	V		
Operating ambient temperature	TA		-40		85	°C		

Notes 1. Vih (MAX.) = Vcc + 1.5 V (Pulse width $\leq 5 ns$)

2. VIL (MIN.) = -1.5 V (Pulse width ≤ 5 ns)

Pin Capacitance (T_A = 25 °C, f = 1 MHz)

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input capacitance	C _{I1}	CLK	2.5		3.5	pF
	C ₁₂	A0 - A11, BA0(A13), BA1(A12), CKE, /CS, /RAS, /CAS, /WE, DQM, UDQM, LDQM	2.5		3.8	
Data input / output capacitance	C _{I/O}	DQ0 - DQ15	4		6.5	pF

DC Characteristics 1 (Recommended Operating Conditions unless otherwise noted)

Parameter	Symbol	Test condition	/CAS	Grade	1	Maximur	n	Unit	Notes
			latency		×4	×8	×16		
Operating current	Icc1	Burst length = 1,	CL = 2	-A75	100	100	110	mA	1
		$t_{RC} \ge t_{RC \text{ (MIN.)}}, \text{ Io = 0 mA},$		-A80	100	100	110		
		One bank active		-A10	100	100	110		
			CL = 3	-A75	105	105	115		
				-A80	100	100	110		
				-A10	100	100	110		
Precharge standby current	Icc2P	CKE ≤ VIL (MAX.), tck = 15 ns			1	1	1	mA	
in power down mode	Icc2PS	CKE ≤ VIL (MAX.), tck = ∞			1	1	1		
Precharge standby current	Icc2N	CKE ≥ VIH (MIN.), tck = 15 ns, /	CS ≥ VIH (N	IIN.),	20	20	20	mA	
in non power down mode		Input signals are changed one	time during	g 30 ns.					
	Icc2NS	CKE ≥ VIH (MIN.), tck = ∞,			8	8	8		
		Input signals are stable.							
Active standby current	Icc3P	CKE ≤ VIL (MAX.), tck = 15 ns			5	5	5	mA	
in power down mode	Icc3PS	CKE ≤ VIL (MAX.), tck = ∞			4	4	4		
Active standby current	Icc3N	CKE \geq ViH (MIN.), tck = 15 ns, /	CS ≥ VIH (N	IIN.),	30	30	30	mA	
in non power down mode		Input signals are changed one	time during	g 30 ns.					
	Icc3NS	CKE \geq V _{IH} (MIN.), t _{CK} = ∞ ,			20	20	20		
		Input signals are stable.							
Operating current	Icc4	$tck \ge tck (MIN.), Io = 0 mA,$	CL = 2	-A75	105	120	145	mA	2
(Burst mode)		All banks active		-A80	105	120	145		
				-A10	85	95	110		
			CL = 3	-A75	140	155	185		
				-A80	130	145	175		
				-A10	110	125	140		
CBR (auto) refresh current	Icc5	$t_{RC} \ge t_{RC \text{ (MIN.)}}$	CL = 2	-A75	230	230	230	mA	3
				-A80	230	230	230		
				-A10	230	230	230		
			CL = 3	-A75	240	240	240		
				-A80	230	230	230		
				-A10	230	230	230		
Self refresh current	Icc6	CKE ≤ 0.2 V		-**	2	2	2	mA	
				-**L	0.8	0.8	0.8	mA	

- **Notes 1.** lcc1 depends on output loading and cycle rates. Specified values are obtained with the output open. In addition to this, lcc1 is measured condition that addresses are changed only one time during tck (MIN.).
 - 2. Icc4 depends on output loading and cycle rates. Specified values are obtained with the output open. In addition to this, Icc4 is measured condition that addresses are changed only one time during tck (MIN.).
 - 3. Iccs is measured on condition that addresses are changed only one time during tck (MIN.).

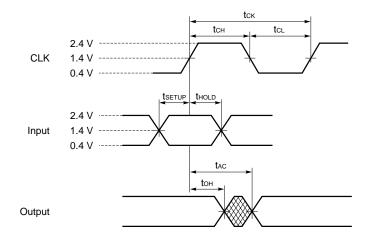
DC Characteristics 2 (Recommended Operating Conditions unless otherwise noted)

Parameter	Symbol	Test condition	MIN.	TYP.	MAX.	Unit	Note
Input leakage current	lı (L)	$0 \le V_1 \le V_{CC}Q$, $V_{CC}Q = V_{CC}$ All other pins not under test = 0 V	-1.0		+1.0	μΑ	
Output leakage current	lo (L)	$0 \le V_0 \le V_{CC}Q$, Dout is disabled	-1.5		+1.5	μΑ	
High level output voltage	Vон	Io = -4 mA	2.4			٧	
Low level output voltage	Vol	Io = +4 mA			0.4	V	

AC Characteristics (Recommended Operating Conditions unless otherwise noted)

Test Conditions

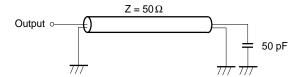
Parameter	Value	Unit
AC high level input voltage / low level input voltage	2.4 / 0.4	V
Input timing measurement reference level	1.4	V
Transition time (Input rise and fall time)	1	ns
Output timing measurement reference level	1.4	V



Synchronous Characteristics

Parameter		Symbol	-A75		-A80		-A10		Unit	Note
		•	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Clock cycle time	/CAS latency = 3	tскз	7.5	(133 MHz)	8	(125 MHz)	10	(100 MHz)	ns	
	/CAS latency = 2	tck2	10	(100 MHz)	10	(100 MHz)	13	(77 MHz)	ns	
Access time from CLK	/CAS latency = 3	t _{AC3}		5.4		6		6	ns	1
	/CAS latency = 2	t _{AC2}		6		6		7	ns	1
CLK high level width		tсн	2.5		3		3		ns	
CLK low level width		t cL	2.5		3		3		ns	
Data-out hold time		tон	2.7		2.7		2.7		ns	1
Data-out low-impedance time		tız	0		0		0		ns	
Data-out high-impedance time	/CAS latency = 3	t _{HZ3}	2.7	5.4	2.7	6	2.7	6	ns	
	/CAS latency = 2	t _{HZ2}	2.7	6	2.7	6	2.7	7	ns	
Data-in setup time		tos	1.5		2		2		ns	
Data-in hold time		tон	8.0		1		1		ns	
Address setup time		tas	1.5		2		2		ns	
Address hold time		t ah	8.0		1		1		ns	
CKE setup time		t cks	1.5		2		2		ns	
CKE hold time		tскн	8.0		1		1		ns	
CKE setup time (Power down exit)		tcksp	1.5		2		2		ns	
Command (/CS, /RAS, /CAS, /WE, DQM) setup time		tсмs	1.5		2		2		ns	
Command (/CS, /RAS, /CAS, /WE, DQM) hold time		tсмн	0.8		1		1		ns	

Note 1. Output load

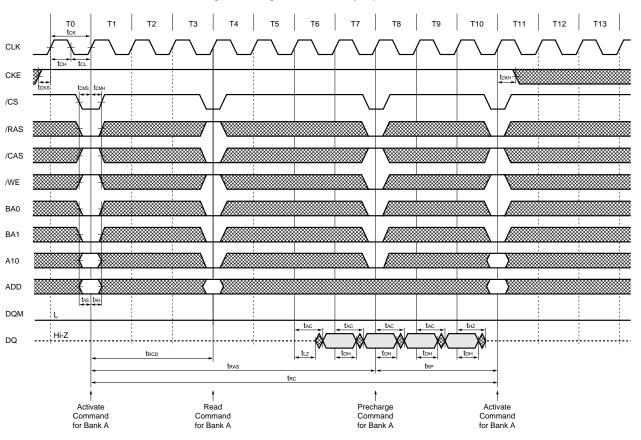


Asynchronous Characteristics

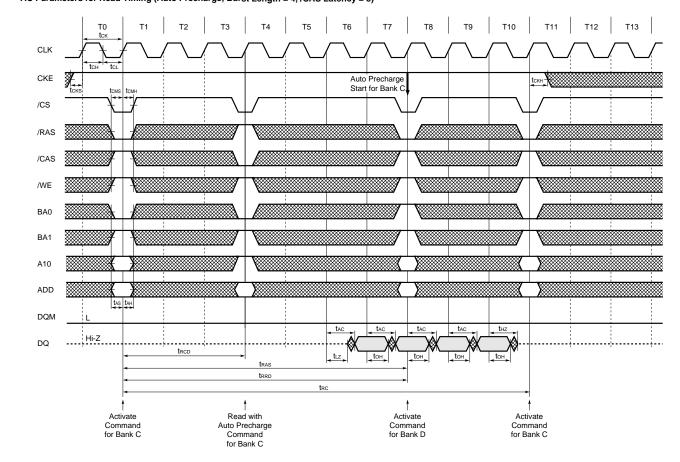
Parameter		Symbol	-A75		-A80		-A10		Unit	Note
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
ACT to REF/ACT command period (operation)		t RC	67.5		70		70		ns	
REF to REF/ACT command period (refresh)		t _{RC1}	67.5		70		70		ns	
ACT to PRE command period		tras	45	120,000	48	120,000	50	120,000	ns	
PRE to ACT command period		t RP	20		20		20		ns	
Delay time ACT to READ/WRITE command		tRCD	20		20		20		ns	
ACT (one) to ACT (another) command period		trrd	15		16		20		ns	
Data-in to PRE command period		topl	15		15		15		ns	
Data-in to ACT (REF) command period	/CAS latency = 3	t DAL3	1CLK +22.5		1CLK +20		1CLK +20		ns	1
(Auto precharge)	/CAS latency = 2	t _{DAL2}	1CLK +20		1CLK +20		1CLK +20		ns	
Mode register set cycle time		trsc	2		2		2		CLK	
Transition time		t⊤	0.5	30	0.5	30	1	30	ns	
Refresh time (4,096 refresh cycles)		t REF		64		64		64	ms	

Note 1. The -A75 grade device can satisfy the tDAL3 spec of 1CLK+20 ns for up to and including 125MHz operation.

13.1 AC Parameters for Read Timing (Manual Precharge, Burst Length = 4, /CAS Latency = 3)

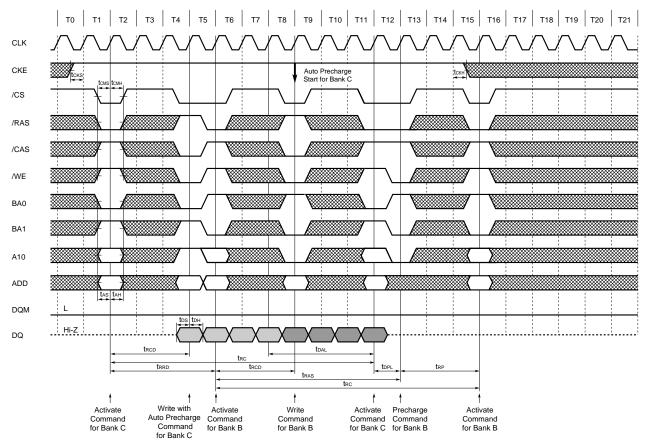






Preliminary Data Sheet E0233N10

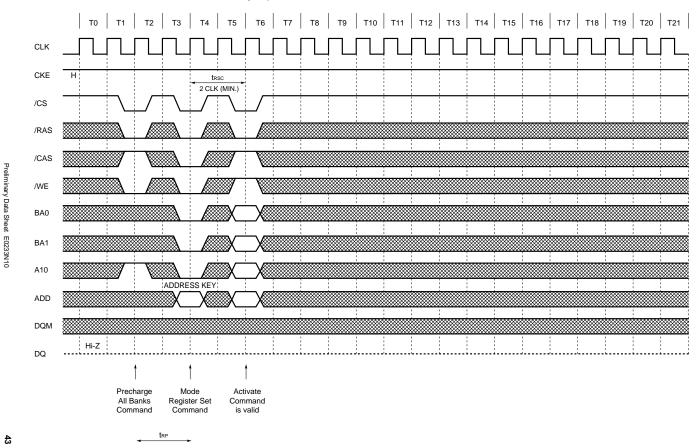
13.2 AC Parameters for Write Timing (Burst Length = 4, /CAS Latency = 3)



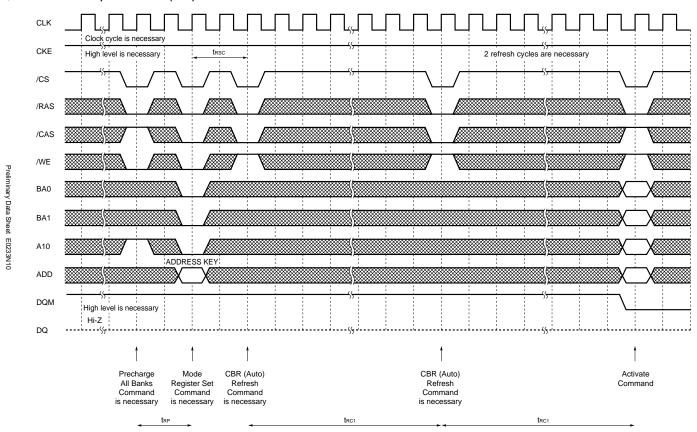
13.3 Relationship between Frequency and Latency

Speed version	-75		-	-80	-10		
Clock cycle time [ns]	7.5	10	8	10	10	13	
Frequency [MHz]	133	100	125	100	100	77	
/CAS latency	3	2	3	2	3	2	
[trcd]	3	2	3	2	2	2	
/RAS latency (/CAS latency + [tRCD])	6	4	6	4	5	4	
[trc]	9	7	9	7	7	6	
[trc1]	9	7	9	7	8	6	
[tras]	6	5	6	5	5	4	
[trrd]	2	2	2	2	2	2	
[trp]	3	2	3	2	2	2	
[tdpl]	2	2	2	2	2	2	
[tdal]	4	3	4	3	3	3	
[trsc]	2	2	2	2	2	2	

13.4 Mode Register Set (Burst Length = 4, /CAS Latency = 2)

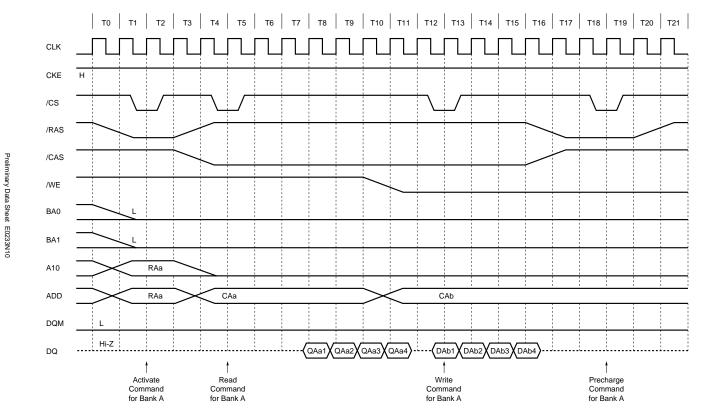


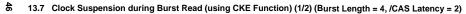


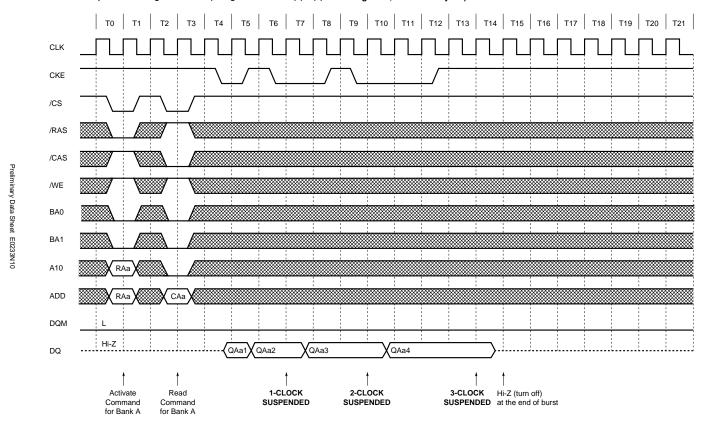


13.6 /CS Function (Burst Length = 4, /CAS Latency = 3)

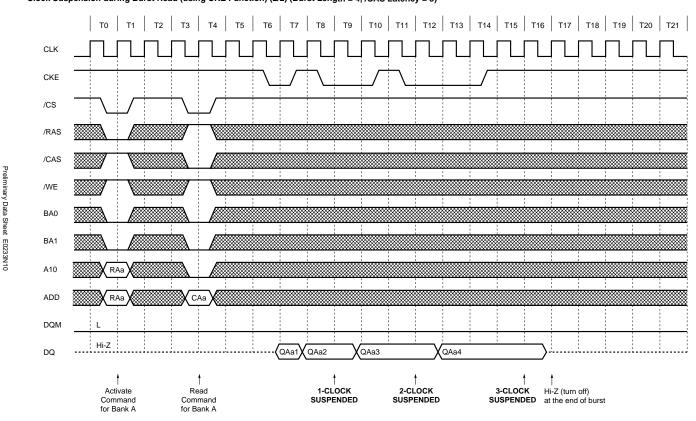
Only /CS signal needs to be issued at minimum rate

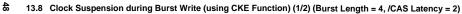


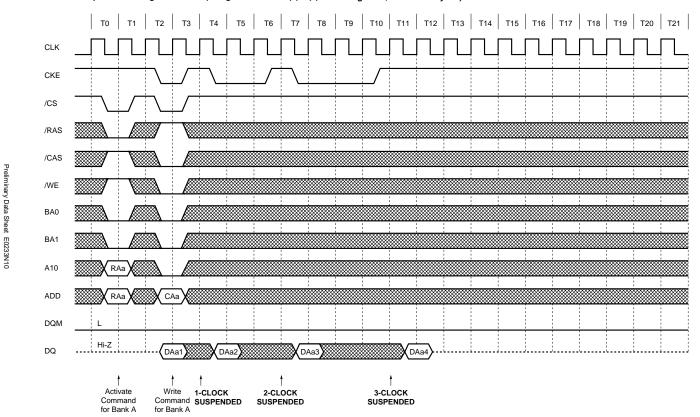




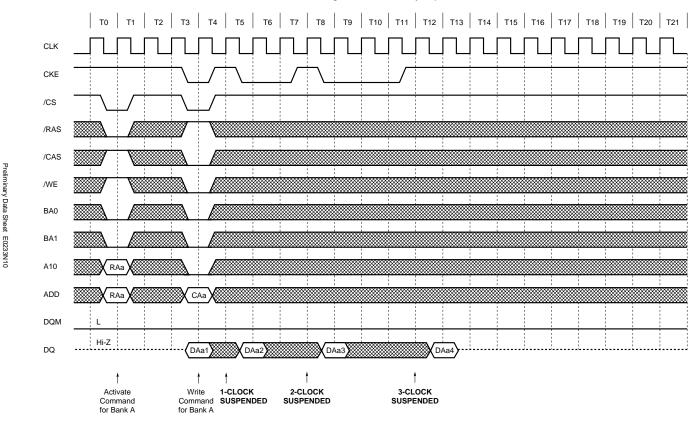




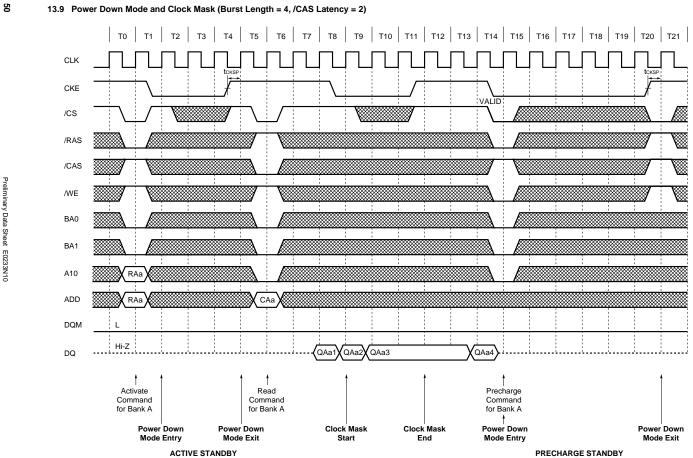


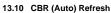


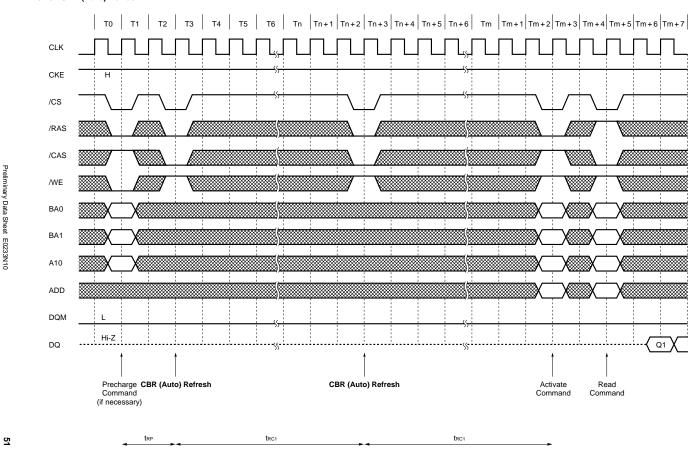


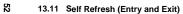


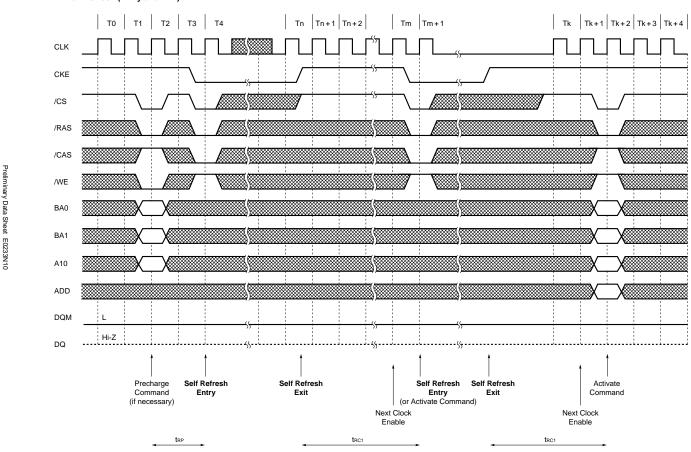




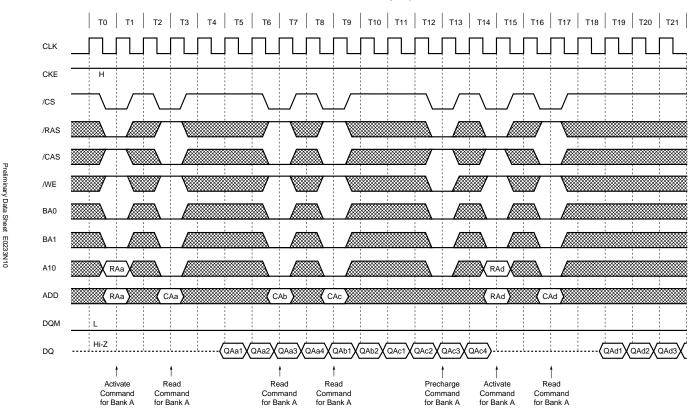




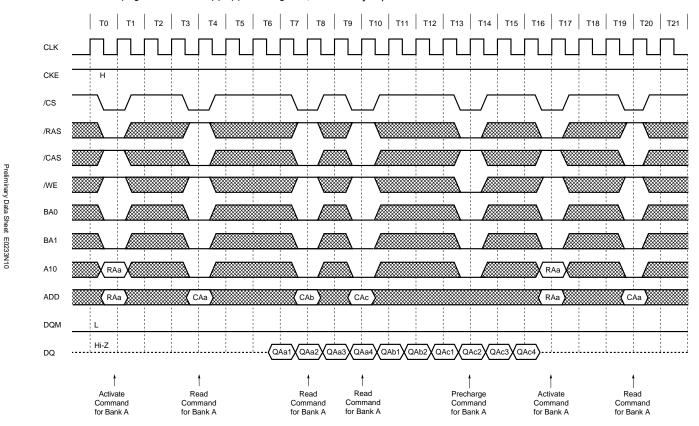




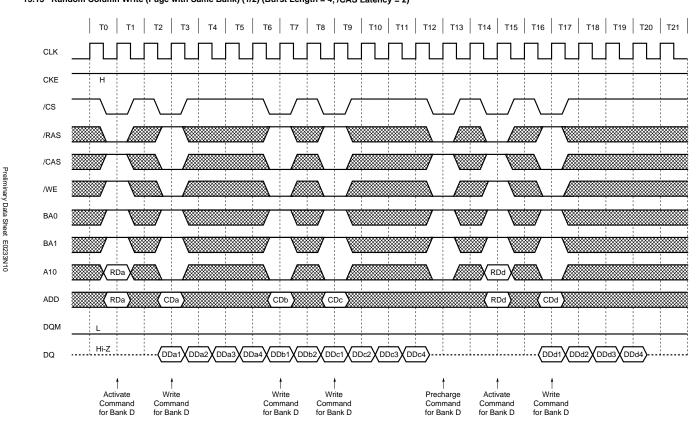




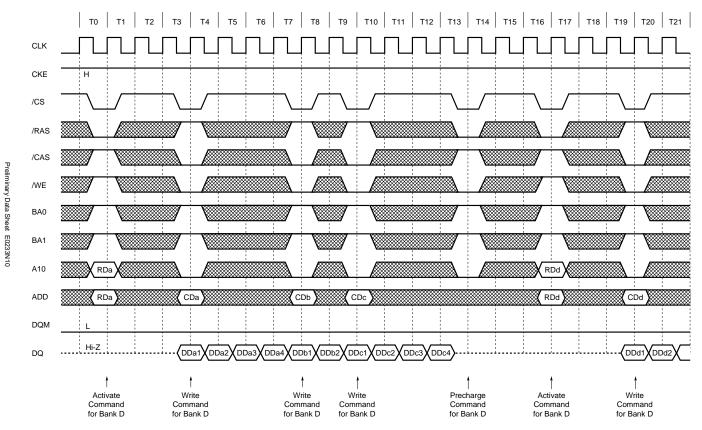




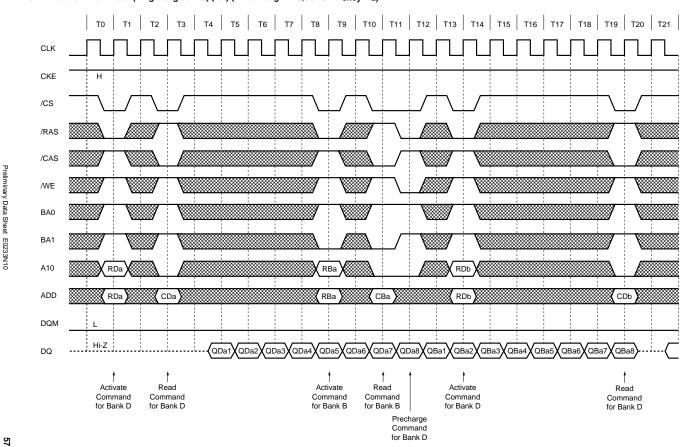
13.13 Random Column Write (Page with Same Bank) (1/2) (Burst Length = 4, /CAS Latency = 2)

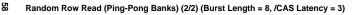


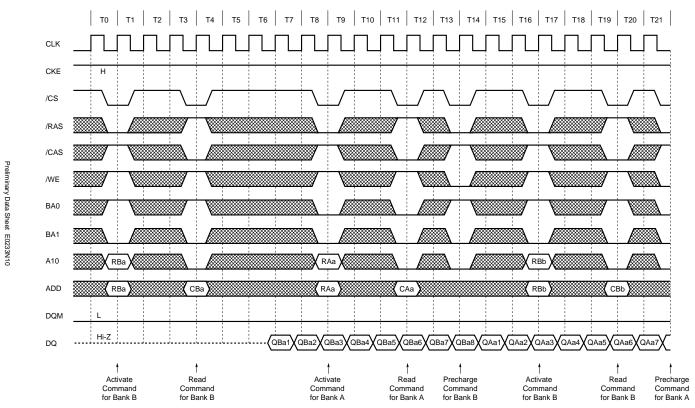




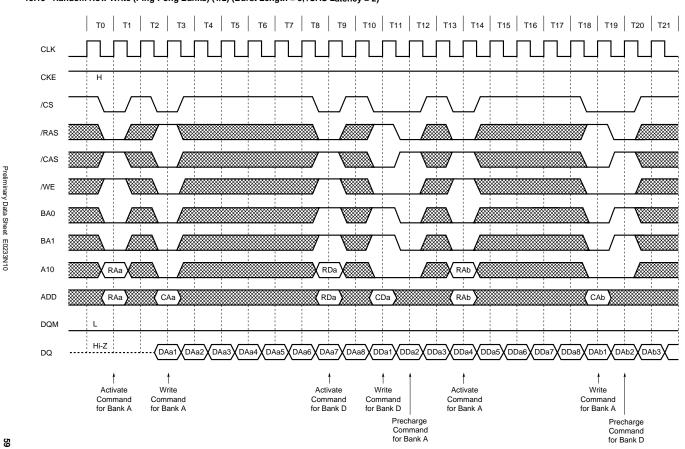
13.14 Random Row Read (Ping-Pong Banks) (1/2) (Burst Length = 8, /CAS Latency = 2)

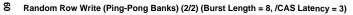


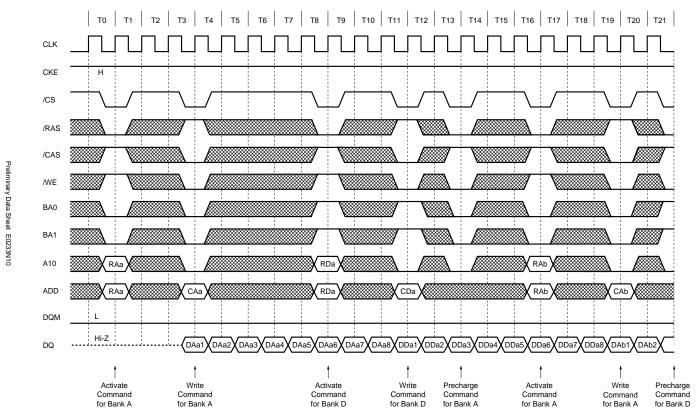




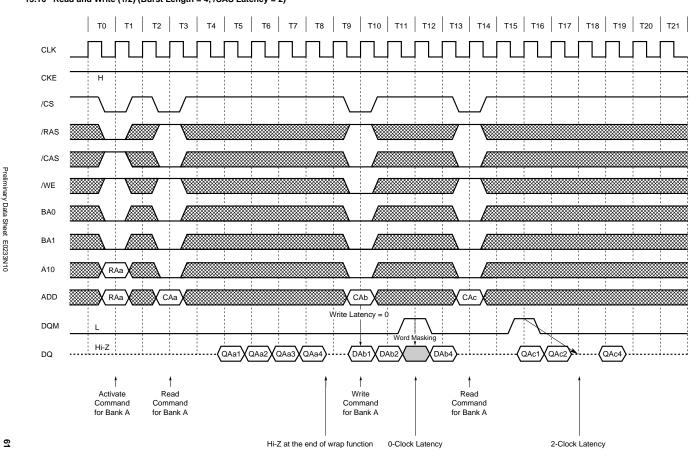


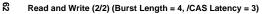


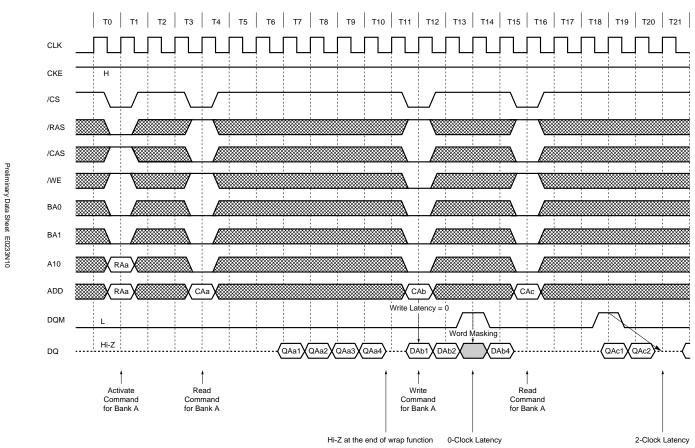


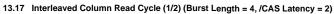


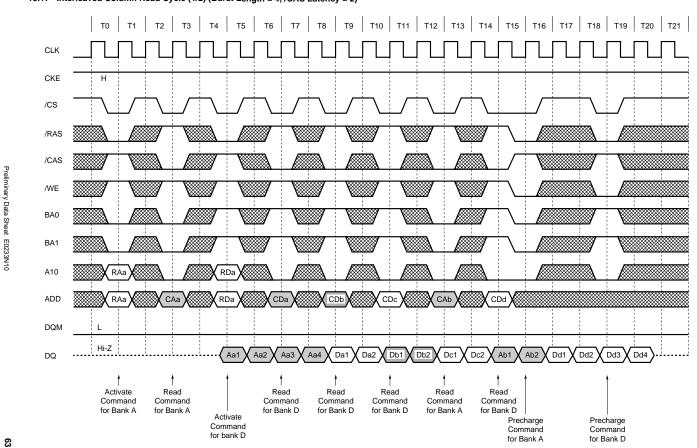


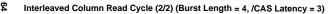


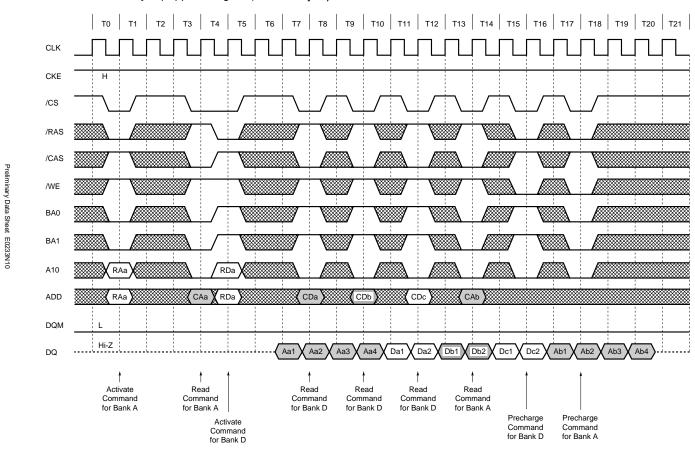


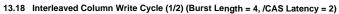


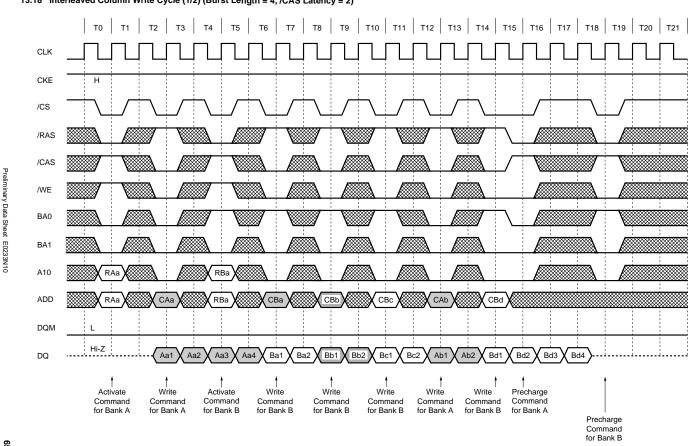


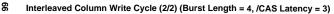


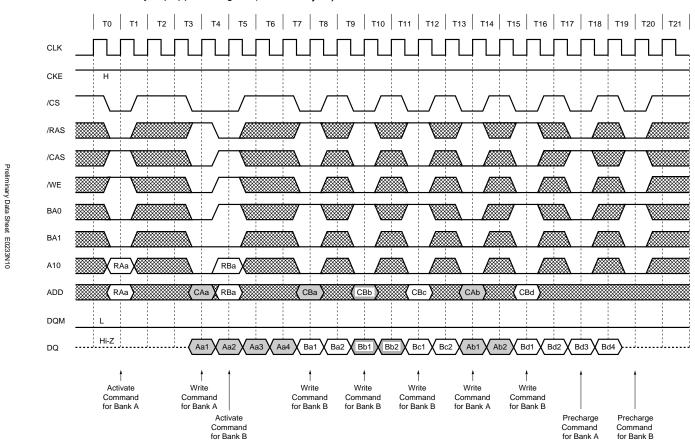




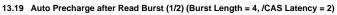


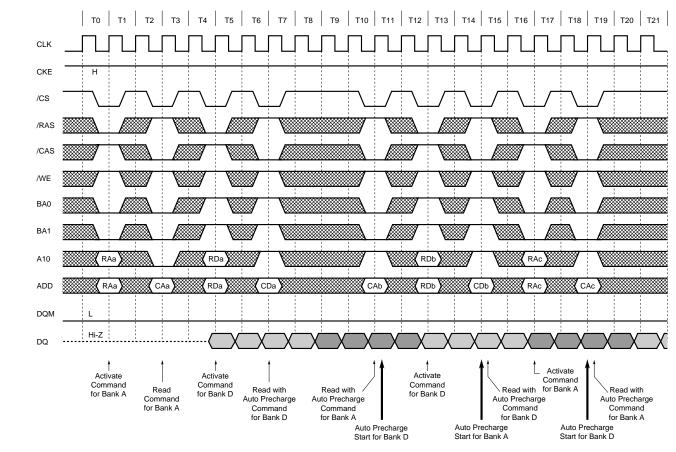


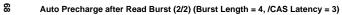


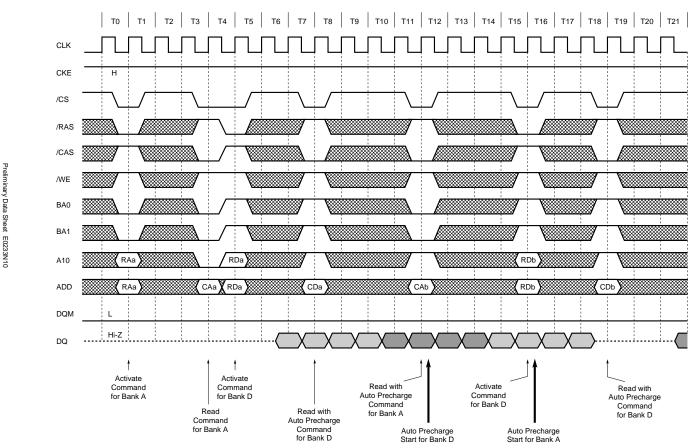


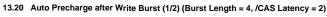


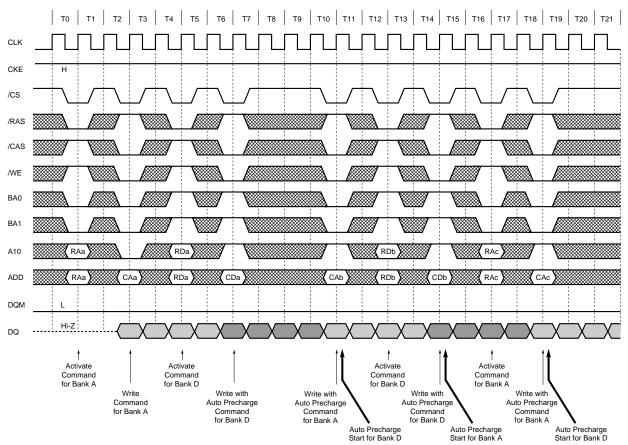


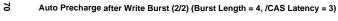


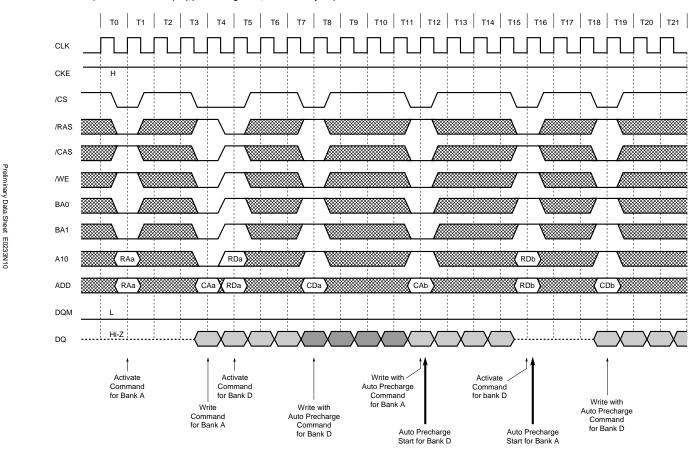




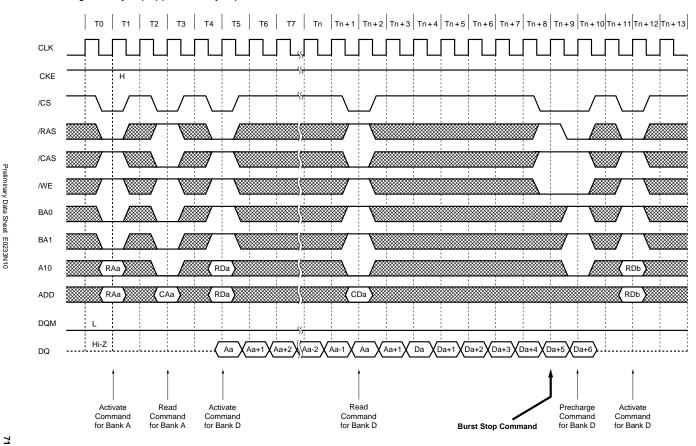




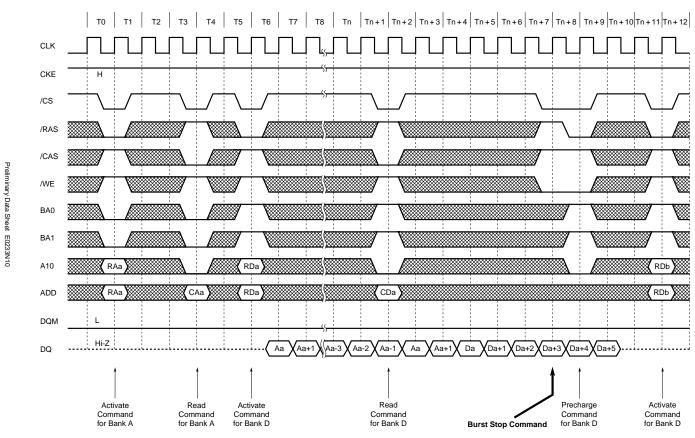




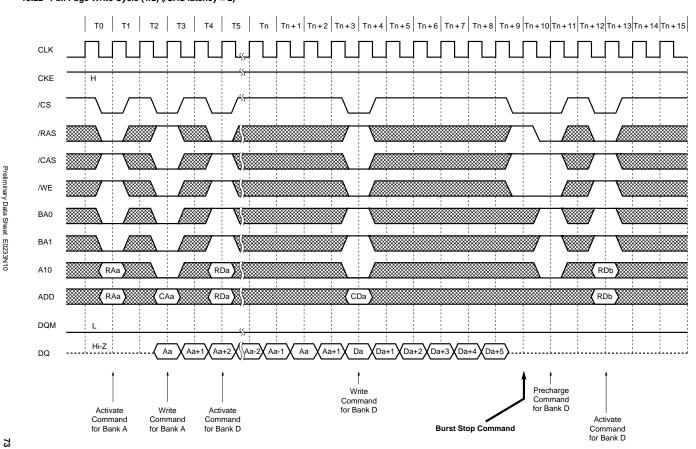
13.21 Full Page Read Cycle (1/2) (/CAS Latency = 2)

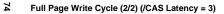


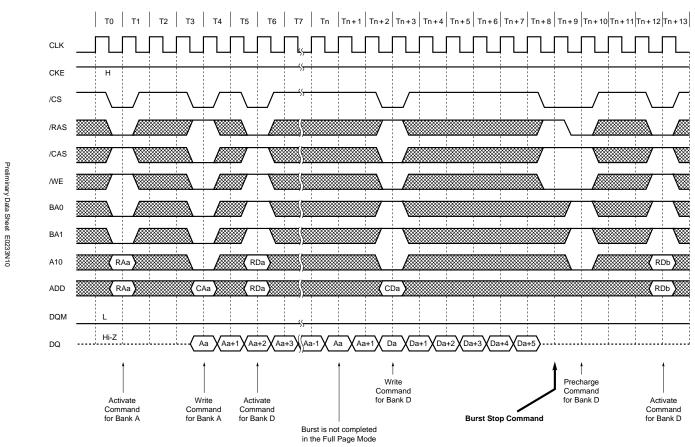
รี Full Page Read Cycle (2/2) (/CAS latency = 3)

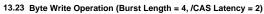


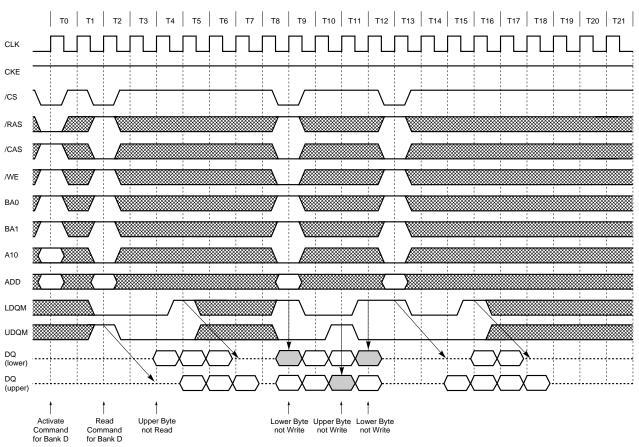
13.22 Full Page Write Cycle (1/2) (/CAS latency = 2)



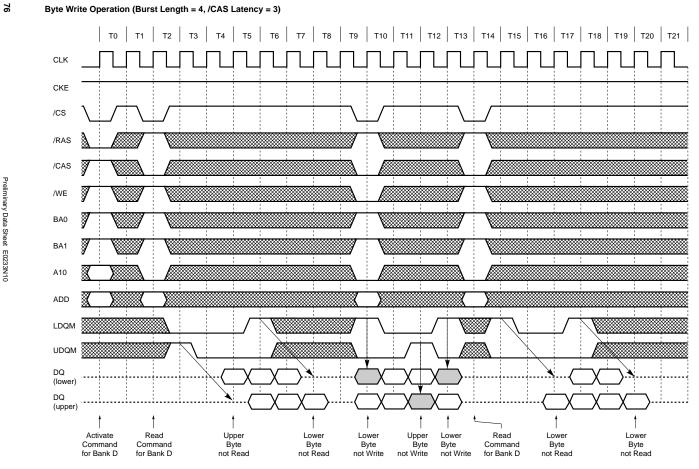




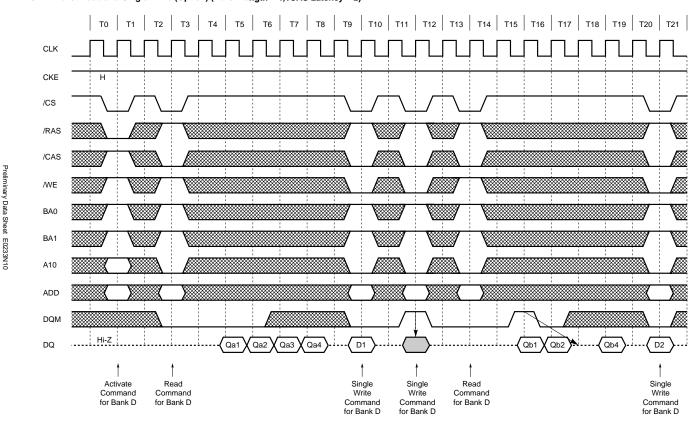




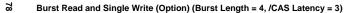


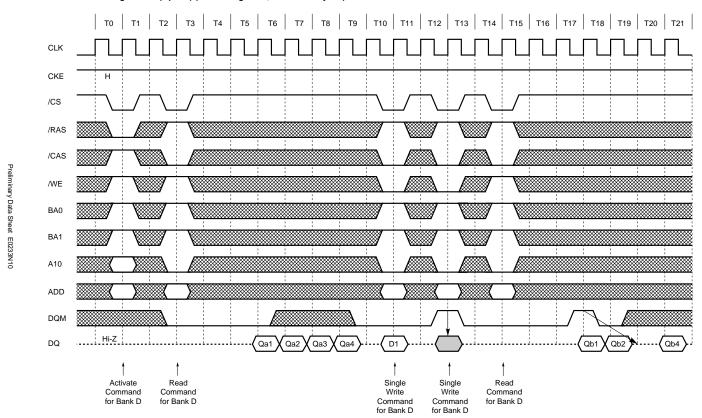


13.24 Burst Read and Single Write (Option) (Burst Length = 4, /CAS Latency = 2)



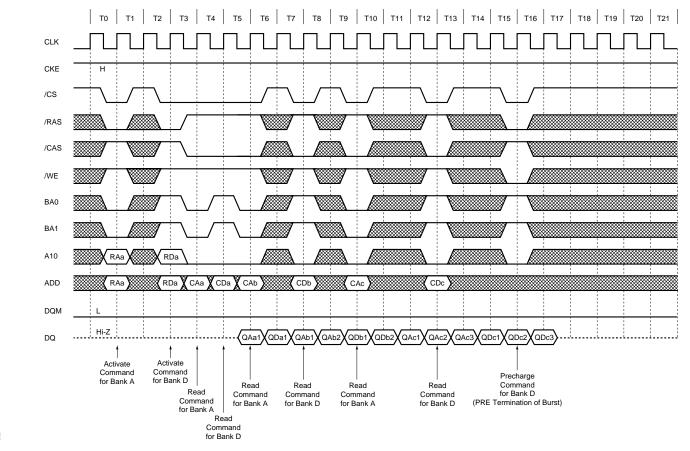
7

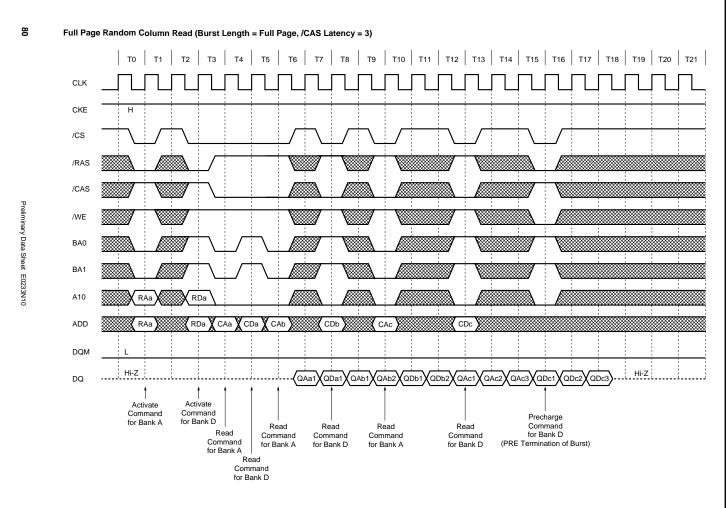




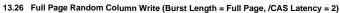


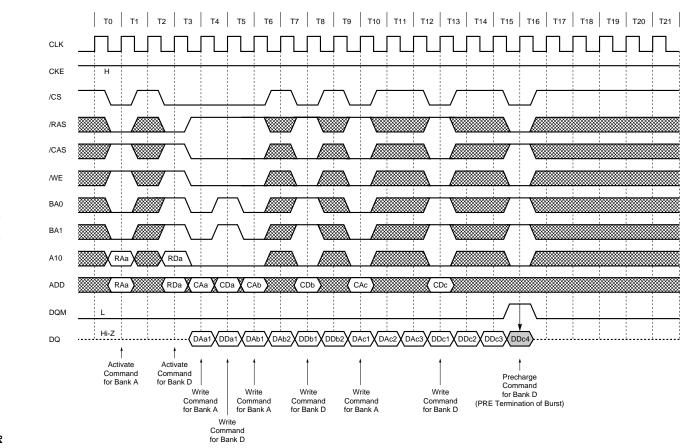


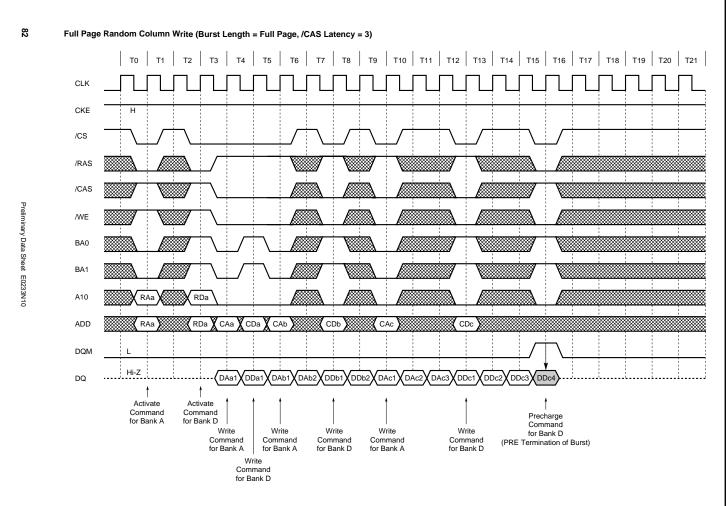




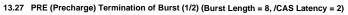
μPD45128441-I, 45128841-I, 45128163-I

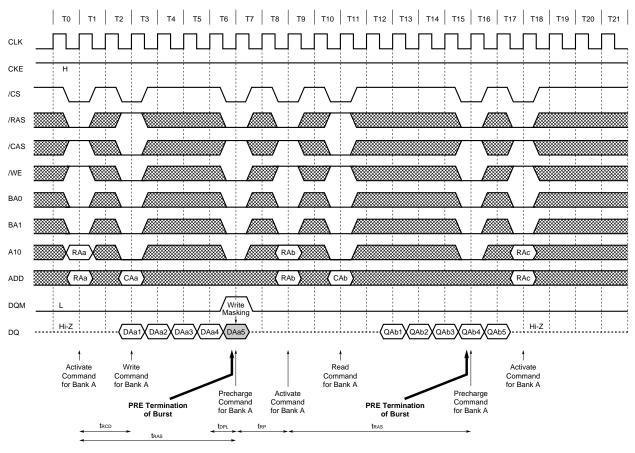




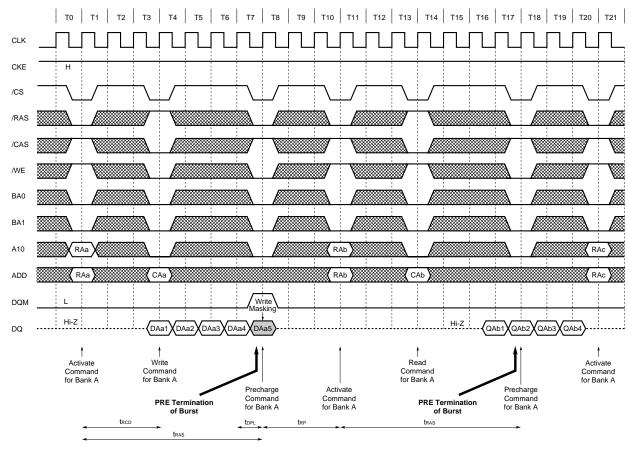


Preliminary Data Sheet E0233N10



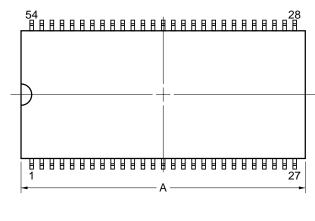




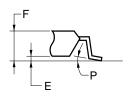


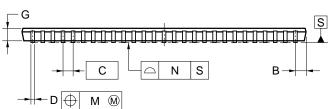
14. Package Drawing

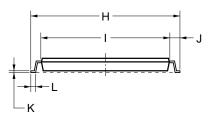
54-PIN PLASTIC TSOP (II) (10.16 mm (400))



detail of lead end







NOTES

- 1. Each lead centerline is located within 0.13 mm of its true position (T.P.) at maximum material condition.
- Dimension "A" does not include mold fiash, protrusions or gate burrs. Mold flash, protrusions or gate burrs shall not exceed 0.15 mm per side.

ITEM	MILLIMETERS
Α	22.22±0.05
В	0.91 MAX.
С	0.80 (T.P.)
D	$0.32^{+0.08}_{-0.07}$
Е	0.10±0.05
F	1.1±0.1
G	1.00
Н	11.76±0.20
I	10.16±0.10
J	0.80±0.20
K	$0.145^{+0.025}_{-0.015}$
L	0.50±0.10
М	0.13
N	0.10
Р	3°+7°

S54G5-80-9JF-2

15. Recommended Soldering Conditions

Please consult with our sales offices for soldering conditions of the μ PD45128xxx.

Type of Surface Mount Device

 μ PD45128xxxG5 : 54-pin Plastic TSOP (II) (10.16mm (400))

16. Revision History

Version /	Page		Description	
Date	This edition	Previous edition	Type of revision	Location
1.0 / Nov. 2001	_		_	

NOTES FOR CMOS DEVICES -

1 PRECAUTION AGAINST ESD FOR MOS DEVICES

Exposing the MOS devices to a strong electric field can cause destruction of the gate oxide and ultimately degrade the MOS devices operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it, when once it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. MOS devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. MOS devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor MOS devices on it.

(2) HANDLING OF UNUSED INPUT PINS FOR CMOS DEVICES

No connection for CMOS devices input pins can be a cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. The unused pins must be handled in accordance with the related specifications.

(3) STATUS BEFORE INITIALIZATION OF MOS DEVICES

Power-on does not necessarily define initial status of MOS devices. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the MOS devices with reset function have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. MOS devices are not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for MOS devices having reset function.

CME0107

The information in this document is subject to change without notice. Before using this document, confirm that this is the latest version.

No part of this document may be copied or reproduced in any form or by any means without the prior written consent of Elpida Memory, Inc.

Elpida Memory, Inc. does not assume any liability for infringement of any intellectual property rights (including but not limited to patents, copyrights, and circuit layout licenses) of Elpida Memory, Inc. or third parties by or arising from the use of the products or information listed in this document. No license, express, implied or otherwise, is granted under any patents, copyrights or other intellectual property rights of Elpida Memory, Inc. or others.

Descriptions of circuits, software and other related information in this document are provided for illustrative purposes in semiconductor product operation and application examples. The incorporation of these circuits, software and information in the design of the customer's equipment shall be done under the full responsibility of the customer. Elpida Memory, Inc. assumes no responsibility for any losses incurred by customers or third parties arising from the use of these circuits, software and information.

[Product applications]

Elpida Memory, Inc. makes every attempt to ensure that its products are of high quality and reliability. However, users are instructed to contact Elpida Memory's sales office before using the product in aerospace, aeronautics, nuclear power, combustion control, transportation, traffic, safety equipment, medical equipment for life support, or other such application in which especially high quality and reliability is demanded or where its failure or malfunction may directly threaten human life or cause risk of bodily injury.

[Product usage]

Design your application so that the product is used within the ranges and conditions guaranteed by Elpida Memory, Inc., including the maximum ratings, operating supply voltage range, heat radiation characteristics, installation conditions and other related characteristics. Elpida Memory, Inc. bears no responsibility for failure or damage when the product is used beyond the guaranteed ranges and conditions. Even within the guaranteed ranges and conditions, consider normally foreseeable failure rates or failure modes in semiconductor devices and employ systemic measures such as fail-safes, so that the equipment incorporating Elpida Memory, Inc. products does not cause bodily injury, fire or other consequential damage due to the operation of the Elpida Memory, Inc. product.

[Usage environment]

This product is not designed to be resistant to electromagnetic waves or radiation. This product must be used in a non-condensing environment.

If you export the products or technology described in this document that are controlled by the Foreign Exchange and Foreign Trade Law of Japan, you must follow the necessary procedures in accordance with the relevant laws and regulations of Japan. Also, if you export products/technology controlled by U.S. export control regulations, or another country's export control laws or regulations, you must follow the necessary procedures in accordance with such laws or regulations.

If these products/technology are sold, leased, or transferred to a third party, or a third party is granted license to use these products, that third party must be made aware that they are responsible for compliance with the relevant laws and regulations.

M01E010