

# Ultralow Noise VGAs with Preamplifier and Programmable RIN

# AD8331/AD8332

03199-B-001

#### **FEATURES**

**Ultralow noise preamplifier Voltage noise = 0.74 nV/√Hz Current noise = 2.5 pA/√Hz 3 dB bandwidth AD8331: 120 MHz AD8332: 100 MHz Low power AD8331: 125 mW/channel AD8332: 145 mW/channel Wide gain range with programmable postamp −4.5 dB to +43.5 dB 7.5 dB to 55.5 dB Low output-referred noise: 48 nV/√Hz typical Active input impedance matching Optimized for 10-bit/12-bit ADCs Selectable output clamping level Single 5 V supply operation AD8332 available in space-saving, chip scale package** 

#### **APPLICATIONS**

**Ultrasound and sonar time-gain controls High performance AGC systems I/Q signal processing High speed dual ADC drivers** 

### **GENERAL DESCRIPTION**

The AD8331/AD8332 are single- and dual-channel ultralow noise, linear-in-dB, variable gain amplifiers (VGAs) usable as low noise variable gain elements at frequencies up to 120 MHz.

Each channel consists of an ultralow noise preamplifier (LNA), an X-AMP® VGA with 48 dB of gain range, and a selectable gain postamplifier with adjustable output limiting. The LNA gain is 19 dB with a single-ended input and differential outputs. Using a single resistor, the LNA input impedance can be adjusted to match a signal source.

The 48 dB gain range of the VGAs makes these devices suitable for a variety of applications. Excellent bandwidth uniformity is maintained across the entire range. The gain control interface provides precise linear-in-dB scaling of 50 dB/V for control voltages between 40 mV and 1 V. Factory trim ensures excellent part-to-part and channel-to-channel gain matching. Differential signal paths lead to superb second- and third-order distortion performance and low crosstalk.

#### **Rev. D**

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#### **FUNCTIONAL BLOCK DIAGRAM**



Figure 1. 28-Lead TSSOP (AD8332 Shown)



Figure 2. Gain vs. Frequency Response

The VGA's low output-referred noise is advantageous in driving high speed differential ADCs. The gain of the postamplifier can be pin selected to 3.5 dB or 15.5 dB to optimize gain range and output noise for 12-bit or 10-bit converter applications. The output can be limited to a user-selected clamping level, preventing input overload to a subsequent ADC. An external resistor adjusts the clamping level.

The operating temperature range is –40°C to +85°C. The AD8331 is available in a 20-lead QSOP package, and the AD8332 is available in 28-lead TSSOP and 32-lead LFCSP packages. They require a single 5 V supply.

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### **REVISION HISTORY**









### $5/03$ —Rev. A to Rev. B



### SPECIFICATIONS

 $T_A = 25$ °C, V<sub>S</sub> = 5 V, R<sub>L</sub> = 500 Ω, R<sub>S</sub> = R<sub>IN</sub> = 50 Ω, R<sub>FB</sub> = 280 Ω, C<sub>SH</sub> = 22 pF, f = 10 MHz, R<sub>CLMP</sub> = ∞, C<sub>L</sub> = 1 pF, V<sub>CM</sub> pin floating, −4.5 dB to +43.5 dB gain (HILO = LO), and differential output voltage, unless otherwise specified.

#### **Table 1.**







<sup>1</sup> All dBm values are referred to 50 Ω, unless otherwise noted.<br><sup>2</sup> Conformance to theoretical gain expression (see Equation 1).<br><sup>3</sup> Conformance to best-fit dB linear curve.

### ABSOLUTE MAXIMUM RATINGS

#### **Table 2.**



Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

1 Four-layer JEDEC board (2S2P).

2 Exposed pad soldered to board, nine thermal vias in pad—JEDEC, 4-layer board, J-STD-51-9.

### **ESD CAUTION**

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



# PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS



Figure 3. 20-Lead QSOP Pin Configuration (AD8331)

#### **Table 3. 20-Lead QSOP Pin Function Description (AD8331)**



LMD <sub>2</sub> INH2 2	1	PIN <sub>1</sub> <b>IDENTIFIER</b>	28 27	LMD <sub>1</sub> INH <sub>1</sub>
$VPS2$ 3			26	VPS <sub>1</sub>
LON <sub>2</sub>	4		25	LON <sub>1</sub>
LOP2	5	AD8332 <b>TOP VIEW</b>	24	LOP1
COM2	6		23	COM <sub>1</sub>
VIP2 7		(Not to Scale)	22	VIP <sub>1</sub>
VIN2 8			21	VIN <sub>1</sub>
VCM2 9			20	VCM1
GAIN	10		19	HILO
<b>RCLMP</b>	l 11		18	<b>ENB</b>
VOH <sub>2</sub> 12			17	VOH <sub>1</sub>
VOL2 13			16	VOL1
<b>COMM</b>	14		15	vpsv

Figure 4. 28-Lead TSSOP Pin Configuration (AD8332)

3199-B-081







Figure 5. 32-Lead LFCSP Pin Configuration (AD8332)



32 LOP1 CH1 LNA Noninverting Output

### TYPICAL PERFORMANCE CHARACTERISTICS

 $T_A = 25^{\circ}$ C,  $V_S = 5$  V,  $R_L = 500 \Omega$ ,  $R_S = R_{IN} = 50 \Omega$ ,  $R_{FB} = 280 \Omega$ ,  $C_{SH} = 22$  pF,  $f = 10$  MHz,  $R_{CLMP} = \infty$ ,  $C_L = 1$  pF,  $V_{CM} = 2.5$  V,  $-4.5$  dB to +43.5 dB gain (HILO = LO), and differential signal voltage, unless otherwise specified.



Figure 6. Gain vs. V<sub>GAIN</sub> and MODE (MODE Available on AC Package)



Figure 7. Absolute Gain Error vs. V<sub>GAIN</sub> at Three Temperatures



Figure 8. Absolute Gain Error vs. V<sub>GAIN</sub> at Various Frequencies



Figure 9. Gain Error Histogram



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Figure 47. LNA Overdrive Recovery, VINH 0.05 V p-p to 1 V p-p Burst, VGAIN = 0.27 V, VGA Output Shown



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# TEST CIRCUITS



Figure 54. Gain and Bandwidth Measurements



Figure 55. Transient Measurements



Figure 56. Used for Noise Measurements



Figure 58. S11 Measurements

### THEORY OF OPERATION

### **OVERVIEW**

The following discussion applies to all part numbers. Figure 59 and Figure 1 are functional block diagrams of the AD8331 and AD8332, respectively.



Each channel contains an LNA that provides user-adjustable input impedance termination, a differential X-AMP VGA, and a programmable gain postamplifier with adjustable output voltage limiting. Figure 60 shows a simplified block diagram.



Figure 60. Simplified Block Diagram

The linear-in-dB gain control interface is trimmed for slope and absolute accuracy. The overall gain range is 48 dB, extending from −4.5 dB to +43.5 dB or from +7.5 dB to +55.5 dB, depending on the setting of the HILO pin. The slope of the gain control interface is 50 dB/V, and the gain control range is 40 mV to 1 V, leading to the following expressions for gain:

$$
GAIN (dB) = 50 (dB/V) \times V_{GAN} - 6.5 dB, (HILO = LO)
$$
 (1)

$$
\overline{\text{or}}
$$

$$
GAIN (dB) = 50 (dB/V) \times V_{GAIN} + 5.5 dB, (HILO = LO)
$$
 (2)

The gain characteristics are shown in Figure 61.



Figure 61. Gain Control Characteristics

When MODE is set high (where available):

$$
GAIN (dB) = -50 (dB/V) \times V_{GAIN} + 45.5 dB, (HILO = LO)
$$
 (3)

or

$$
GAIN (dB) = -50 (dB/V) \times V_{GAIN} + 57.5 dB, (H ILO = HI)
$$
 (4)

The LNA converts a single-ended input to a differential output with a voltage gain of 19 dB. When only one output is used, the gain is 13 dB. The inverting output is used for active input impedance termination. Each of the LNA outputs is capacitively coupled to a VGA input. The VGA consists of an attenuator with a range of 48 dB followed by an amplifier with 21 dB of gain, for a net gain range of −27 dB to +21 dB. The X-AMP gain-interpolation technique results in low gain error and uniform bandwidth, and differential signal paths minimize distortion.

The final stage is a logic-programmable amplifier with gains of 3.5 dB or 15.5 dB. The LO and HI gain modes are optimized for 12-bit and 10-bit ADC applications, in terms of output-referred noise and absolute gain range. Output voltage limiting can be programmed by the user.

### **LOW NOISE AMPLIFIER (LNA)**

Good noise performance relies on a proprietary ultralow noise preamplifier at the beginning of the signal chain, which minimizes the noise contribution in the following VGA. Active impedance control optimizes noise performance for applications that benefit from input matching.

A simplified schematic of the LNA is shown in Figure 62. INH is capacitively coupled to the source. An on-chip bias generator centers the output dc levels at 2.5 V and the input voltages at 3.25 V. A capacitor  $C_{\text{LMD}}$  of the same value as the input coupling capacitor C<sub>INH</sub> is connected from the LMD pin to ground.



Figure 62. Simplified LNA Schematic

The LNA supports differential output voltages as high as 5 V p-p with positive and negative excursions of  $\pm$ 1.25 V, about a common-mode voltage of 2.5 V. Because the differential gain magnitude is 9, the maximum input signal before saturation is ±275 mV or 550 mV p-p. Overload protection ensures a quick recovery time from large input voltages. Because the inputs are capacitively coupled to a bias voltage near midsupply, very large inputs can be handled without interacting with the ESD protection.

Low value feedback resistors and the current-driving capability of the output stage allow the LNA to achieve a low inputreferred voltage noise of 0.74 nV/ $\sqrt{Hz}$ . This is achieved with a modest current consumption of 10 mA per channel (50 mW). On-chip resistor matching results in precise gains of 4.5 per side (9 differential), critical for accurate impedance control. The use of a fully differential topology and negative feedback minimizes distortion. Low HD2 is particularly important in second harmonic ultrasound imaging applications. Differential signaling enables smaller swings at each output, further reducing third-order distortion.

#### **Active Impedance Matching**

The LNA supports active impedance matching through an external shunt feedback resistor from Pin LON to Pin INH. The input resistance  $R_{IN}$  is given by Equation 5, where A is the single-ended gain of 4.5, and 6 k $\Omega$  is the unterminated input impedance.

$$
R_{IN} = \frac{R_{FB}}{1 + A} \parallel 6 \text{ k}\Omega = \frac{6 \text{ k}\Omega \times R_{FB}}{33 \text{ k}\Omega + R_{FB}}
$$
(5)

C<sub>FB</sub> is needed in series with R<sub>FB</sub>, because the dc levels at Pin LON and Pin INH are unequal. Expressions for choosing R<sub>FB</sub> in terms of  $R_{IN}$  and for choosing  $C_{FB}$  are found in the Applications section. C<sub>SH</sub> and the ferrite bead enhance stability at higher frequencies where the loop gain declines and prevents peaking. Frequency response plots of the LNA are shown in Figure 22 and Figure 23. The bandwidth is approximately 130 MHz for matched input impedances of 50  $\Omega$  to 200  $\Omega$  and declines at higher source impedances. The unterminated bandwidth  $(R_{FB} = \infty)$  is approximately 80 MHz.

Each output can drive external loads as low as 100  $\Omega$  in addition to the 100  $\Omega$  input impedance of the VGA (200  $\Omega$  differential). Capacitive loading up to 10 pF is permissible. All loads should be ac-coupled. Typically, Pin LOP output is used as a singleended driver for auxiliary circuits, such as those used for Doppler mode ultrasound imaging, and Pin LON drives RFB. Alternatively, a differential external circuit can be driven from the two outputs, in addition to the active feedback termination. In both cases, important stability considerations discussed in the Applications section should be carefully observed.

The impedance at each LNA output is 5  $\Omega$ . A 0.4 dB reduction in open-circuit gain results when driving the VGA, and 0.8 dB with an additional 100  $\Omega$  load at the output. The differential gain of the LNA is 6 dB higher. If the load is less than 200  $\Omega$  on either side, a compensating load is recommended on the opposite output.

#### **LNA Noise**

The input-referred voltage noise sets an important limit on system performance. The short-circuit input voltage noise of the LNA is 0.74 nV/ $\sqrt{\text{Hz}}$  or 0.82 nV/ $\sqrt{\text{Hz}}$  (at maximum gain), including the VGA noise. The open-circuit current noise is 2.5 pA/ $\sqrt{Hz}$ . These measurements, taken without a feedback resistor, provide the basis for calculating the input noise and noise figure performance of the configurations in Figure 63. Figure 64 and Figure 65 are simulations extracted from these results, and the 4.1 dB NF measurement with the input actively matched to a 50  $\Omega$  source. Unterminated (R<sub>FB</sub> =  $\infty$ ) operation exhibits the lowest equivalent input noise and noise figure. Figure 64 shows the noise figure vs. source resistance, rising at low R<sub>s</sub>, where the LNA voltage noise is large compared to the source noise, and again at high R<sub>s</sub> due to current noise. The VGA's input-referred voltage noise of 2.7 nV/√Hz is included in all of the curves.





**RESISTIVE TERMINATION**



**ACTIVE IMPEDANCE MATCH –RS = RIN**  $R_{IN}$ 



Figure 63. Input Configurations



Figure 64. Noise Figure vs.  $R<sub>S</sub>$  for Resistive, Active Matched, and Unterminated Inputs



Figure 65. Noise Figure vs.  $R_S$  for Various Fixed Values of  $R_{IN}$ , Actively Matched

The primary purpose of input impedance matching is to improve the system transient response. With resistive termination, the input noise increases due to the thermal noise of the matching resistor and the increased contribution of the LNA's input voltage noise generator. With active impedance matching, however, the contributions of both are smaller than they would be for resistive termination by a factor of  $1/(1 + LNA \text{ Gain})$ . Figure 64 shows their relative noise figure (NF) performance. In this graph, the input impedance was swept with  $R<sub>s</sub>$  to preserve the match at each point. The noise figures for a source impedance of 50 Ω are 7.1 dB, 4.1 dB, and 2.5 dB, respectively, for the resistive, active, and unterminated configurations. The noise figures for 200  $Ω$  are 4.6 dB, 2.0 dB, and 1.0 dB, respectively.

Figure 65 is a plot of the NF vs.  $R_s$  for various values of  $R_{\text{IN}}$ , which is helpful for design purposes. The plateau in the NF for actively matched inputs mitigates source impedance variations. For comparison purposes, a preamp with a gain of 19 dB and noise spectral density of 1.0 nV/√Hz, combined with a VGA with 3.75 nV/√Hz, would yield a noise figure degradation of approximately 1.5 dB (for most input impedances), significantly worse than the AD8332 performance.

The equivalent input noise of the LNA is the same for singleended and differential output applications. The LNA noise figure improves to 3.5 dB at 50  $\Omega$  without VGA noise, but this is exclusive of noise contributions from other external circuits connected to LOP. A series output resistor is usually recommended for stability purposes, when driving external circuits on a separate board (see the Applications section). In low noise applications, a ferrite bead is even more desirable.

### **VARIABLE GAIN AMPLIFIER**

The differential X-AMP VGA provides precise input attenuation and interpolation. It has a low input-referred noise of 2.7  $\text{nV}/\sqrt{\text{Hz}}$ and excellent gain linearity. A simplified block diagram is shown in Figure 66.



Figure 66. Simplified VGA Schematic

### **X-AMP VGA**

The input of the VGA is a differential R-2R ladder attenuator network, with 6 dB steps per stage and a net input impedance of 200 Ω differential. The ladder is driven by a fully differential input signal from the LNA and is not intended for single-ended operation. LNA outputs are ac-coupled to reduce offset and isolate their common-mode voltage. The VGA inputs are biased through the ladder's center tap connection to VCM, which is typically set to 2.5 V and is bypassed externally to provide a clean ac ground.

The signal level at successive stages in the input attenuator falls from 0 dB to −48 dB, in 6 dB steps. The input stages of the X-AMP are distributed along the ladder, and a biasing interpolator, controlled by the gain interface, determines the input tap point. With overlapping bias currents, signals from successive taps merge to provide a smooth attenuation range from 0 dB to −48 dB. This circuit technique results in excellent, linear-in-dB gain law conformance and low distortion levels and deviates ±0.2 dB or less from ideal. The gain slope is monotonic with respect to the control voltage and is stable with variations in process, temperature, and supply.

The X-AMP inputs are part of a gain-of-12 feedback amplifier, which completes the VGA. Its bandwidth is 150 MHz. The input stage is designed to reduce feedthrough to the output and ensure excellent frequency response uniformity across gain setting (see Figure 11 and Figure 12).

### **Gain Control**

Position along the VGA attenuator is controlled by a singleended analog control voltage,  $V_{\text{GAN}}$ , with an input range of 40 mV to 1.0 V. The gain control scaling is trimmed to a slope of 50 dB/V (20 mV/dB). Values of  $V_{\rm GAIN}$  beyond the control range saturate to minimum or maximum gain values. Both channels of the AD8332 are controlled from a single gain interface to preserve matching. Gain can be calculated using Equation 1 and Equation 2.

Gain accuracy is very good because both the scaling factor and absolute gain are factory trimmed. The overall accuracy relative to the theoretical gain expression is  $\pm 1$  dB for variations in temperature, process, supply voltage, interpolator gain ripple, trim errors, and tester limits. The gain error relative to a best-fit line for a given set of conditions is typically ±0.2 dB. Gain matching between channels is better than 0.1 dB (see Figure 10, which shows gain errors in the center of the control range). When  $V_{\text{GAN}}$  < 0.1 or > 0.95, gain errors are slightly greater.

The gain slope can be inverted, as shown in Figure 61 (available in most versions). The gain drops with a slope of –50 dB/V across the gain control range from maximum to minimum gain. This slope is useful in applications, such as automatic gain control, where the control voltage is proportional to the

measured output signal amplitude. The inverse gain mode is selected by setting the MODE pin HI.

Gain control response time is less than 750 ns to settle within 10% of the final value for a change from minimum to maximum gain.

### **VGA Noise**

In a typical application, a VGA compresses a wide dynamic range input signal to within the input span of an ADC. While the input-referred noise of the LNA limits the minimum resolvable input signal, the output-referred noise, which depends primarily on the VGA, limits the maximum instantaneous dynamic range that can be processed at any one particular gain control voltage. This limit is set in accordance with the quantization noise floor of the ADC.

Output- and input-referred noise as a function of VGAIN are plotted in Figure 24 and Figure 26 for the short-circuited input condition. The input noise voltage is simply equal to the output noise divided by the measured gain at each point in the control range.

The output-referred noise is flat over most of the gain range, because it is dominated by the fixed output-referred noise of the VGA. Values are 48 nV/√Hz in LO gain mode and 178 nV/√Hz in HI gain mode. At the high end of the gain control range, the noise of the LNA and source prevail. The input-referred noise reaches its minimum value near the maximum gain control voltage, where the input-referred contribution of the VGA becomes very small.

At lower gains, the input-referred noise, and thus noise figure, increases as the gain decreases. The instantaneous dynamic range of the system is not lost, however, because the input capacity increases with it. The contribution of the ADC noise floor has the same dependence as well. The important relationship is the magnitude of the VGA output noise floor relative to that of the ADC.

With its low output-referred noise levels, these devices ideally drive low voltage ADCs. The converter noise floor drops 12 dB for every 2 bits of resolution and drops at lower input full-scale voltages and higher sampling rates. ADC quantization noise is discussed in the Applications section.

The preceding noise performance discussion applies to a differential VGA output signal. Although the LNA noise performance is the same in single-ended and differential applications, the VGA performance is not. The noise of the VGA is significantly higher in single-ended usage, because the contribution of its bias noise is designed to cancel in the differential signal. A transformer can be used with single-ended applications when low noise is desired.

Gain control noise is a concern in very low noise applications. Thermal noise in the gain control interface can modulate the channel gain. The resultant noise is proportional to the output signal level and usually only evident when a large signal is present. Its effect is observable only in LO gain mode, where the noise floor is substantially lower. The gain interface includes an on-chip noise filter, which reduces this effect significantly at frequencies above 5 MHz. Care should be taken to minimize noise impinging at the GAIN input. An external RC filter can be used to remove V<sub>GAIN</sub> source noise. The filter bandwidth should be sufficient to accommodate the desired control bandwidth.

#### **Common-Mode Biasing**

An internal bias network connected to a midsupply voltage establishes common-mode voltages in the VGA and postamp. An externally bypassed buffer maintains the voltage. The bypass capacitors form an important ac ground connection, because the VCM network makes a number of important connections internally, including the center tap of the VGA's differential input attenuator, the feedback network of the VGA's fixed gain amplifier, and the feedback network of the postamplifier in both gain settings. For best results, use a 1 nF and a 0.1 µF capacitor in parallel, with the 1 nF nearest to Pin VCM. Separate VCM pins are provided for each channel. For dc-coupling to a 3 V ADC, the output common-mode voltage is adjusted to 1.5 V by biasing the VCM pin.

### **POSTAMPLIFIER**

The final stage has a selectable gain of 3.5 dB or 15.5 dB, set by the logic pin, HILO. These correspond to linear gains of 1.5 or 6. A simplified block diagram of the postamplifier is shown in Figure 67.

Separate feedback attenuators implement the two gain settings. These are selected in conjunction with an appropriately scaled input stage to maintain a constant 3 dB bandwidth between the two gain modes ( $\sim$ 150 MHz). The slew rate is 1200 V/ $\mu$ s in HI gain mode and 300 V/µs in LO gain mode. The feedback networks for HI and LO gain modes are factory trimmed to adjust the absolute gains of each channel.

#### **Noise**

The topology of the postamplifier provides constant inputreferred noise with the two gain settings and variable outputreferred noise. The output-referred noise in HI gain mode increases (with gain) by four. This setting is recommended when driving converters with higher noise floors. The extra gain boosts the output signal levels and noise floor appropriately. When driving circuits with lower input noise floors, the LO gain mode optimizes the output dynamic range.



Figure 67. Postamplifier Block Diagram

Although the quantization noise floor of an ADC depends on a number of factors, the 48 nV/ $\sqrt{Hz}$  and 178 nV/ $\sqrt{Hz}$  levels are well suited to the average requirements of most 12-bit and 10 bit converters, respectively. An additional technique, described in the Applications section, can extend the noise floor even lower for possible use with 14-bit ADCs.

#### **Output Clamping**

Outputs are internally limited to a level of 4.5 V p-p differential when operating at a 2.5 V common-mode voltage. The postamp implements an optional output clamp engaged through a resistor from the RCLMP pin to ground. Table 7 shows a list of recommended resistor values.

Output clamping can be used for ADC input overload protection, if needed, or postamp overload protection when operating from a lower common-mode level, such as 1.5 V. The user should be aware that distortion products increase as output levels approach the clamping levels and should adjust the clamp resistor accordingly. Also, see the Applications section.

The accuracy of the clamping levels is approximately  $\pm 5\%$  in LO or HI mode. Figure 68 illustrates the output characteristics for a few values of  $R<sub>CLMP</sub>$ .



Figure 68. Output Clamping Characteristics

### APPLICATIONS

### **LNA—EXTERNAL COMPONENTS**

The LMD pin (connected to the bias circuitry) must be bypassed to ground and signal sourced to the INH pin capacitively coupled using 2.2 nF to 0.1 µF capacitors (see Figure 69).

The unterminated input impedance of the LNA is 6 k $\Omega$ . The user can synthesize any LNA input resistance between 50  $\Omega$  and 6 kΩ. RFB is calculated according to Equation 6 or selected from Table 6.

$$
R_{FB} = \frac{33 \text{ k}\Omega \times (R_{IN})}{6 \text{ k}\Omega - (R_{IN})}
$$
\n
$$
\tag{6}
$$

**Table 6. LNA External Component Values for Common Source Impedances**

$R_{IN}(\Omega)$	$R_{FB}$ (Nearest STD 1% Value, $\Omega$ )	$C_{SH}$ (pF)
50	280	22
75	412	12
100	562	8
200	1.13k	1.2
500	3.01 <sub>k</sub>	None
6k	$\infty$	None

When active input termination is used, a 0.1  $\mu$ F capacitor (C<sub>FB</sub>) is required to isolate the input and output bias voltages of the LNA.

The shunt input capacitor, C<sub>SH</sub>, reduces gain peaking at higher frequencies where the active termination match is lost due to the HF gain roll-off of the LNA. Suggested values are shown in Table 6; for unterminated applications, reduce the capacitor value by half.

When a long trace to Pin INH is unavoidable, or if both LNA outputs drive external circuits, a small ferrite bead (FB) in series with Pin INH preserves circuit stability with negligible effect on noise. The bead shown is 75  $Ω$  at 100 MHz (Murata BLM21 or equivalent). Other values can prove useful.

Figure 70 shows the interconnection details of the LNA output. Capacitive coupling between the LNA outputs and the VGA inputs is required because of the differences in their dc levels and the need to eliminate the offset of the LNA. Capacitor values of 0.1 µF are recommended. There is 0.4 dB loss in gain between the LNA output and the VGA input due to the 5  $\Omega$ output resistance. Additional loading at the LOP and LON outputs affects LNA gain.



Figure 69. Basic Connections for a Typical Channel (AD8332 Shown)



Figure 70. Interconnections of the LNA and VGA

Both LNA outputs are available for driving external circuits. Pin LOP should be used in those instances when a singleended LNA output is required. The user should be aware of stray capacitance loading of the LNA outputs, in particular LON. The LNA can drive 100  $\Omega$  in parallel with 10 pF. If an LNA output is routed to a remote PC board, it tolerates a load capacitance up to 100 pF with the addition of a 49.9  $\Omega$  series resistor or ferrite 75  $Ω/100$  MHz bead.

#### **Gain Input**

The GAIN pin is common to both channels of the AD8332. The input impedance is nominally 10 MΩ and a bypass capacitor from 100 pF to1 nF is recommended.

Parallel-connected devices can be driven by a common voltage source or DAC. Decoupling should take into account any bandwidth considerations of the drive waveform, using the total distributed capacitance.

If gain control noise in LO gain mode becomes a factor, maintaining  $\leq$ 15 nV/ $\sqrt{Hz}$  noise at the GAIN pin ensures satisfactory noise performance. Internal noise prevails below  $15 \text{ nV}/\sqrt{\text{Hz}}$  at the GAIN pin. Gain control noise is negligible in HI gain mode.

#### **VCM Input**

The common-mode voltage of Pin VCM, Pin VOL, and Pin VOH defaults to 2.5 V dc. With output ac-coupled applications, the VCM pin is unterminated; however, it must still be bypassed in close proximity for ac grounding of internal circuitry. The VGA outputs can be dc connected to a differential load, such as an ADC. Common-mode output voltage levels between 1.5 V and 3.5 V can be realized at Pin VOH and Pin VOL by applying the desired voltage at Pin VCM. DC-coupled operation is not recommended when driving loads on a separate PC board.

The voltage on the VCM pin is sourced by an internal buffer with an output impedance of 30  $\Omega$  and a  $\pm 2$  mA default output current (see Figure 71). If the VCM pin is driven from an external source, its output impedance should be <<30  $\Omega$  and its current drive capability should be >>2 mA. If the VCM pins of several devices are connected in parallel, the external buffer should be capable of overcoming their collective output currents. When a common-mode voltage other than 2.5 V is used, a voltage-limiting resistor, RCLMP, is needed to protect against overload.



Figure 71. VCM Interface

#### **Logic Inputs—ENB, MODE, and HILO**

The input impedance of the enable pins is nominally 25 k $\Omega$  and can be pulled up to 5 V (a pull-up resistor is recommended) or driven by any 3 V or 5 V logic families. The enable pins perform a power-down function, when disabled, the VGA outputs are near ground. Multiple devices can be driven from a common source. See Table 3, Table 4, and Table 5 for circuit functions controlled by the enable pins.

Pin HILO is compatible with 3 V or 5 V CMOS logic families. It is either connected to ground or pulled up to 5 V, depending on the desired gain range and output noise.

#### **Optional Output Voltage Limiting**

The RCLMP pin provides the user with a means to limit the output voltage swing when used with loads that have no provisions for prevention of input overdrive. The peak-to-peak limited voltage is adjusted by a resistor to ground, and Table 7 lists several voltage levels and the corresponding resistor value. Unconnected, the default limiting level is 4.5 V p-p.

Note that third harmonic distortion increases as waveform amplitudes approach clipping. For lowest distortion, the clamp level should be set higher than the converter input span. A clamp level of 1.5 V p-p is recommended for a 1 V p-p linear output range, 2.7 V p-p for a 2 V p-p range, or 1 V p-p for a 0.5 V p-p operation. The best solution is determined experimentally. Figure 72 shows third harmonic distortion as a function of the limiting level for a 2 V p-p output signal. A wider limiting level is desirable in HI gain mode.



Figure 72. HD3 vs. Clamping Level for 2 V p-p Differential Input

#### **Table 7. Clamp Resistor Values**



#### **Output Filtering and Series Resistor Requirements**

To ensure stability at the high end of the gain control range, series resistors or ferrite beads are recommended for the outputs when driving large capacitive loads or circuits on other boards. These components can be part of the external noise filter.

Recommended resistor values are 84.5  $\Omega$  for LO gain mode and 100 Ω for HI gain mode (see Figure 69) and are placed near the VOH and VOL pins. Lower value resistors are permissible for applications with nearby loads or with gains less than 40 dB. Lower values are best selected empirically.

An antialiasing noise filter is typically used with an ADC. Filter requirements are application dependent.

When the ADC resides on a separate board, the majority of filter components should be placed nearby to suppress noise picked up between boards and to mitigate charge kickback from the ADC inputs. Any series resistance beyond that required for output stability should be placed on the ADC board. Figure 73 shows a second-order, low-pass filter with a bandwidth of 20 MHz. The capacitor is chosen in conjunction with the 10 pF input capacitance of the ADC.



### **DRIVING ADCS**

The output drive accommodates a wide range of ADCs. The noise floor requirements of the VGA depend on a number of application factors, including bit resolution, sampling rate, fullscale voltage, and the bandwidth of the noise/antialias filter. The output noise floor and gain range can be adjusted by selecting HI or LO gain mode.

The relative noise and distortion performance of the two gain modes can be compared in Figure 24 and Figure 30 through Figure 40. The 48 nV/ $\sqrt{Hz}$  noise floor of the LO gain mode is suited to converters with higher sampling rates or resolutions (such as 12 bits). Both gain modes can accommodate ADC fullscale voltages as high as 4 V p-p. Because distortion performance remains favorable for output voltages as high as 4 V p-p (see Figure 35), it is possible to lower the output-referred noise even further by using a resistive attenuator (or transformer) at the output. The circuit in Figure 74 has an output full-scale range of 2 V p-p, a gain range of −10.5 dB to +37.5 dB, and an output noise floor of 24 nV/ $\sqrt{Hz}$ , making it suitable for some 14-bit ADC applications.



Figure 74. Adjusting the Noise Floor for 14-Bit ADCs

### **OVERLOAD**

These devices respond gracefully to large signals that overload its input stage and to normal signals that overload the VGA when the gain is set unexpectedly high. Each stage is designed for clean-limited overload waveforms and fast recovery when gain setting or input amplitude is reduced.

Signals larger than ±275 mV at the LNA input are clipped to 5 V p-p differential prior to the input of the VGA. Figure 47 shows the response to a 1 V p-p input burst. The symmetric overload waveform is important for applications, such as CW Doppler ultrasound, where the spectrum of the LNA outputs during overload is critical. The input stage is also designed to accommodate signals as high as  $\pm 2.5$  V without triggering the slow-settling ESD input protection diodes.

Both stages of the VGA are susceptible to overload. Postamp limiting is more common and results in the clean-limited output characteristics found in Figure 48. Under more extreme conditions, the X-AMP overloads, causing the minor glitches evident in Figure 49. Recovery is fast in all cases. Figure 75 summarizes the combinations of input signal and gain that lead to the different types of overload.



Figure 75. Overload Gain and Signal Conditions

The previously mentioned clamp interface controls the maximum output swing of the postamp and its overload response. When no RCLMP resistor is provided, this level defaults to near 4.5 V p-p differential to protect outputs centered at a 2.5 V common mode. When other common-mode levels are set through the VCM pin, the value of RCLMP should be chosen for graceful overload. A value of 8.3 k $\Omega$  or less is recommended for 1.5 V or 3.5 V common-mode levels (7.2 kΩ for HI gain mode). This limits the output swing to just above 2 V p-p differential.

### **OPTIONAL INPUT OVERLOAD PROTECTION**

Applications in which high transients are applied to the LNA input can benefit from the use of clamp diodes. A pair of backto-back Schottky diodes can reduce these transients to manageable levels. Figure 76 illustrates how such a diodeprotection scheme can be connected.



Figure 76. Input Overload Clamping

When selecting overload protection, the important parameters are forward and reverse voltages and  $t_{rr}$  (or  $\tau_{rr}$ .). The Infineon BAS40 series shown in Figure 76 has a  $\tau_{rr}$  of 100 ps and  $V_F$  of 310 mV at 1 mA. Many variations of these specifications can be found in vendor catalogs.

### **LAYOUT, GROUNDING, AND BYPASSING**

Due to their excellent high frequency characteristics, these devices are sensitive to their PCB environment. Realizing expected performance requires attention to detail critical to good high speed board design.

A multilayer board with power and ground plane is recommended, and unused area in the signal layers should be filled with ground. The multiple power and ground pins provide robust power distribution to the device and must all be connected. The power supply pins should each be with multiple values of high frequency ceramic chip capacitors to maintain low impedance paths to ground over a wide frequency range. These should have capacitance values of 0.01  $\mu$ F to 0.1  $\mu$ F in parallel with 100 pF to 1 nF and be placed as close as possible to the pins. The LNA power pins should be decoupled from the VGA using ferrite beads. Together with the decoupling capacitors, ferrite beads help eliminate undesired high frequencies without reducing the headroom, as do small value resistors.

Several critical LNA areas require special care. The LON and LOP output traces must be as short as possible before connecting to the coupling capacitors connected to the VIN and VIP pins. R<sub>FB</sub> must be placed nearby the LON pin as well. Resistors must be placed as close as possible to the VGA output pins, VOL and VOH, to mitigate loading effects of connecting traces. Values are discussed in the Output Filtering and Series Resistor Requirements section.

Signal traces must be short and direct to avoid parasitic effects. Wherever there are complementary signals, symmetrical layout should be employed to maintain waveform balance. PCB traces should be kept adjacent when running differential signals over a long distance.

### **MULTIPLE INPUT MATCHING**

Matching of multiple sources with dissimilar impedances can be accomplished as shown in Figure 78. A relay and low supply voltage analog switch can be used to select between multiple sources and their associated feedback resistors. An ADG736 dual SPDT switch is shown in this example; however, multiple switches are also available and users are referred to the Analog Devices, Inc. Selection Guide for switches and multiplexers.

#### **DISABLING THE LNA**

Where accessible, connection of the LNA enable pin to ground powers down the LNA, resulting in a current reduction of about half. In this mode, the LNA input and output pins can be left unconnected; however, the power must be connected to the supply pins for the disabling circuit to function. Figure 77 illustrates the connections using an AD8331 as an example.



Figure 77. Disabling the LNA



Figure 78. Accommodating Multiple Sources

#### **MEASUREMENT CONSIDERATIONS**

Figure 54 through Figure 58 show typical measurement configurations and proper interface values for measurements with 50  $Ω$  conditions.

Short-circuit input noise measurements are made using Figure 56. The input-referred noise level is determined by dividing the output noise by the numerical gain between Point A and Point B and accounting for the noise floor of the spectrum analyzer. The gain should be measured at each frequency of interest and with low signal levels because a 50  $\Omega$  load is driven directly. The generator is removed when noise measurements are made.

#### **ULTRASOUND TGC APPLICATION**

The AD8332 ideally meets the requirements of medical and industrial ultrasound applications. The TGC amplifier is a key subsystem in such applications, because it provides the means for echolocation of reflected ultrasound energy.

Figure 79 through Figure 81 are schematics of a dual, fully differential system using the AD8332 and AD9238, 12-bit high speed ADC, with conversion speeds as high as 65 MSPS. In this example, the VGA outputs are dc-coupled, using the reference output of the ADC and a level shifter to center the commonmode output voltage to match that of the converter. Consult the data sheet of the converter to determine whether external CMV biasing is required. AC coupling is recommended if the CMV of the VGA and ADC are widely disparate.

Using the EVAL-AD8332/AD9238 evaluation board and a high speed ADC FIFO evaluation kit connected to a laptop, an FFT can be performed on the AD8332. With the on-board clock of 20 MHz, minimal low-pass filtering, and both channels driven with a 1 MHz filtered sine wave, THD is −75 dB, noise floor is −93 dB, and HD2 is −83 dB.



Figure 79. Schematic, TGC, VGA Section



Figure 80. Converter Schematic



Figure 81. Interface Schematic

### OUTLINE DIMENSIONS





**COMPLIANT TO JEDEC STANDARDS MO-220-VHHD-2**

Figure 84. 32-Lead Lead Frame Chip Scale Package [LFCSP\_VQ] 5 mm × 5 mm Body, Very Thin Quad (CP-32-2) Dimensions shown in millimeters

#### **ORDERING GUIDE**



 $1 Z = Pb$ -free part.

# **NOTES**

# **NOTES**

### **NOTES**

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